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CLASSROOM TEST SERIES**E & T**
ENGINEERING**Test 2****Section A : Network Theory****Section B : Digital Circuits**

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Detailed Explanation

1. (c)

We have, $I = 2 \text{ A}$, $t = 10 \text{ sec}$, $V = 115 \text{ Volt}$

$$\text{Charge } (q) = I \times t$$

$$= 2 \times 10 = 20 \text{ Coulomb}$$

Since,

$$\text{Energy } (E) = qV$$

$$= 20 \times 115 = 2300 \text{ J} = 2.3 \text{ kJ}$$

2. (a)

We have,

$$i = 2\cos 60\pi t \text{ Amp}$$

and

$$V = 5 + 10 \int_0^t i \cdot dt$$

 \therefore

$$V = 5 + 10 \int_0^t 2\cos 60\pi t \cdot dt = 5 + \frac{20}{60\pi} (\sin 60\pi t)_0^t$$

$$V = 5 + \frac{1}{3\pi} \sin 60\pi t \text{ Volt}$$

At $t = 5.55 \text{ ms}$,

$$V = 5 + \frac{1}{3\pi} \sin 60\pi \times 5.55 \times 10^{-3}$$

$$= 5 + \frac{1}{3\pi} \sin \frac{\pi}{3} = 5 + \frac{1}{3\pi} \times \frac{\sqrt{3}}{2}$$

$$V = 5 + \frac{1}{2\sqrt{3}\pi}$$

$$V \approx 5 \text{ Volt}$$

$$\text{At } t = 5.55 \text{ ms} \approx \frac{1}{180},$$

$$i = 2\cos 60\pi t = 2\cos 60\pi \times \frac{1}{180} = 2\cos \frac{\pi}{3} = 1 \text{ Amp}$$

 \therefore Power at $t = 5.55 \text{ ms}$,

$$P = v \cdot i = 5 \times 1 \approx 5 \text{ Watt}$$

3. (b)

$$\bullet \text{ Power in kWh} = \frac{600 \times 4}{1000} = 2.4 \text{ kWh}$$

$$\bullet \text{ Electricity rate} = \frac{\text{Amount}}{\text{Power in kWh}}$$

$$10 = \frac{\text{Amount}}{2.4}$$

$$\text{Amount} = 24 \text{ cents}$$

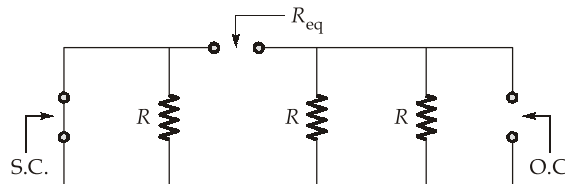
 \therefore Total 24 cents are wasted.

4. (c)

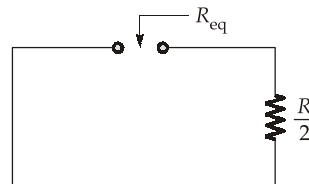
CONCEPT:**To obtain time constant:**

- Replace inductor and capacitor with open circuit across which equivalent resistance is to be calculated.
- Replace independent voltage source with short circuit.
- Replace independent current source with open circuit.

Now after applying above concept,



Since, resistor across short circuit act as redundant element.



$$R_{eq} = \frac{R}{2}$$

$$\therefore \text{Time constant } (\tau) = \frac{L_{eq}}{R_{eq}} = \frac{L}{R/2} = \frac{2L}{R}$$

Note: For 'RC' network time constant can be obtained as

$$\tau = R_{eq} \cdot C_{eq}$$

where, R_{eq} = Equivalent resistance across capacitor and C_{eq} = Total capacitance.

5. (b)

Conductance: "It is the ability of an element to conduct electric current."

6. (d)

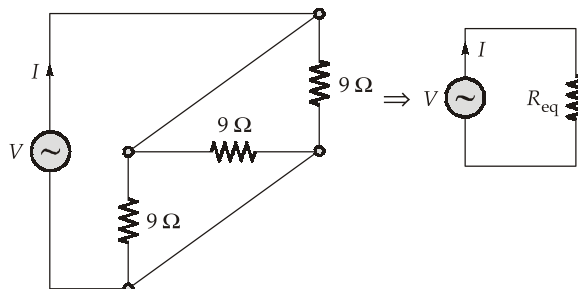
We have, $V = 6\cos 0.5 \times 10^6 t$ and $\omega = 0.5 \times 10^6 \text{ rad/s}$

$$L = 1 \text{ mH} \Rightarrow X_L = \omega L = 0.5 \times 10^6 \times 10^{-3} = 0.5 \times 10^3 \Omega$$

$$C = 4 \text{ nF} \Rightarrow X_C = \frac{1}{\omega C} = \frac{1}{0.5 \times 10^6 \times 4 \times 10^{-9}} = 0.5 \times 10^3 \Omega$$

$$\therefore X_C = X_L$$

Equivalent circuit will be,



$$R_{eq} = 9\ \Omega \parallel 9\ \Omega \parallel 9\ \Omega = 3\ \Omega$$

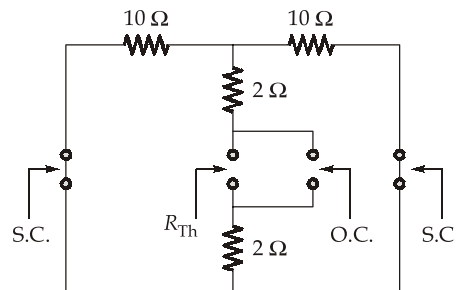
$$\therefore I = \frac{V}{R_{eq}} = \frac{6 \cos 0.5 \times 10^6 t}{3} = 2 \cos 0.5 \times 10^6 t\ \text{A}$$

7. (b)

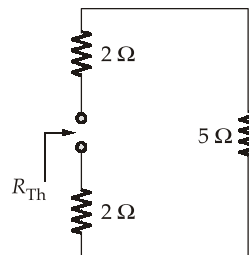
Calculation of Thevenin's Resistance:

- Replace independent voltage source with short circuit.
- Replace independent current source with open circuit.
- Remove load resistor across which Thevenin's resistance is to be calculated.

Now, equivalent circuit



- $10\ \Omega$ is in parallel with $10\ \Omega$.

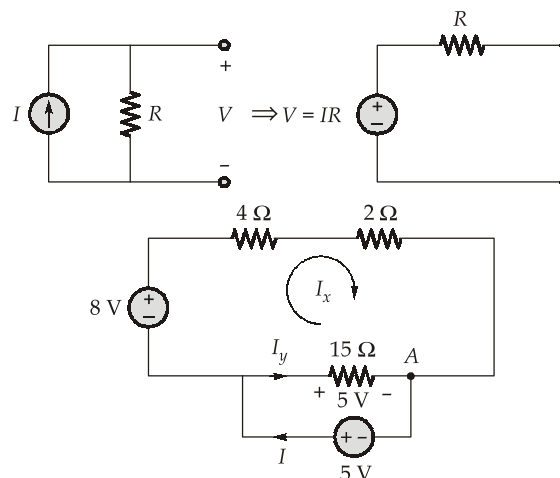


\Rightarrow

$$R_{Th} = 5 + 2 + 2 = 9\ \Omega$$

8. (a)

From the source transformation theorem,



$$I_x = \frac{8+5}{6} = \frac{13}{6} \text{ A}$$

$$I_y = \frac{5}{15} = \frac{1}{3} \text{ A}$$

KCL at node A:

$$I_x + I_y = I$$

$$\frac{13}{6} + \frac{1}{3} = I$$

$$I = \frac{13+2}{6} = \frac{15}{6} = \frac{5}{2} = 2.5 \text{ Amp}$$

9. (b)

Mathematically, KCL implies that

$$\sum_{n=1}^N i_n = 0$$

It is based on law of conservation of charge.

10. (d)

We have, $f = 50 \text{ Hz}$,

$$V_{\text{rms}} = \frac{V_m}{\sqrt{2}} \Rightarrow V_m = 100 \text{ Volt}$$

$$V(t) = V_m \sin(2\pi ft) = 100 \sin(314t) \text{ Volt}$$

11. (c)

We have,

$$V = -2 \sin(314t + 10^\circ) = 2 \cos(314t + 10^\circ + 90^\circ)$$

$$V = 2 \cos(314t + 100^\circ) \text{ Volt}$$

$$V = 2 \angle 100^\circ \text{ Volt}$$

Now,

$$I = 5 \cos(314t + 160^\circ) = 5 \angle 160^\circ \text{ Amp}$$

Here ; $\theta = \theta_V - \theta_I = 100 - 160 = -60^\circ$

Power factor $\Rightarrow \cos \theta = \cos(-60^\circ) = 0.5(\text{leading})$

Note: Leading because current is leading with voltage.

12. (a)

The total number of possible trees,

$$T = |A \cdot A^T|$$

$$[A] = \begin{bmatrix} 1 & 1 & 0 & 0 & 1 \\ -1 & 0 & 1 & 0 & 0 \\ 0 & -1 & -1 & -1 & 0 \end{bmatrix}$$

$$[A^T] = \begin{bmatrix} 1 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \\ 1 & 0 & 0 \end{bmatrix}$$

$$[A \cdot A^T] = \begin{bmatrix} 1 & 1 & 0 & 0 & 1 \\ -1 & 0 & 1 & 0 & 0 \\ 0 & -1 & -1 & -1 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \\ 1 & 0 & 0 \end{bmatrix}$$

$$[A \cdot A^T] = \begin{bmatrix} 3 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 3 \end{bmatrix}$$

$$|A \cdot A^T| = 3(6 - 1) + 1(-3 - 1) - 1(1 + 2) = 15 - 4 - 3 = 8$$

13. (a)

Transmission parameter is $ABCD$ parameter given as:

$$V_1 = AV_2 - BI_2$$

$$I_1 = CV_2 - DI_2$$

14. (c)

Symmetric conditions for 2-port parameters:

- $Z_{11} = Z_{22}$
- $Y_{11} = Y_{22}$
- $h_{11}h_{22} - h_{12}h_{21} = 1$
- $g_{11}g_{22} - g_{12}g_{21} = 1$
- $A = D$

Reciprocal conditions for 2-port parameters:

- $Z_{12} = Z_{21}$
- $Y_{12} = Y_{21}$
- $h_{12} = -h_{21}$
- $g_{12} = -g_{21}$
- $AD - BC = 1$

15. (b)

In a complete graph, each pair of graph vertices is connected by an edge. Hence, the number of edges in complete graph is nC_2 .

16. (a)

Current through capacitor:

$$I_C = C \cdot \frac{dV}{dt}$$

$$1 = C \cdot \left(\frac{1}{2}\right)$$

$$C = 2 \text{ F}$$

17. (c)

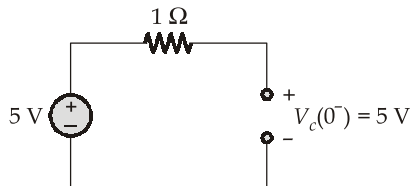
- For a linear element, VI characteristics is a straight line passing through origin. Hence, the element is not linear.
- Since the VI characteristics depend on the direction of current flow, hence the element is not bidirectional.
- Since $V/I =$ positive in both the quadrants, hence the element is Passive.

18. (c)

Tellegen's theorem:

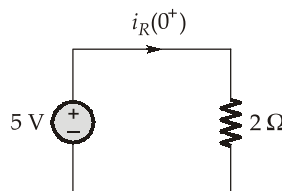
- It is applicable to any network (i.e. linear, non-linear, unidirectional, time variant, time invariant).
- It is based on law of conservation of energy.

19. (b)

At $t = 0^-$ (switch is present at A) and capacitor acts as open-circuit. \therefore

$$V_c(0^-) = V_c(0^+) = 5 \text{ V}$$

"Capacitor do not allow sudden change in voltage".

At $t = 0^+$;

$$i_R(0^+) = \frac{5}{2} = 2.5 \text{ Amp}$$

20. (d)

In series combination,

$$P = I^2 R \Rightarrow P \propto R$$

$$V = IR \Rightarrow V \propto R$$

 \therefore

$$V \propto P$$

Now,

$$V_1 = V \cdot \frac{P_1}{P_1 + P_2}$$

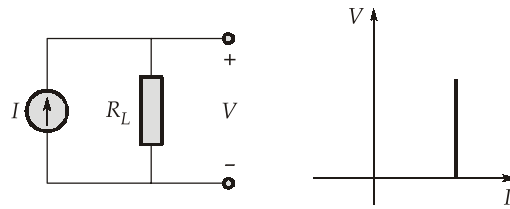
Here, $V = 12 \text{ V}$, $P_1 = 15 \text{ W}$ and $P_2 = 10 \text{ W}$. \therefore

$$V_1 = 12 \times \frac{15}{15 + 10} = 7.2 \text{ V}$$

$$V_2 = 12 \times \frac{10}{15 + 10} = 4.8 \text{ V}$$

21. (c)

For ideal current source, internal resistance is infinite and the output current is constant irrespective of the load.



22. (d)

$$\text{Crest factor or peak factor} = \frac{V_{\text{peak}}}{V_{\text{rms}}}$$

$$\text{Form factor} = \frac{V_{\text{rms}}}{V_{\text{avg}}}$$

23. (a)

We have, $I_1 = 2\cos 10t$ A and $I_2 = 10\sin 10t$ A

Since I_1 and I_2 is in quadrature.

So, time constant of branch will be equal.

i.e.

$$\frac{L}{R_1} = R_2 C$$

$$R_1 = \frac{L}{R_2 C} = \frac{12}{5 \times 3} = 0.8 \Omega$$

24. (d)

Series Resonance:

- Impedance is minimum $\Rightarrow Z = R$.
- Bandwidth = $\frac{R}{L}$ (rad/s).
- It perform voltage magnification as the magnitude of voltage across the inductor and the capacitor is equal to Q times the input sinusoidal voltage V .
- It act as bandpass filter.

25. (b)

We know, for parallel L - R - C circuit

$$\text{Bandwidth } (\omega) = \frac{1}{RC}$$

\therefore

$$R_2 = 2R = 2 \Omega$$

$$C_2 = 2C = 2 \text{ F}$$

$$\text{Bandwidth } (\omega') = \frac{1}{R_2 C_2} = \frac{1}{4}$$

\Rightarrow

$$\omega' = \frac{\omega}{4}$$

26. (a)

When all the nodes are connected to each other and there is no repeated path existing between any two node then;

$$\text{Total number of tress possible} = N^{N-2}$$

$$N = \text{Number of nodes} = 4$$

$$\text{Total number of tress possible} = 4^{4-2} = 16$$

27. (b)

- For parallel R - L - C resonance circuit

$$B_L = \frac{1}{X_L} = \frac{1}{\omega \cdot L}$$

$$B_C = \frac{1}{X_C} = \omega C$$

- At low frequency $\Rightarrow B_L > B_C$ (Inductive).
- At high frequency $\Rightarrow B_C > B_L$ (Capacitive).

28. (b)

We know, $\text{Quality factor } (Q) = \frac{\text{Resonant frequency } (\omega_0)}{\text{Bandwidth}}$

Here, $\text{Resonance frequency } (\omega_0) = \sqrt{\omega_1 \cdot \omega_2} = 2\omega_1$

$$\text{Bandwidth (B.W.)} = \omega_2 - \omega_1 = 3\omega_1$$

$$\therefore Q = \frac{2\omega_1}{3\omega_1} = \frac{2}{3}$$

29. (b)

For parallel connection;

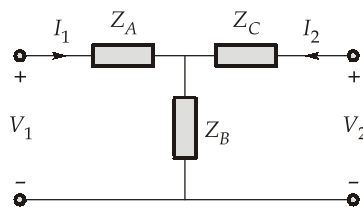
$$\text{Input admittance } (Y) = G + \frac{1}{sL}$$

where, $G = \frac{1}{R} = \frac{1}{3} S$

$$Y = \frac{1}{3} + \frac{1}{2s} = \frac{2s+3}{6s}$$

30. (d)

We know,



$$\Rightarrow \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} = \begin{bmatrix} Z_A + Z_B & Z_B \\ Z_B & Z_B + Z_C \end{bmatrix}$$

For network-A:

$$\begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 3 \end{bmatrix}$$

For network-B:

$$\begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ 2 & 3 \end{bmatrix}$$

- If networks are connected in series, then equivalent z-parameter is obtained by addition.

$$\begin{aligned} \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix}_{\text{equivalent}} &= \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix}_A + \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix}_B \\ &= \begin{bmatrix} 2 & 2 \\ 2 & 3 \end{bmatrix} + \begin{bmatrix} 3 & 2 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} 5 & 4 \\ 4 & 6 \end{bmatrix} \end{aligned}$$

31. (d)

For R-L-C series circuit:

$$\text{Quality factor } (Q) = \frac{1}{R} \sqrt{\frac{L}{C}} = \frac{1}{2} \sqrt{\frac{10^{-4}}{10^{-4}}} = \frac{1}{2}$$

$$\text{Damping ratio } (\xi) = \frac{1}{2Q} = 1$$

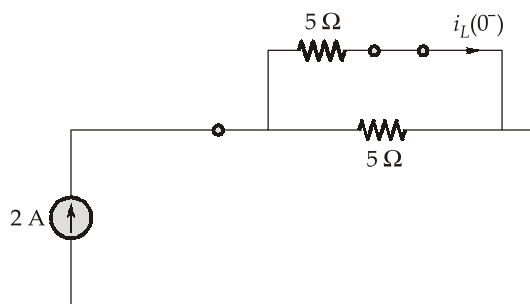
If $\xi = 1$, then system is critically damped.

Note:

- For $0 < \xi < 1 \Rightarrow$ system is underdamped.
- For $\xi > 1 \Rightarrow$ system is overdamped.
- For $\xi = 0 \Rightarrow$ system is undamped.

32. (a)

At $t = 0^-$ (switch is at position A), and at steady state inductor acts as short-circuit.

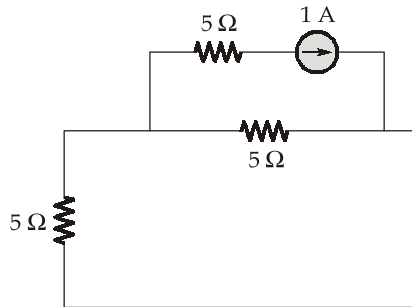


$$i_L(0^-) = 1 \text{ A}$$

\therefore Inductor do not allow sudden change in current value and direction.

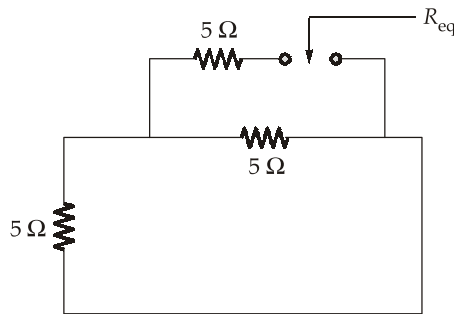
$$\therefore i_L(0^-) = i_L(0^+) = 1 \text{ A}$$

At $t = 0^+$ (switch is at position B), the circuit can be drawn as below:



Obtain time constant:

- Replace inductor with open circuit.
- Operate the switch for $t > 0$.
- Deactivate independent source.



$$R_{eq} = 5 + [5 \parallel 5] = 7.5 \Omega$$

$$\text{Time constant } (\tau) = \frac{L}{R_{eq}} = \frac{2.5}{7.5} = \frac{1}{3}$$

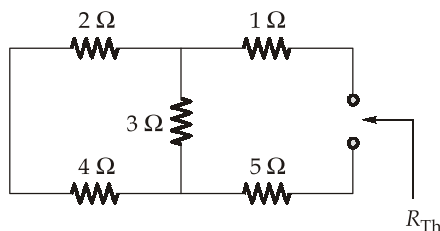
\therefore Current flowing through inductor:

$$i(t) = i_L(0^+) \times e^{-t/\tau} = e^{-3t} \text{ Amp}$$

33. (a)

To get Thevenin's resistance across load:

- Deactivate independent sources.
- Replace load resistance with open circuit.



$$R_{Th} = [(2 + 4) \parallel 3] + [1 + 5] = 8 \Omega$$

- For maximum power to transfer at load;

$$R_L = R_{Th}$$

\therefore

$$R_L = 8 \Omega$$

34. (b)

Hybrid parameters are defined as:

$$V_1 = h_{11} I_1 + h_{12} V_2$$

$$I_2 = h_{21} I_1 + h_{22} V_2$$

$$h_{12} = \left. \frac{V_1}{V_2} \right|_{I_1=0} \Rightarrow \text{Reverse voltage gain}$$

$$h_{21} = \left. \frac{I_2}{I_1} \right|_{V_2=0} \Rightarrow \text{Forward current gain}$$

35. (c)

In dual concept:

- $R \longleftrightarrow G$
- $L \longleftrightarrow C$
- Series \longleftrightarrow Parallel
- Nodal \longleftrightarrow Mesh

36. (d)

- Mesh analysis works only with planar circuit.
- Mesh analysis works with KVL which is based on law of conservation of energy.

37. (c)

$$\text{Quality factor (Q)} = 2\pi \left[\frac{\text{Maximum energy stored in circuit}}{\text{Power dissipation per cycle}} \right]$$

$$Q \propto \frac{1}{\text{Power loss (I}^2 R\text{)}}$$

38. (c)

The given logic function can be written as,

$$f(A, B, C, D) = \Sigma m(0, 4, 5, 10, 11, 13, 15)$$

Using K-map:

		CD			
AB		00	01	11	10
	00	1			
	01	1	1		
	11		1	1	
	10			1	1

Total prime implicants = 6 ($AC'D'$, $A'BC'$, $BC'D$, ABD , ACD and $AB'C$)Number of essential prime implicants = 2 ($A'C'D'$ and $AB'C$)

39. (b)

Given,

$$f_1(A, B, C) = \Sigma m(2, 3, 4)$$

$$f_2(A, B, C) = \pi M(0, 1, 5, 6, 7) = \Sigma m(2, 3, 4)$$

For f_{out} to be zero, the function f_3 should be equal to,

$$f_3(A, B, C) = \Sigma m(2, 3, 4)$$

 \therefore The maximum number of possible minterms = 3.

40. (a)

From the given number, the minimum value of 'x' can be written as, "12 + 1 = 13" ($\because C = 12$)

Therefore, the least decimal equivalent

$$= 10 \times 13^2 + 11 \times 13^1 + 12 \times 13^0$$

$$= 1690 + 143 + 12 = (1845)_{10}$$

42. (c)

Since, given that,

$$V_{\text{out}} = 0.2 \text{ V for } 00001$$

 \therefore the weight of LSB is 0.2 V.

The the weight of other bits in weighted D/A converter can be obtained as 0.4 V, 0.8 V, 1.6 V and 3.2 V respectively.

For a digital input of 11111, the value of output, $V_{\text{out}} = 3.2 + 1.6 + 0.8 + 0.4 + 0.2 = 6.2 \text{ V}$.

43. (b)

Given, decimal number is $(417)_{10}$

8	417
8	52 - 1
	6 - 4

$$\therefore (417)_{10} = (641)_8$$

44. (a)

TTL logic family has leakage current in the HIGH state and has assymmetric output drive; they can sink much more current in the low state than they can source in the high state.

45. (c)

DCTL, I^2L , HTL, TTL are saturating type logic families wherein the transistors are driven into saturation.

Schottky TTL, ECL are non saturated logic families wherein the transistors are not driven into saturation.

46. (b)

Output of 2×1 MUX,

$$Y = \bar{S}I_0 + SI_1$$

where, $S = \bar{Q}$; $I_0 = \bar{X}$; $I_1 = X$ \therefore

$$Y = \bar{\bar{Q}}\bar{X} + \bar{Q}X$$

$$Y = Q\bar{X} + \bar{Q}X$$

Since, $Q_{n+1} = D = Y = Q\bar{X} + \bar{Q}X$

which is the characteristic equation of T flip-flop.

47. (b)

Let output of 4×1 MUX is P ,

$$\therefore P = \bar{S}_1 \bar{S}_0 I_0 + \bar{S}_1 S_0 I_1 + S_1 \bar{S}_0 I_2 + S_1 S_0 I_3$$

where, $S_1 = A$; $S_0 = B$; $I_0 = 1$; $I_1 = 0$; $I_2 = B$, $I_3 = 1$

$$P = \bar{A}\bar{B}(1) + \bar{A}B(0) + A\bar{B}(B) + AB$$

$$P = \bar{A}\bar{B} + AB$$

Output,

$$Y = \bar{S}I_0 + SI_1$$

$$= \bar{A}\bar{B}(B) + \overline{AB} \cdot P = AB + (\bar{A} + \bar{B})(\bar{A}\bar{B} + AB)$$

$$= AB + \bar{A}\bar{B} + \bar{A}\bar{B} = AB + \bar{A}\bar{B}$$

$$Y = A \odot B$$

48. (a)

In a 4-bit ripple counter, four flip-flops (FF0 to FF3) are used. The input frequency of flip-flop FF0 is ' f ' and its output waveform frequency is $f/2$ which is applied as input of FF1. Consequently, the output waveform frequency of FF1 is $f/4$ which is used as input of FF2.

Then output waveform frequency of FF2 is $f/8$ which is used as input of FF3. Therefore, the output waveform frequency of FF3 is $f/16$ and the time period is

$$T = \frac{1}{\text{Frequency}} = \frac{16}{f}$$

Since, time period of the last flip-flop (FF3) is 128 microseconds.

$$\therefore T = \frac{16}{f} = 128 \times 10^{-6}$$

$$\therefore f = \frac{16}{128 \times 10^{-6}} = 125 \text{ kHz}$$

\therefore The clock frequency of a 4-bit ripple counter is,

$$f = 125 \text{ kHz}$$

49. (c)

15's complement is equivalent to

$$\begin{array}{r} \text{F F F} \\ - \text{B B D} \\ \hline (442)_{16} \end{array}$$

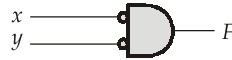
50. (b)

$$F = \overline{x + \bar{y}} + x$$

$$= \overline{x + \bar{y}} \cdot \bar{x}$$

$$= (x + \bar{y}) \cdot (\bar{x})$$

$$F = \bar{x}\bar{y}$$



51. (b)

In toggle mode of operation in J - K flip-flop, the output frequency is half of the clock frequency.

$$\therefore f = \frac{1}{2} \times 3 \text{ MHz} = 1.5 \text{ MHz}$$

52. (d)

The K -map wraps around itself, so the top and bottom cells are adjacent to each other. The cells of the rightmost column are adjacent to those in the leftmost column of the map. The minterms may be grouped horizontally or vertically.

Groupings may occur in the size of 2^r where, $r = 1, 2, 3 \dots n$.

53. (c)

Excess-3 code representation for integers 0 to 9 is

Number	Code (ABCD)
0	0011
1	0100
2	0101
3	0110
4	0111
5	1000
6	1001
7	1010
8	1011
9	1100

\therefore The excess-3 code, $f_{ABCD} = \Sigma m(3, 4, 5, 6, 7, 8, 9, 10, 11, 12)$

Invalid code is $f'_{ABCD} = \Sigma m(0, 1, 2, 13, 14, 15)$

		CD			
		00	01	11	10
AB	00	1	1		1
	01				
	11		1	1	1
	10				

$$f_{ABCD} = \bar{A}\bar{B}\bar{C} + \bar{A}\bar{B}\bar{D} + ABD + ABC$$

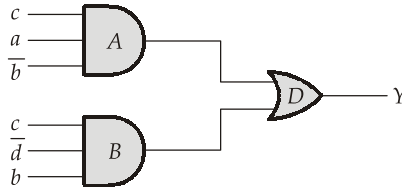
$$f'_{ABCD} = \bar{A}\bar{B}(\bar{C} + \bar{D}) + AB(C + D)$$

54. (c)

The output,

$$Y = a\bar{b}c + \bar{d}bc + \bar{d}ac$$

$$= c[a\bar{b} + \bar{d}b + \bar{d}a] = c[a\bar{b} + \bar{d}b], \text{ using consensus theorem}$$



55. (c)

In priority encoder, if an input has 1 then the other inputs with lower priority can be considered with the "don't care" condition.

$$I_2 = 1, I_3 = 0; I_1 = X \text{ and } I_0 = X.$$

Hence, the output will be 10.

56. (b)

Since, RIGHT/LEFT input is HIGH, it's a right shift register.

After 3 clock pulses, entered bits are 011 shifting the bits of register to the right.

Given, 1101 \longrightarrow 1011

1st clock pulse \Rightarrow 1110 \longleftarrow 101

2nd clock pulse \Rightarrow 1111 \longleftarrow 10

3rd clock pulse \Rightarrow 0111 \longleftarrow 1

Therefore, 0111 is the stored value in the register.

57. (a)

After every full modulus the initial state will repeat, hence after 16-clock pulses the counter holds the same state i.e., decimal 5. The remaining clock pulses are $30 - 16 = 14$, so, the final state is $14 + 5 = 19 = 16 + 3$.

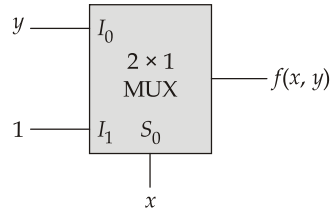
\therefore After 30th clock pulse the counter reads 0011.

58. (c)

From the given circuit,

$$\begin{aligned} f(x, y) &= x \oplus y \oplus xy \\ &= x \oplus [y(\bar{x}y) + \bar{y}(xy)] \\ &= x \oplus \bar{x}y \\ &= x(\bar{x}y) + \bar{x}(\bar{x}y) \\ &= x(x + \bar{y}) + \bar{x}(\bar{x}y) = x + \bar{x}y \\ f(x, y) &= x + y \end{aligned}$$

Hence, we can design the above $f(x, y)$ function by using 2×1 MUX as follows:



60. (b)

Given, $A \oplus C = B$

$$\bar{A}C + A\bar{C} = B \quad \dots(i)$$

$$\begin{aligned} A \odot B &= AB + \bar{A}\bar{B} \\ &= A[\bar{A}C + A\bar{C}] + \bar{A}[\bar{A}C + A\bar{C}] \\ &= A\bar{C} + \bar{A}[\bar{A}C \cdot \overline{A\bar{C}}] = A\bar{C} + \bar{A}[(A + \bar{C})(\bar{A} + C)] \\ &= A\bar{C} + \bar{A}[\bar{C}\bar{A} + AC] = A\bar{C} + \bar{A}\bar{C} + 0 \\ &= \bar{C}[A + \bar{A}] \\ &= \bar{C} \end{aligned}$$

61. (d)

Given, $\bar{A} + AB = 0$

$$(i) \quad (\bar{A} + A)(\bar{A} + B) = 0$$

$$\bar{A} + B = 0$$

$$\Rightarrow A = 1 \text{ and } B = 0$$

$$(ii) \quad AB = AC$$

$$(or) \quad B = C$$

$$(iii) \quad AB + A\bar{C} + CD = \bar{C}D$$

$$1 \cdot 0 + 1 \cdot 1 + 0 \cdot D = 1 \cdot D$$

$$D = 1$$

Hence, option (d) is correct.

62. (d)

$$\text{Given: } \frac{(302)_x}{(20)_x} = (12.1)_x$$

$$\frac{3x^2 + 2}{2x} = x + 2 + \frac{1}{x}$$

$$3x^2 + 2 = 2x^2 + 4x + 2$$

$$x^2 - 4x = 0$$

$$\therefore x = 4$$

63. (d)

PSRAM is basically a dynamic RAM. It has a built in refresh logic. Hence, no external refreshing circuit is required and thereby PSRAM can be used as a static RAM device. SRAM is used in hard disk buffers, router buffers and LCD screen. LCD screens employ SRAM to hold the image displayed.

64. (d)

Since, SRAM uses flip-flops, which can be made of upto 6 transistors, SRAM needs more transistors to store 1-bit than DRAM does, which only uses a single transistor and capacitor.

Thus, for the same amount of memory, SRAM requires higher number of transistors which increases the production cost compared to DRAM.

65. (d)

In the ripple counter (asynchronous counter) different flip-flops are applied with different clocks. Only one flip-flop is applied with external clock and for rest of the flip-flops, the output of one flip-flop acts as clock for the next flip-flop. For every input clock pulse, atleast one flip flop get clocked at a time. The triggering edge of the clock pulses of more than one flip-flops may also coincide at some time.

66. (c)

Input voltage required to generate a change of 1 LSB at the output is

$$\Delta V_i = \frac{V_{FS}}{2^n}$$

$$\Delta V_i = \frac{8}{2^8} = \frac{2^3}{2^8} = \frac{1}{2^5} = 31.25 \text{ mV}$$

67. (d)

CMOS devices dissipates almost zero static power.

$$\text{Dynamic power of CMOS device} = CfV_{DD}^2$$

68. (b)

A	B	T ₂	T ₃	Y
0	0	ON	ON	1
0	1	ON	OFF	1
1	0	OFF	ON	1
1	1	OFF	OFF	0

Transistor T₁ is always in saturation mode.

$$Y = \overline{A + B} = \overline{A} \cdot \overline{B}$$

∴ NAND gate.

69. (c)

0	1	1	0	CLK pulse
1	1	0	1	①
1	0	1	1	②
0	1	1	0	③

70. (a)

Full adder, full subtractor and half adder come under the class of combinational logic circuits.

⇒ J-K flip flop and counter comes under the class of sequential logic circuit.

71. (a)

MOD-1000 ripple-up counter is constructed using 10-flip flops.

The MSB i.e., Q_9 will have 50% duty cycle if it is MOD-1024 ripple up counter.

But for MOD-1000, Q_9 will be '0' for 512 clock pulses and will be '1' for 488 clock pulses.

Hence,

$$\text{Duty cycle} = \frac{T_{\text{ON}}}{T_{\text{ON}} + T_{\text{OFF}}}$$

$$\% \text{ Duty cycle} = \frac{488 T_{\text{CLK}}}{1000 T_{\text{CLK}}} \times 100 = 48.8\%$$

72. (c)

$$\text{Memory capacity} = 16 \text{ K} \times 16 = 2^4 \times 2^{10} \times 16 = 2^{14} \times 16$$

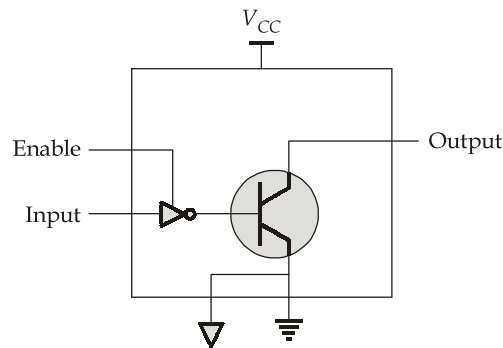
∴

$$\text{Address lines} = 14$$

$$\text{Data lines} = 16$$

73. (d)

Since, the tri-state buffer allows input to go to output when desired using enable input, it can be used to design multiplexers, where a selected input is sent to the output. The open-collector tri-state buffer is as shown below:



74. (c)

The input at which flip-flop changes its state when synchronized with the clock is called synchronous control inputs.

75. (c)

By using the combination of NAND and NOR gates, we can realize any Boolean function but not with the minimum number of logic gates. Hence, Statement(II) is incorrect.

