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Important Questions
for **GATE 2022**

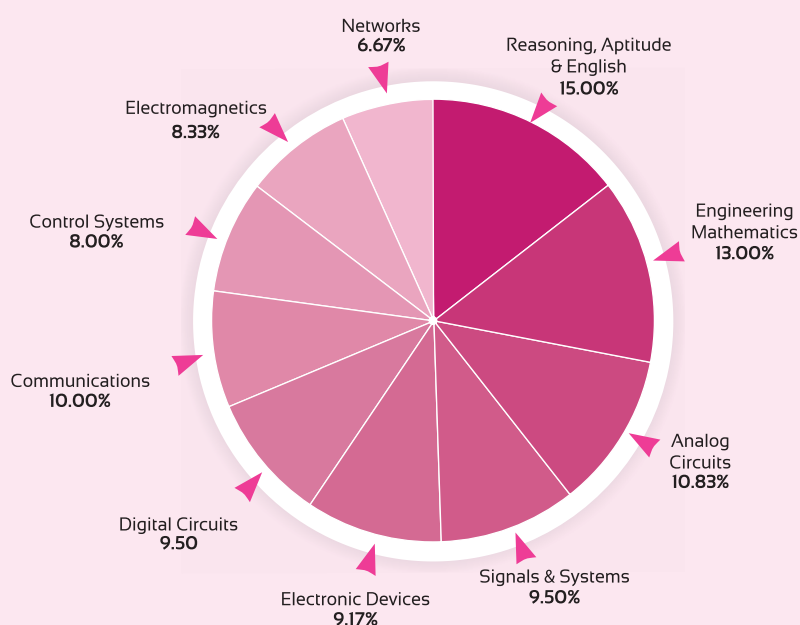
**ELECTRONICS
ENGINEERING**

Day 2 of 8

Q.26 - Q.50 (Out of 200 Questions)

Networks and Control Systems

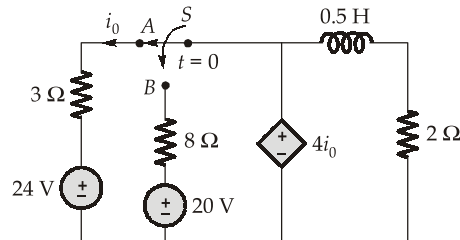
SUBJECT-WISE WEIGHTAGE ANALYSIS OF GATE SYLLABUS



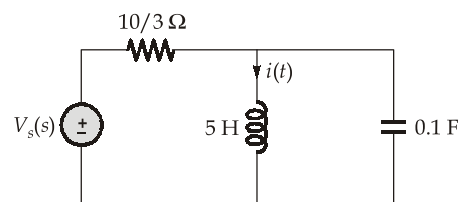
Subject	Average % (last 5 yrs)*
Reasoning, Aptitude & English	15.00%
Engineering Mathematics	13.00%
Analog Circuits	10.83%
Signals & Systems	9.50%
Electronic Devices	9.17%
Digital Circuits	9.50%
Communications	10.00%
Control Systems	8.00%
Electromagnetics	8.33%
Networks	6.67%
Total	100%

Networks and Control Systems

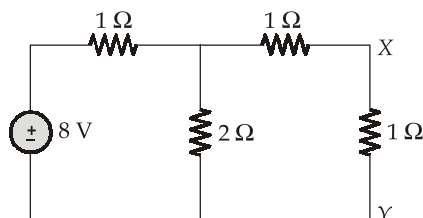
- Q.26** For the circuit shown in the figure below (the switch 'S' moves from A to B at $t = 0$). The voltage across $2\ \Omega$ resistor for $t > 0$ will be



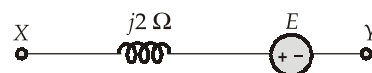
- (a) $96e^{-3.2t} u(t)$ V
(b) $48e^{-4t} u(t)$ V
(c) $96e^{-4t} u(t)$ V
(d) $48e^{-t/3.2t} u(t)$ V
- Q.27** The Thevenin equivalent impedance of a source is $Z_{Th} = (120 + j60)\ \Omega$ and the peak Thevenin voltage is $V_{Th} = (150 + j0)$. The maximum average available power from the source is _____ W.
- Q.28** Consider the circuit shown in the figure below. Assuming the value of $V_s(t) = 10u(t)$ V and assume that at $t = 0$, $i(0) = -1$ A flows through the inductor and +5 V is across the capacitor, the voltage across the capacitor will be for $t > 0$,



- (a) $(30e^{-t} + 7e^{-2t}) u(t)$ V
(b) $(1 - e^{-t} + 7e^{-2t}) u(t)$ V
(c) $(3 - 7e^{-t} + 3e^{-2t}) u(t)$ V
(d) $(35e^{-t} - 30e^{-2t}) u(t)$ V
- Q.29** For the circuit shown in below figure, we are interested in replacing the branch X-Y by a voltage generator with series impedance of $j2\ \Omega$ as shown in figure (b), without affecting the circuit response.



(a)

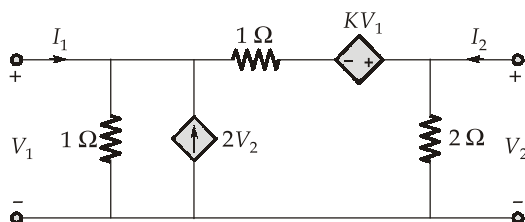


(b)

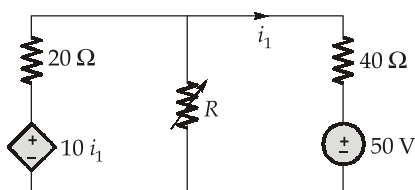
The value of voltage of the generator E will be

- (a) $2\angle 90^\circ$ V
(b) $2\sqrt{5}\angle -63.43^\circ$ V
(c) $2\angle -180^\circ$ V
(d) $\sqrt{5}\angle 35^\circ$ V

Q.30 The circuit shown in the below figure is reciprocal if $K =$ _____.

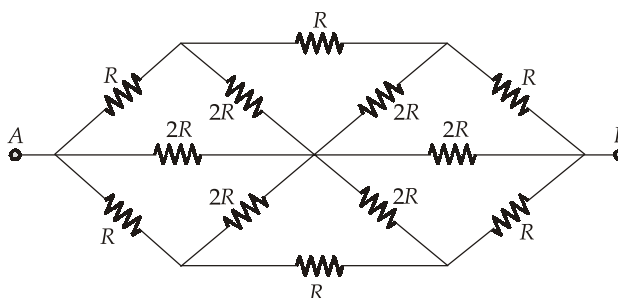


Q.31 For the circuit shown in the figure below, the resistance R and the maximum power transfer to it will be



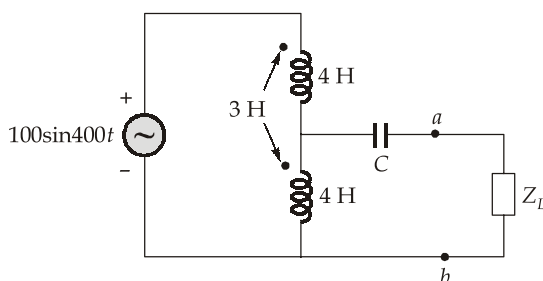
- (a) 4Ω and 1.56 W (b) 16Ω and 17.36 W
(c) 16Ω and 1.56 W (d) 4Ω and 7.36 W

Q.32 A rectangular hexagon is formed from six wires of $R \Omega$ each as shown in the figure below:



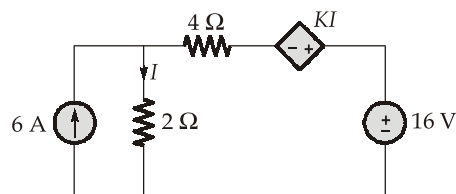
The equivalent resistance seen across the terminal A and B is _____ $R \Omega$.

Q.33 Consider the circuit shown below:



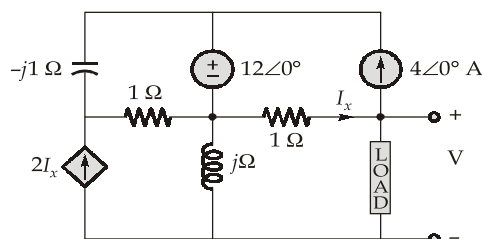
If the voltage across Z_L is to be independent of the value of Z_L , then the value of C is _____ μF .

Q.34 Consider the circuit shown in the figure below:

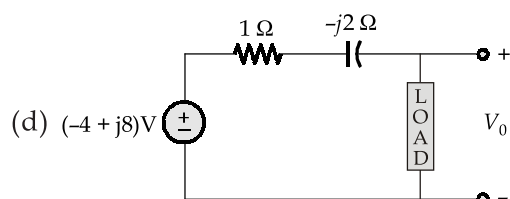
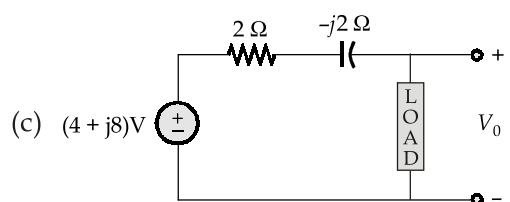
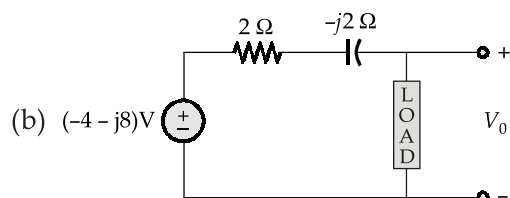
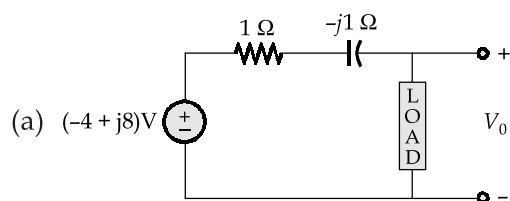


The value of 'K' such that the power dissipated by $2\ \Omega$ resistor does not exceed 50 W is _____.

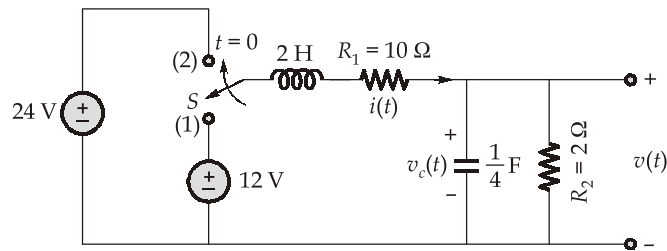
Q.35 Consider the circuit shown in the figure below:



Then the Thevenin's equivalent circuit with connected one Ω load can be represented as



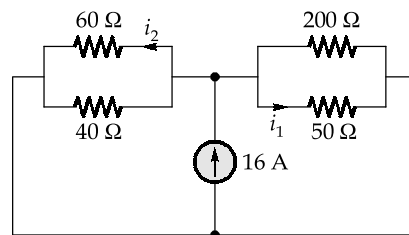
Q.36 Consider the circuit shown in the figure below:



The switch 'S' is moved from position (1) to position (2) at $t = 0$. Then which of the following differential equations does not satisfy the circuit working condition.

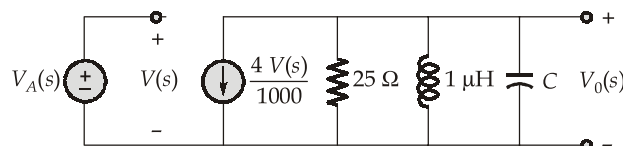
- (a) $\frac{di(t)}{dt} + 5i(t) + 0.5v(t) = 12$ for $t > 0$ (b) $\frac{dv(0)}{dt} = 4i(0) - 2v(0)$
 (c) $\frac{dv(t)}{dt} + 2v(t) = 4i(t)$ for $t > 0$ (d) $\frac{d^2v(t)}{dt^2} + 7\frac{dv(t)}{dt} + 12v(t) = 48$ for $t > 0$

Q.37 Consider the circuit shown in the figure below:



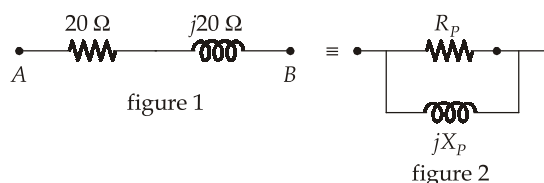
Then the ratio $\frac{i_1}{i_2}$ is equal to _____.

Q.38 Consider the RLC circuit shown in the figure below:



Let the input voltage be $V_A(s)$ and output voltage be $V_0(s)$, then the value of 'C' for which the circuit will produce maximum gain at 91.1 MHz is equal to _____ pF.

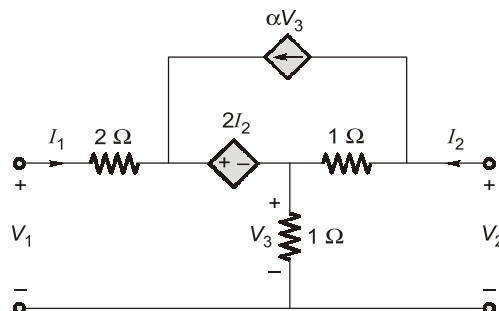
Q.39 Consider the series R-L series circuit shown in the figure 1 below.



If the circuit shown in figure-2 is equivalent to figure-1 then the value of R_p and L_p is equal to

- (a) $R_p = 20 \Omega$ and $X_p = 40 \Omega$ (b) $R_p = 20 \Omega$ and $X_p = 20 \Omega$
 (c) $R_p = 40 \Omega$ and $X_p = 40 \Omega$ (d) $R_p = 40 \Omega$ and $X_p = 20 \Omega$

Q.40 Consider the circuit shown below:



The value of ' α ' for which the circuit is said to be reciprocal is _____ Ω .

Q.41 The open-loop transfer function of a closed-loop system with unity negative feedback is given by,

$$G(s) = \frac{K(s^2 + s + 1)}{s(s^3 + 2s^2 + s + 1)}$$

Consider the following statements regarding the Nyquist plot of $G(s)$:

S_1 : For $K > 1$, the Nyquist plot encircles the point $(-1 + j0)$ two times in clockwise direction.

S_2 : For $0 < K < 1$, the Nyquist plot encircles the point $(-1 + j0)$ two times in counterclockwise direction.

S_3 : For $K = 1$, the Nyquist plot passes through the point $(-1 + j0)$.

Select the correct statement(s) using the codes given below.

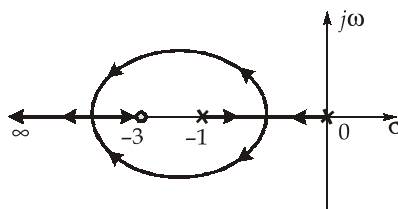
- (a) S_1 and S_3 only (b) S_2 and S_3 only
(c) S_1 and S_2 only (d) S_3 only

Q.42 The open-loop transfer function of a closed-loop system with unity negative feedback is given by,

$$G(s) = \frac{K}{s(s+2)^2}$$

The root locus plot (for $K > 0$) of this system intersects the constant damping ratio (ξ) line, for $\xi = 0.50$, at $K = K_0$. The value of K_0 is _____.

Q.43 Consider the root locus diagram of a unity negative feedback system shown below:



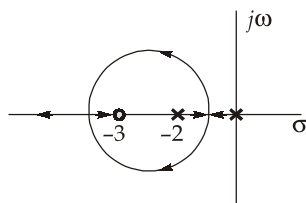
The corresponding open loop transfer function will be

- (a) $\frac{K}{s(s+1)(s+3)}$ (b) $\frac{K(s+3)}{s(s+1)}$
(c) $\frac{K(s+1)}{s(s+3)}$ (d) $\frac{Ks}{(s+1)(s+3)}$

Q.44 The open-loop transfer function of negative feedback system is

$$G(s)H(s) = \frac{k(s+3)}{s(s+2)}$$

The root locus plot of the system consists a circle as shown in the figure below. The equation of this circle is



(a) $(\sigma + 4)^2 + \omega^2 = 4$

(b) $(\sigma - 3)^2 + \omega^2 = 9$

(c) $(\sigma + 3)^2 + \omega^2 = 3$

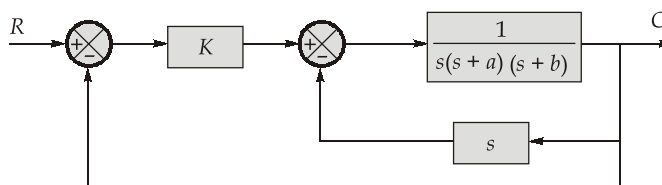
(d) $(\sigma - 4)^2 + \omega^2 = (2)^2$

Q.45 Consider a unity negative feedback system having the characteristic equation,

$$1 + \frac{K}{(s+1)(s+1.5)(s+2)} = 0$$

It is desired that, all roots of the characteristic equation have real parts less than or equal to -1 . The maximum value of K , that satisfies the given condition is _____.

Q.46 Consider the unity feedback system which employs rate feedback as shown in the figure.



The undamped oscillation frequency of this system is

(a) $\sqrt{ab} + 1$ rad/sec

(b) \sqrt{ab} rad/sec

(c) $\sqrt{ab+1}$ rad/sec

(d) $ab + 1$ rad/sec

Q.47 A unity negative feedback control system has an amplifier with gain $K = 10$ and gain ratio

$$G(s) = \frac{1}{s(s+2)}$$

in the forward path. A derivative negative feedback $H(s) = K_0 s$ is introduced as

a minor loop around $G(s)$. The value of derivative feedback constant K_0 such that the system damping ratio is 0.6 will be _____.

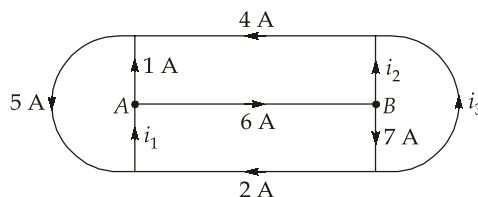
Q.48 The open loop transfer function of a unity feedback control system is given by

$$G(s) = \frac{10}{s(s+A)}$$

If the step response of the closed loop system will have 0% overshoot and minimum settling time then, the value of 'A' is _____.

Multiple Select Questions (MSQ)

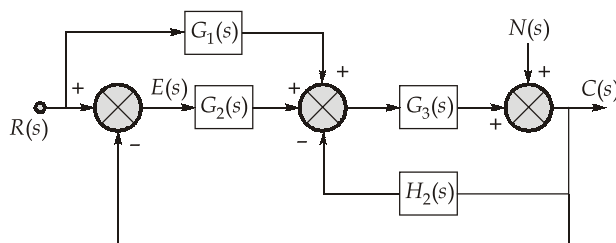
Q.49 For the given circuit :



Which of the following is correct?

- (a) $i_1 = 7 \text{ A}$ (b) $i_3 = 5 \text{ A}$
(c) $i_2 = 1 \text{ A}$ (d) $i_2 = -1 \text{ A}$

Q.50 The block diagram of a control system is shown in figure.



Which of the following statements is/are true?

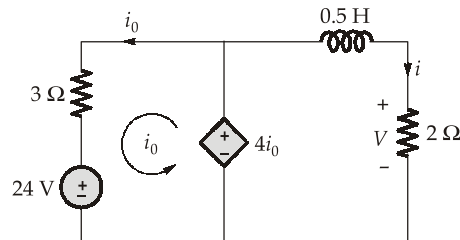
- (a) $\left. \frac{C(s)}{R(s)} \right|_{N(s)=0} = \frac{G_1 G_3 + G_2 G_3}{1 + G_3 H_1 + G_2 G_3}$ (b) $\left. \frac{C(s)}{N(s)} \right|_{R(s)=0} = \frac{G_1 G_3 + G_2 G_3}{1 + G_3 H_1 + G_2 G_3}$
(c) $\left. \frac{C(s)}{N(s)} \right|_{R(s)=0} = \frac{1}{1 + G_3 H_1 + G_2 G_3}$ (d) $\left. \frac{C(s)}{R(s)} \right|_{N(s)=0} = \frac{1}{1 + G_3 H_1 + G_2 G_3}$

■■■■

Detailed Explanations

26. (c)

At $t < 0$, the circuit can be redrawn as



By using KVL in first loop, we get,

$$3i_0 + 24 - 4i_0 = 0$$

or $i_0 = 24$

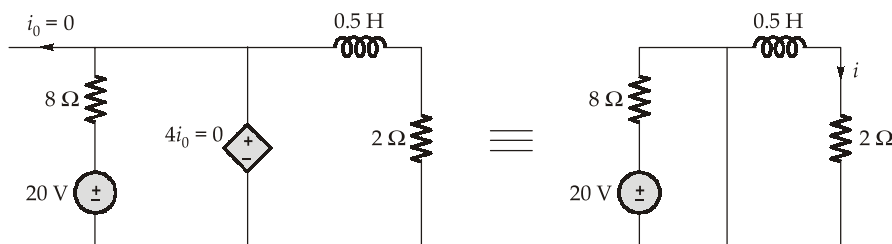
\therefore Under steady state, the inductor behaves as a short circuit,

$\therefore v(0^-) = 4 \times i_0 = 96 \text{ V}$

and $i(0^-) = i(0^+) = \frac{96}{2} = 48 \text{ A} \quad \dots(i)$

For $t > 0$, the switch moves to 'B',

\therefore The circuit can be modified as



Due to short circuit the current $i(\infty) = 0$

$\therefore i(t) = i(\infty) + [i(0) - i(\infty)]e^{-t/\tau}$

where $R_{Th} = 2 \Omega$ and $\tau = \frac{L}{R_{Th}} = \frac{0.5}{2} = \frac{1}{4}$

$\therefore i(t) = 48e^{-4t}$

and $v(t) = 2i(t) = 96e^{-4t} u(t) \text{ V}$

27. 23.44 (23.20 to 23.80)

For maximum power transfer to the load,

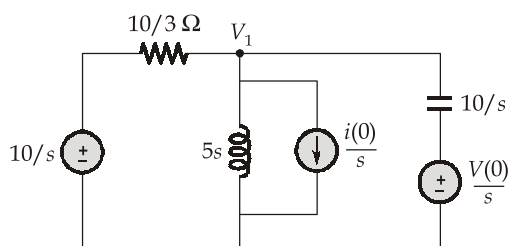
$$Z_L = Z_{Th}^*$$

$\therefore Z_L = (120 - j60) \Omega$

$\therefore I_{Lrms} = \frac{150}{\sqrt{2} \times (Z_L + Z_{Th})} = \frac{150}{\sqrt{2} \times 240} = 0.442 \text{ A}$

and $P_{avg} = |I_{Lrms}|^2 \times 120$
 $= (0.442)^2 \times 120 = 23.44 \text{ W}$

28. (d)

 The circuit can be represent in s -domain as


Using nodal equation at (1), we get,

$$\frac{V_1 - 10/s}{10/3} + \frac{V_1 - 0}{5s} + \frac{i(0)}{s} + \frac{V_1 - (V(0)/s)}{10/s} = 0$$

$$0.1 \left(s + 3 + \frac{2}{s} \right) V_1 = \frac{3}{s} + \frac{1}{s} + 0.5$$

 where, $v(0) = 5$ V and $i(0) = -1$ A

Simplifying, we get,

$$(s^2 + 3s + 2)V_1 = 40 + 5s$$

$$\text{or} \quad V_1 = \frac{40 + 5s}{(s+1)(s+2)}$$

Using partial fraction, we get,

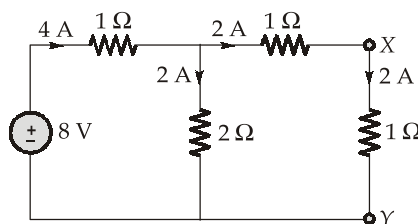
$$V_1 = \frac{35}{(s+1)} - \frac{30}{(s+2)}$$

Taking inverse Laplace transform, we get,

$$v_1(t) = v_c(t) = (35e^{-t} - 30e^{-2t}) u(t) \text{ V}$$

29. (b)

Considering figure (a), we get,



Here,

$$I_{XY} = 2 \text{ A and } V_{XY} = 2 \text{ V}$$

 \therefore

$$V_{XY} = Z_{XY} I_{XY} + E$$

$$2 = j2 \times 2 + E$$

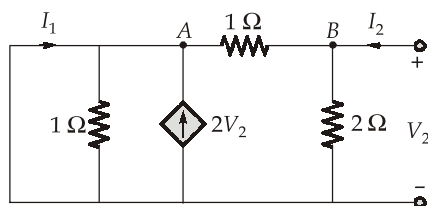
or

$$E = (2 - j4) \text{ V}$$

$$= 2\sqrt{5} \angle -63.43^\circ \text{ V}$$

30. (2)

Let us calculate the y -parameter, for this, considering $V_1 = 0$, the circuit can be redrawn as



\therefore KCL at node (A) results in

$$-I_1 - 2V_2 - \left(I_2 - \frac{V_2}{2}\right) = 0$$

or $I_1 + I_2 = -\frac{3}{2}V_2$... (i)

By KVL in outer loop,

$$V_2 = 1 \times \left(I_2 - \frac{V_2}{2}\right)$$

$$\Rightarrow \frac{3}{2}V_2 = I_2$$

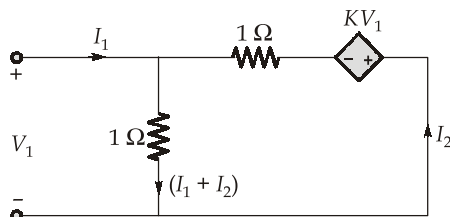
$$\therefore y_{22} = \left. \frac{I_2}{V_2} \right|_{V_1=0} = \frac{3}{2} \text{ S} \quad \dots (i)$$

From equation (i), we get,

$$I_1 + \frac{3}{2}V_2 = -\frac{3}{2}V_2$$

or $y_{12} = \left. \frac{I_1}{V_2} \right|_{V_1=0} = -3 \text{ S}$

Now by keeping $V_2 = 0$, the circuit can be redrawn as



Here, $V_1 = I_1 + I_2$... (iii)

and $KV_1 + I_2 + V_1 = 0$

or $I_2 = -(1+K)V_1$

$$\therefore y_{21} = \left. \frac{I_2}{V_1} \right|_{V_2=0} = -(1+K)$$

For reciprocal network,

$$y_{12} = y_{21}$$

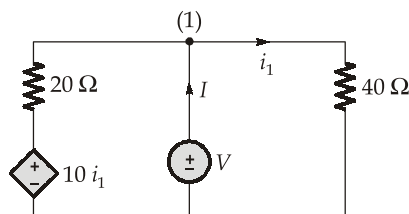
$$-3 = -(1+K)$$

$$\Rightarrow K = 2$$

31. (c)

For maximum power transfer,

$$R = R_{Th}$$

 Finding R_{Th} in the circuit, by removing independent voltage source, as


By KCL at (1), we get,

$$\frac{V - 10i_1}{20} + \frac{V}{40} = I$$

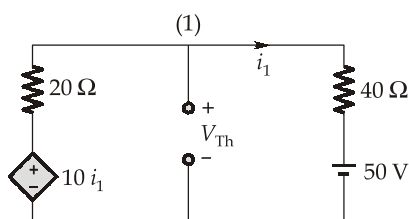
but $i_1 = \frac{V}{40}$

$$\therefore \frac{V - 10\left(\frac{V}{40}\right)}{20} + \frac{V}{40} = I$$

$$\text{or } \frac{\frac{6V}{4} + V}{40} = I$$

$$\text{or } \frac{10V}{160} = I$$

$$\text{or } \frac{V}{I} = \frac{160}{10} = 16 \Omega$$

 Finding V_{Th} :


By KCL at (i),

$$\frac{V_{Th} - 10i_1}{20} + \frac{V_{Th} - 50}{40} = 0$$

$$\frac{V_{Th}}{20} - \frac{1}{2} \left(\frac{V_{Th} - 50}{40} \right) + \left(\frac{V_{Th} - 50}{40} \right) = 0$$

$$\frac{V_{Th}}{20} + \frac{V_{Th}}{80} - \frac{50}{80} = 0$$

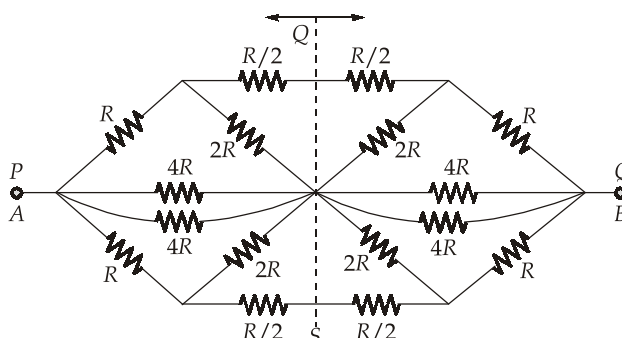
$$\text{or } 5V_{Th} = 50$$

$$\text{or } V_{Th} = 10 \text{ V}$$

$$\therefore P_{\max} = \frac{V_{Th}^2}{4R_{Th}} = \frac{10^2}{4 \times 16} = 1.56 \text{ W}$$

32. 1.037 (0.90 to 1.20)

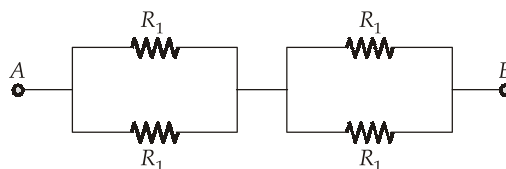
As the hexagon is symmetric, the equivalent resistance across first part (PQ) is



$$R_1 = (2R \parallel R/2 + R) \parallel 4R$$

$$= \frac{28}{27}R$$

\therefore



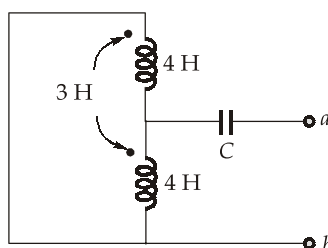
$$R_{AB} = (R_1 \parallel R_1) + (R_1 \parallel R_1) = 2 \left(\frac{28}{27} \parallel \frac{28}{27} \right) R = \frac{28}{27} R \Omega = 1.037 R \Omega$$

33. 1.785 (1.50 to 1.90)

The Thevenin's equivalent voltage with terminals $a - b$ open circuited is obtained as

$$V_{Th} = V \times \frac{1}{2} = 50 \sin 400t \quad (\text{By voltage division rule})$$

In order to find Thevenin's equivalent impedance, the circuit can be redrawn as



$$Z_{Th} = j\omega \left[\frac{L_1 L_2 - M^2}{L_1 + L_2 - 2M} \right] - \frac{j}{\omega C}$$

$$= j400 \left[\frac{4 \times 4 - 3^2}{4 + 4 - 6} \right] - \frac{j}{\omega C} = \left(j1400 - \frac{j}{400C} \right)$$

∴ Current through load impedance,

$$I_L = \frac{V_{Th}}{Z_L + Z_{Th}} = \frac{50 \sin 400t}{\left(j1400 - \frac{j}{400C}\right) + Z_L}$$

∴

$$V_L = I_L \times Z_L$$

∴ The voltage will be independent of Z_L if

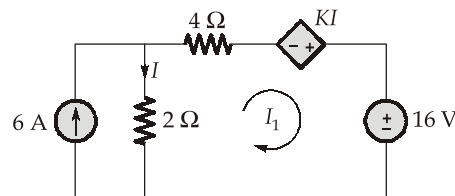
$$j1400 = \frac{j}{400C}$$

or

$$C = \frac{1}{1400 \times 400} = 1.785 \mu\text{F}$$

34. (2)

Redrawing the given circuit, we have,



By KVL, we get,

$$4I_1 - KI + 16 + 2(I_1 - 6) = 0$$

or

$$I_1 = \left(\frac{KI - 4}{6}\right) \quad \dots(i)$$

Also,

$$\begin{aligned} I &= (6 - I_1) \\ &= 6 - \left(\frac{KI - 4}{6}\right) \end{aligned}$$

$$I = \frac{40 - KI}{6}$$

or

$$I = \frac{40}{6 + K}$$

∴ Power dissipated in 2Ω resistor is 50 W.

∴

$$P_{2\Omega} = I^2 \times 2 = 50$$

or

$$I = \sqrt{\frac{50}{2}} = 5 \text{ A}$$

⇒

$$\frac{40}{6 + K} = 5$$

or

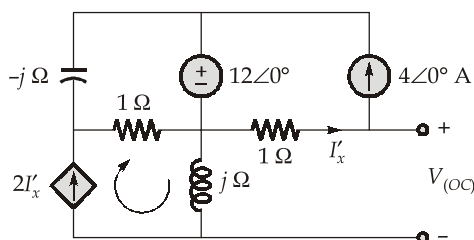
$$5K = 10$$

or

$$K = 2$$

35. (a)

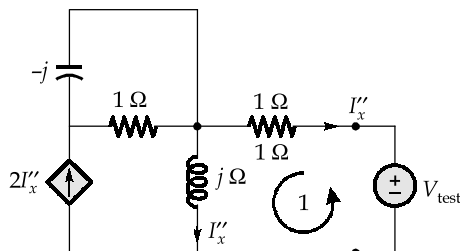
The value of $V_{(OC)}$ can be calculated by removing $1\ \Omega$ resistor



thus, the value of $I'_x = 4\angle 0^\circ$ and current flowing through $j\ \Omega = 2I'_x$

$$\begin{aligned} \text{thus, } V_{OC} &= -4\angle 0^\circ + j(2I'_x) \\ &= -4 + 8j\text{ V} \end{aligned}$$

now, applying a test voltage to find R_{th} we get,



Applying RCL in loop (1)

$$jI''_x - I''_x - V_{test} = 0$$

$$I''_x = \frac{-V_{test}}{1-j}$$

$$\therefore Z_{th} = \frac{-V_{test}}{I''_x} = 1-j\ \Omega$$

36. (d)

Applying KCL at node $V(t)$ we get,

$$i(t) = C \frac{dv_c(t)}{dt} + \frac{v_c(t)}{R} \quad \dots(1)$$

$$\therefore 4i(t) = \frac{dv(t)}{dt} + 2v(t) \text{ for } t > 0$$

for $t > 0$, the 24 V is connected to the circuit.

Thus applying KVL we get

$$\frac{Ldi(t)}{dt} + R_1i(t) + v(t) = 24 \quad \dots(2)$$

$$\frac{di(t)}{dt} + \frac{R_1}{L}i(t) + \frac{v(t)}{L} = \frac{24}{L}$$

$$\therefore \frac{di(t)}{dt} + 5i(t) + 0.5v(t) = 12 \text{ for } t > 0$$

Combining eqn. (1) and (2) we get,

$$\frac{d^2v(t)}{dt^2} + \left(\frac{1}{R_1C} + \frac{R_1}{L} \right) \frac{dv(t)}{dt} + \frac{R_1 + R_2}{R_2LC} v(t) = \frac{24}{LC}$$

$$\therefore \frac{d^2v(t)}{dt^2} + 7 \frac{dv(t)}{dt} + 12v(t) = 48 \quad \text{for } t > 0.$$

Thus option 'd' is incorrect.

37. (1.2)

Since all the branches are connected in parallel to the current source. Thus,

$$\frac{i_1}{i_2} = \frac{\frac{1/50}{R_{eq}}}{\frac{1/60}{R_{eq}}} = \frac{60}{50} = \frac{6}{5} = 1.2$$

where $R_{eq} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \frac{1}{R_4}$

38. (3.05) (2 to 4)

Now,
$$\frac{V_0(s)}{V_A(s)} = \frac{-4}{1000} \times \left[\frac{s/C}{s^2 + s/RC + \frac{1}{LC}} \right]$$

at resonance, $\omega_0 = \frac{1}{\sqrt{LC}}$ (for maximum value of gain)

$$\therefore 2\pi(91.1 \times 10^6) = \frac{1}{\sqrt{LC}}$$

$$\therefore C = 3.05 \text{ pF}$$

39. (c)

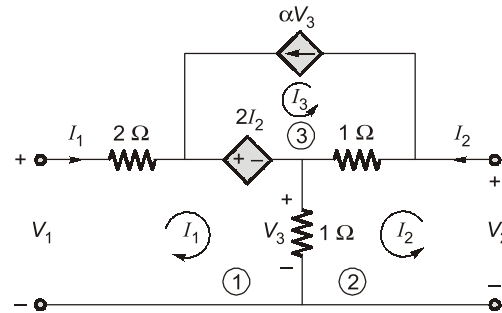
$$R_p = R(1 + Q^2)$$

Now,
$$Q = \frac{|X_L|}{R_L} = \frac{20}{20} = 1$$

$$\therefore R_p = 20 \times 2 = 40 \Omega$$

and
$$jX_p = j20 \left(1 + \frac{1}{Q^2} \right) = j40 \Omega$$

40. (-2)



Writing the KVL equation in loop (1), we get,

$$\begin{aligned} V_1 &= 2I_1 + 2I_2 + I_1 + I_2 \\ V_1 &= 3I_1 + 3I_2 \end{aligned} \quad \dots(i)$$

Writing the KVL equation for loop (2), we get,

$$\begin{aligned} V_2 &= 2I_2 + I_1 + (-\alpha V_3) \\ \text{Also, } V_2 &= V_3 + (I_2 - \alpha V_3) \\ V_2 &= I_2 + (1 - \alpha)V_3 \end{aligned} \quad \dots(ii)$$

$$\therefore V_3 = (I_1 + I_2) \times 1 \Omega \quad \dots(iii)$$

\therefore From equations (ii) and (iii),

$$\begin{aligned} V_2 &= I_2 + (1 - \alpha)(I_1 + I_2) \\ &= I_2 + (1 - \alpha)I_2 + (1 - \alpha)I_1 \\ &= (1 - \alpha)I_1 + (2 - \alpha)I_2 \end{aligned} \quad \dots(iv)$$

From equations (i) and (iv),

$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} 3 & 3 \\ (1 - \alpha) & (2 - \alpha) \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

For the circuit to be reciprocal,

$$\begin{aligned} Z_{12} &= Z_{21} \\ (1 - \alpha) &= 3 \end{aligned}$$

$$\begin{aligned} \text{or } -\alpha &= 3 - 1 = 2 \\ \text{or, } \alpha &= -2 \end{aligned}$$

41. (d)

The number of encirclements (N) of the Nyquist plot about the point $(-1 + j0)$ can be given by,

$$N = P - Z$$

Here, P = Number of open-loop poles in the RHS of s -plane

Z = Number of closed-loop poles in the RHS of s -plane

$s(s^3 + 2s^2 + s + 1) = 0$ does not produce any roots in the RHS of s -plane. So, $P = 0$.

The characteristic equation of the closed-loop system is,

$$s(s^3 + 2s^2 + s + 1) + K(s^2 + s + 1) = 0$$

$$s^4 + 2s^3 + (1 + K)s^2 + (1 + K)s + K = 0$$

Using the RH criteria,

s^4	1	$(1 + K)$	K
s^3	2	$(1 + K)$	0
s^2	$\frac{(1 + K)}{2}$	K	0
s^1	$\frac{(1 - K)^2}{(1 + K)}$	0	0
s^0	K	0	0

- For $K = 1$, row of zeros occurs and the system becomes marginally stable.
- For $K > 1$, system becomes stable.
- For $0 < K < 1$, system becomes stable.

So, for $K = 1$, the Nyquist plot passes through $(-1 + j0)$ point. Hence, statement S_3 is correct.

For $K > 1$, the system is stable. So, $Z = 0$ and $N = P - Z = 0 - 0 = 0$.

For $0 < K < 1$, the system is stable. So, $Z = 0$ and $N = P - Z = 0 - 0 = 0$.

Hence, statements S_1 and S_2 are incorrect.

42. (3)

$$\cos(\phi) = \zeta = 0.50 \Rightarrow \phi = \cos^{-1}(0.50) = 60^\circ$$

Let, the $\zeta = 0.50$ line intersects the root locus plot at point "P" in the s-plane.

$$\text{So, } P = r \angle 120^\circ = -\frac{r}{2} + j\sqrt{3}\frac{r}{2}$$

From angle condition,

$$\angle G(s)|_{s=P} = \pm 180^\circ$$

$$G(s)|_{s=P} = \frac{K}{(r \angle 120^\circ) \left(2 - \frac{r}{2} + j\sqrt{3}\frac{r}{2} \right)^2}$$

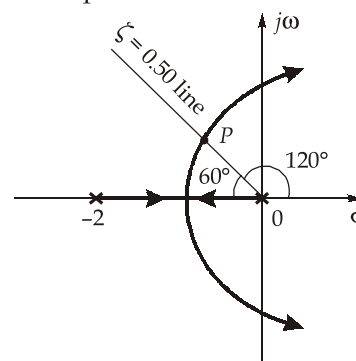
$$-\left[120^\circ + 2 \tan^{-1} \left(\frac{\sqrt{3}r}{4-r} \right) \right] = \pm 180^\circ$$

$$\tan^{-1} \left(\frac{\sqrt{3}r}{4-r} \right) = 30^\circ$$

$$\frac{\sqrt{3}r}{4-r} = \tan(30^\circ) = \frac{1}{\sqrt{3}}$$

$$3r = 4 - r$$

$$r = 1$$



So, the $\xi = 0.50$ line intersects the root locus plot at a radial distance of 1 from the origin.

From cosine rule,

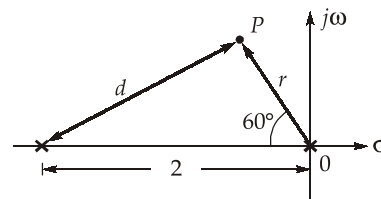
$$d^2 = (2)^2 + r^2 - 2(2)(r)\cos(60^\circ)$$

$$= 4 + (1)^2 - (2)(1) = 3$$

$$d = \sqrt{3}$$

From magnitude condition,

$$K_0 = \frac{\Pi(\text{Vector distances from OL poles})}{\Pi(\text{Vector distances from OL zeros})} = \sqrt{3} \times \sqrt{3} \times 1 = 3$$



43. (b)

The root loci starts from $s = -1$ and 0 and ends at -3 and ∞ . Hence poles are at $-1, 0$ and zeros

are at $-3, \infty$. Thus, the transfer function will be $\frac{K(s+3)}{s(s+1)}$.

44. (c)

For root locus plot

$$\angle G(s)H(s) = 180^\circ$$

\therefore substituting $s = \sigma + j\omega$ we get

$$G(\sigma + j\omega)H(\sigma + j\omega) = \frac{k(\sigma + 3 + j\omega)}{(\sigma + j\omega)(\sigma + 2 + j\omega)}$$

$$\Rightarrow \tan^{-1}\left(\frac{\omega}{\sigma+3}\right) - \tan^{-1}\left(\frac{\omega}{\sigma}\right) = 180^\circ + \tan^{-1}\left(\frac{\omega}{\sigma+2}\right)$$

$$\frac{\frac{\omega}{\sigma+3} - \frac{\omega}{\sigma}}{1 + \left(\frac{\omega}{\sigma+3}\right)\left(\frac{\omega}{\sigma}\right)} = \frac{\omega}{\sigma+2}$$

$$\frac{-3\omega}{\sigma(\sigma+3) + \omega^2} = \frac{\omega}{\sigma+2}$$

$$-3(\sigma+2) = \sigma(\sigma+3) + \omega^2$$

$$(\sigma^2 + 6\sigma + 9) + \omega^2 = -6 + 9$$

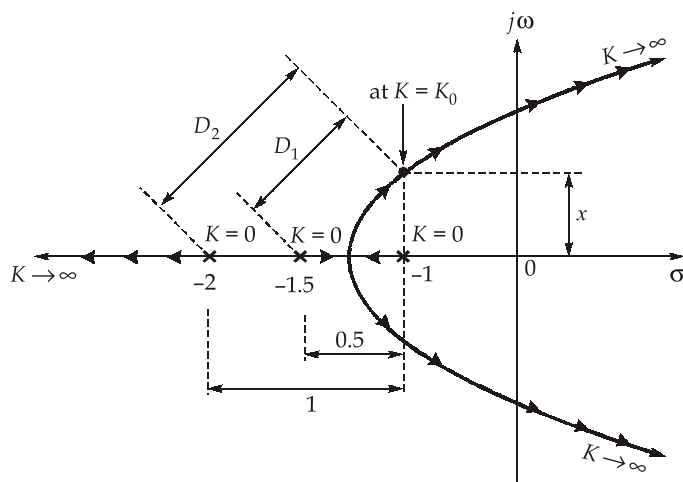
$$(\sigma+3)^2 + \omega^2 = 3$$

45. 0.75 (0.60 to 0.90)

The loop transfer function,

$$G(s)H(s) = \frac{K}{(s+1)(s+1.5)(s+2)}$$

Drawing the root locus plot of the corresponding system,



From root locus diagram, it is clear that, for $K \leq K_0$, all roots of the characteristic equation have real parts less than or equal to -1

To determine the value of K_0 :

If we know the value of ' x ', then it is very easy to determine the value of K_0 .

- Using angle condition, to determine the value of " x ".

$$\angle G(s)H(s) \Big|_{s=-1+jx} = -180^\circ$$

$$-90^\circ - \tan^{-1}(2x) - \tan^{-1}(x) = -180^\circ$$

$$\tan^{-1}\left(\frac{3x}{1-2x^2}\right) = 90^\circ$$

$$1 - 2x^2 = 0$$

$$x = \frac{1}{\sqrt{2}} \text{ rad/sec}$$

- Using magnitude condition, to determine the value of K_0

$$|G(s)H(s)| \Big|_{s=-1+jx} = 1$$

or,

$$K_0 = (D_1)(D_2)(x)$$

$$x = \frac{1}{\sqrt{2}}; D_1 = \sqrt{0.25 + x^2} = \sqrt{0.75}; D_2 = \sqrt{1 + x^2} = \sqrt{1.50}$$

$$\text{So, } K_0 = \frac{1}{\sqrt{2}} \times \sqrt{0.75} \times \sqrt{1.50} = 0.75$$

46. (c)

$$\frac{C(s)}{R(s)} = \frac{K}{s(s+a)(s+b)+s+K}$$

Characteristic equation $\Rightarrow s^3 + (a+b)s^2 + (ab+1)s + K = 0$

Routh Table

s^3	1	$ab+1$
s^2	$a+b$	K
s^1	$\frac{(a+b)(ab+1)-K}{a+b}$	
s^0	K	

For undamped oscillations, s^1 Row must have all zeros.

$$(a+b)(ab+1) = K$$

Also auxiliary equation

$$A(s) \Rightarrow (a+b)s^2 + K = 0$$

at $s = j\omega$

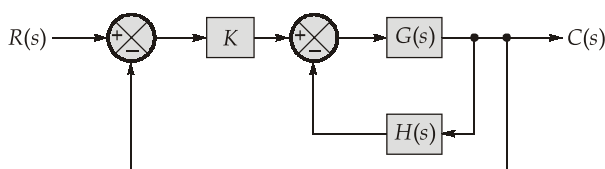
$$(a+b)(-\omega^2) + K = 0$$

$$\omega^2 = \frac{K}{a+b} = \frac{(a+b)(ab+1)}{(a+b)}$$

$$\omega = (\sqrt{ab+1}) \text{ rad/sec}$$

47. 1.794 (1.60 to 2.00)

The block diagram representation of the given system is



Where $K = 10$, $G(s) = \frac{1}{s(s+2)}$ and $H(s) = K_0 s$

The closed-loop transfer function is,

$$\begin{aligned} \frac{C(s)}{R(s)} &= \frac{K \frac{G(s)}{1 + G(s)H(s)}}{1 + \frac{KG(s)}{1 + G(s)H(s)}} = \frac{KG(s)}{1 + KG(s) + G(s)H(s)} \\ &= \frac{\frac{10}{s(s+2)}}{1 + \frac{10}{s(s+2)} + \frac{K_0 s}{s(s+2)}} = \frac{10}{s(s+2) + 10 + K_0 s} \end{aligned}$$

or
$$\frac{C(s)}{R(s)} = \frac{10}{s^2 + (2 + K_0)s + 10}$$

Comparing the above equation with standard second order equation, we get,

and
$$2\xi\omega_n = (2 + K_0)$$

Here
$$\omega_n = \sqrt{10} = 3.162 \text{ rad/sec}$$

given,
$$\xi = 0.6$$

$$2 \times 0.6 \times \sqrt{10} = 2 + K_0$$

$$K_0 = [2 \times 0.6 \times 3.162 - 2] = 1.794$$

48. (6.325)(6.25 to 6.45)

Minimum settling time and 0% overshoot means 100% damping ratio i.e., $\xi = 1$.

From given system,

$$T(s) = \frac{10}{s^2 + As + 10}$$

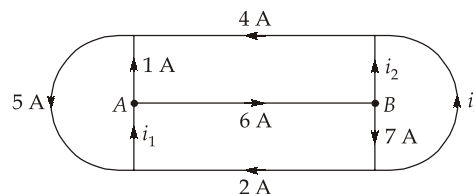
Here,
$$\omega_n = \sqrt{10}$$

and
$$2\xi\omega_n = A$$

$\therefore A = 2 \times 1 \times \sqrt{10}$

$$= 2\sqrt{10} = 6.3245$$

49. (a, b, d)



Applying KCL at A

$$1 + 6 = i_1$$

$$i_1 = 7 \text{ A}$$

Applying KCL at B

$$i_2 + 7 = 6$$

$$i_2 = -1 \text{ A}$$

Applying KCL at C

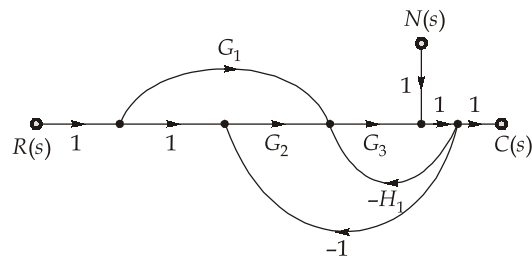
$$i_2 + i_3 = 4$$

$$-1 + i_3 = 4$$

$$i_3 = 5 \text{ A}$$

50. (a, c)

Signal flow diagram



To find $\frac{C(s)}{R(s)}$ when $N(s) = 0$

The two forward paths are

$$P_1 = G_1 G_3$$

$$P_2 = G_2 G_3$$

The closed loop touches both the forward paths, therefore path factors are

$$\Delta_1 = 1 \quad \text{and} \quad \Delta_2 = 1$$

The individual loops are $L_1 = -G_3 H_1$ and $L_2 = -G_2 G_3$

Applying Mason's gain formula the closed loop transfer function.

$$\left. \frac{C(s)}{R(s)} \right|_{N(s)=0} = \frac{G_1 G_3 + G_2 G_3}{1 + G_3 H_1 + G_2 G_3}$$

To find $\left. \frac{C(s)}{N(s)} \right|_{R(s)=0}$

There is single forward path having gain

$$P_1 = 1$$

The path factor $\Delta_1 = 1$.

The individual loops are

$$L_1 = -G_3 H_1 \quad \text{and} \quad L_2 = -G_2 G_3$$

$$R(s) = 0$$

$$\frac{C(s)}{N(s)} = \frac{1}{1 + G_3 H_1 + G_2 G_3}$$

■■■■