

Q.1(a)

Given

$$A = \begin{bmatrix} \frac{1}{2}(1+i) & \frac{1}{2}(-1+i) \\ \frac{1}{2}(1+i) & \frac{1}{2}(1-i) \end{bmatrix}$$

As we know for unitary matrix

$$AA^D = I$$

$$\bar{A} = \begin{bmatrix} \frac{1}{2}(1-i) & \frac{1}{2}(-1-i) \\ \frac{1}{2}(1-i) & \frac{1}{2}(1+i) \end{bmatrix}$$

$$(\bar{A})^T = A^D = \begin{bmatrix} \frac{1}{2}(1-i) & \frac{1}{2}(1-i) \\ \frac{1}{2}(-1-i) & \frac{1}{2}(1+i) \end{bmatrix}$$

$$AA^D = \begin{bmatrix} \frac{1}{2}(1+i) & \frac{1}{2}(-1+i) \\ \frac{1}{2}(1+i) & \frac{1}{2}(1-i) \end{bmatrix} \begin{bmatrix} \frac{1}{2}(1-i) & \frac{1}{2}(1-i) \\ \frac{1}{2}(-1-i) & \frac{1}{2}(1+i) \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{4}(1+1+1+1) & \frac{1}{4}(1+i-i-i) \\ \frac{1}{4}(1+i-i-i) & \frac{1}{4}(1+1+1+1) \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I \quad \rightarrow \therefore A \text{ is unitary matrix}$$

$$|A| = \frac{1}{4} (1+i)(1-i) - \frac{1}{4} (1+i)(-1+i)$$

$$= \frac{1}{4} [1+1 - (-1-1)]$$

$$= \frac{1}{4} \times 4 = 1$$

$$\text{Adj } A = \begin{bmatrix} \frac{1}{2}(1-i) & -\frac{1}{2}(-1+i) \\ -\frac{1}{2}(1+i) & \frac{1}{2}(1+i) \end{bmatrix}$$

$$\therefore A^{-1} = \frac{\text{adj } A}{|A|} = \begin{bmatrix} \frac{1}{2}(1-i) & -\frac{1}{2}(-1+i) \\ -\frac{1}{2}(1+i) & \frac{1}{2}(1+i) \end{bmatrix}$$

Q.1(b)

Case-1

$$r_1 = 1.5 \text{ m}, h_1 = 4 \text{ m}$$

$$\text{Vol. of balloon } V_1 = \pi r_1^2 h_1$$

$$= \pi \times 1.5^2 \times 4$$

Case-2

$$r_2 = 1.5 + 0.01 = 1.51 \text{ m}$$

$$h_2 = 4 + 0.05 = 4.05 \text{ m}$$

$$\text{Vol. of balloon } V_2 = \pi r_2^2 h_2$$

$$= \pi \times 1.51^2 \times 4.05$$

$$\% \text{ Change in Vol.} = \frac{V_2 - V_1}{V_1} \times 100$$

$$= \frac{\pi \times 1.51^2 \times 4.05 - \pi \times 1.5^2 \times 4}{\pi \times 1.5^2 \times 4} \times 100 = 2.6045\%$$

↑ 2.61%

Q. 1(d)

Given -

$$v_s(t) = 4 \cos \omega_0 t \text{ Volt}$$

$$i_s(t) = 3 \cos(\omega_0 t - 30^\circ) + 2 \cos(3\omega_0 t - 50^\circ) \text{ Amp.}$$

(i)

$$V_{s_{rms}} = \frac{4}{\sqrt{2}} = 2.828 \text{ Volt}$$

$$I_{s_{rms}} = \sqrt{\frac{3^2}{2} + \frac{2^2}{2}} = 2.5495 \text{ Amp.}$$

(ii)

$$P_{avg} = V_{s_{rms}} I_{s_{rms}} \cos \phi$$

$$= \frac{4}{\sqrt{2}} \times \frac{3}{\sqrt{2}} \times \cos 30^\circ$$

$$= 5.196 \text{ Watt}$$

(iii)

$$V_{s_{rms}} = \frac{4}{\sqrt{2}} = 2.828 \text{ Volt}$$

$$I_{s_{rms}} = \frac{2}{\sqrt{2}} = 2.12 \text{ Amp.}$$

(iv)

$$g_{\text{current}} = \frac{I_{s_{rms}}}{I_{s_{rms}}} = \frac{2.12}{2.5495} = 0.832$$

$$THD_{\text{current}} = \sqrt{\frac{1}{g_{\text{current}}^2} - 1} = 0.667$$

$$g_{\text{voltage}} = \frac{V_{s_{rms}}}{V_{s_{rms}}} = 1$$

$$THD_{\text{voltage}} = \sqrt{\frac{1}{1} - 1} = 0$$

(v)

$$Pf = \frac{5.196}{2.828 \times 2.5495} = 0.721 \text{ lag.}$$



Q.1(e) AIC to ques.

4

$$V_o = E_b + I_o R_o$$

$$\frac{3V_{mL}}{\pi} \cos \alpha - GfL_s I_o = 400 + 20 \times 1$$

$$\frac{3 \times 230 \times \sqrt{2}}{\pi} \cos \alpha = 400 + 20 + 6 \times 50 \times 4 \times 10^{-3} \times 20 = 444$$

$\Rightarrow 444$

$$\cos \alpha = \frac{444 \times \pi}{2 \sqrt{2} \times 230}$$

$$\alpha = 34.38^\circ$$

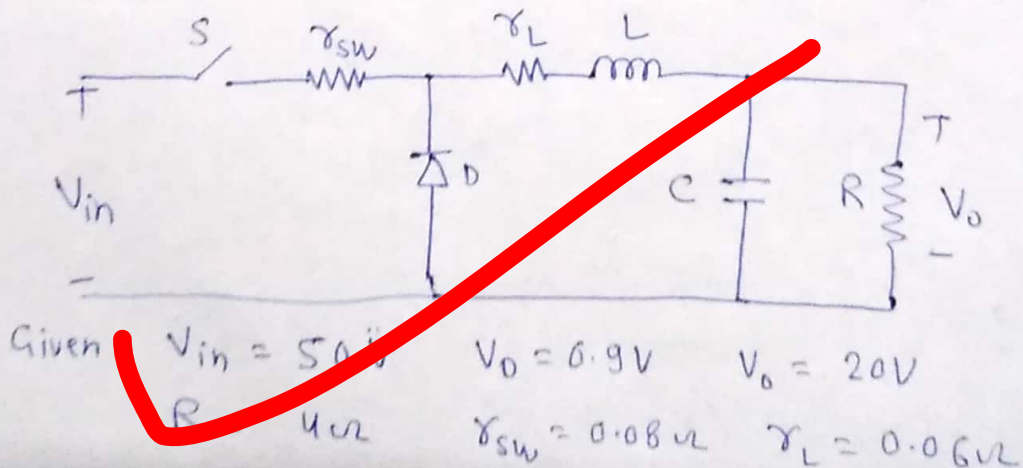
$$\Delta V_o = \frac{V_{d0}}{2} [\cos \alpha - \cos(\alpha + \mu)]$$

$$GfL_s I_o = \frac{3V_{mL}}{2\pi} [\cos \alpha - \cos(\alpha + \mu)]$$

$$6 \times 50 \times 4 \times 10^{-3} \times 20 = \frac{3 \times \sqrt{2} \times 230}{2\pi} [\cos 34.38 - \cos(34.38 + \mu)]$$

$$\mu = 8.22^\circ$$

Q.1(c)



$$P_S = P_0 + P_L$$

$$V_S I_S = V_0 I_0 + I_S^2 r_{sw} + I_S^2 r_L + V_D I_0$$

$$V_S \frac{I_S}{\alpha} = V_0 \times \frac{I_S}{\alpha} + \frac{I_S^2}{\alpha} r_{sw} + \frac{I_S^2}{\alpha} r_L + V_D \times \frac{I_S}{\alpha}$$

$$V_S = \frac{V_0}{\alpha} + \alpha \frac{V_0}{R} r_{sw} + \alpha \frac{V_0}{R} r_L + \frac{V_D}{\alpha}$$

$$50 = \frac{20}{\alpha} + \frac{\alpha \times 20 \times 0.08}{4} + \frac{\alpha \times 20 \times 0.06}{4} + \frac{0.9}{\alpha}$$

$$50 = \frac{20.9}{\alpha} + 0.7\alpha$$

$$0.7\alpha^2 - 50\alpha + 20.9 = 0$$

$$\alpha = 0.42$$

$$\begin{aligned} \% \eta &= \frac{P_0}{P_0 + P_L} \times 100 = \frac{\frac{V_0^2}{R}}{\frac{V_0^2}{R} + I_S^2 (r_{sw} + r_L) + V_D I_0} \times 100 \\ &= \frac{20^2/4}{\frac{20^2}{4} + \frac{0.42^2 \times 20^2}{42} \times 0.14 + \frac{0.9 \times 20}{4}} \times 100 \\ &= 95.132\% \end{aligned}$$

Q. 2(a) ①  $I = \int_{0.1}^{0.5} e^{-x^3} dx$

Step size  $h = \frac{0.5 - 0.1}{4} = 0.1$

$x$	0.1	0.2	0.3	0.4	0.5
$f(x)$	0.9990	0.9920	0.9734	0.9380	0.8825
$y_0$		$y_1$	$y_2$	$y_3$	$y_4$

⑥

By Simpson's  $\frac{1}{3}$ rd rule -

$$I = \frac{h}{3} [(y_0 + y_n) + 2(y_2 + y_4 + \dots) + 4(y_1 + y_3 + \dots)]$$

$$= \frac{0.1}{3} [(0.9990 + 0.8825) + 2 \times 0.9734 + 4 \times (0.9920 + 0.9380)]$$

$$I = 0.3849$$

By Trapezoidal rule

$$I = \frac{h}{2} [(y_0 + y_n) + 2(y_1 + y_2 + \dots)]$$

$$= \frac{0.1}{2} [(0.9990 + 0.8825) + 2(0.9734 + 0.9920 + 0.9380)]$$

$$I = 0.384415$$

⑪ Given -

$$y'' - 2y' + 2y = x + e^x \cos x$$

Auxiliary eq<sup>n</sup>

$$m^2 - 2m + 2 = 0$$

$$m = 1 \pm i$$

$$CF = e^x (c_1 \cos x + c_2 \sin x)$$

$$PI = \frac{1}{D^2 - 2D + 2} (x + e^x \cos x)$$

$$= \frac{1}{(D^2 - 2D + 2)} x + \frac{1}{D^2 - 2D + 2} e^x \cos x$$

$$= \frac{1}{2 \left[ 1 + \frac{D^2 - 2D}{2} \right]} x + \frac{e^x}{(D+1)^2 - 2(D+1) + 2} \cos x$$

Replace  
 $D \rightarrow D+1$



$$= \frac{1}{2} \left[ 1 + \frac{D^2 - 2D}{2} \right]^{-1} x + \frac{e^x}{D^2 + 1 + 2D - 2D - 2 + 2} \cos x$$

$$= \frac{1}{2} \left[ 1 - \frac{D^2 - 2D}{2} \right] x + \frac{e^x}{D^2 + 1} \cos x$$

Replace  $D^2 = -1$   
 $-1 + 1 = 0$   
 Case fail

$$= \frac{1}{2} [x - 0 + 1] + \frac{e^x}{-1} \sin x$$

$$= \frac{x+1}{2} + \frac{e^x \sin x}{-1}$$

∴ Complete sol<sup>n</sup>

$$y = CF + PI$$

$$y = e^x (c_1 \cos x + c_2 \sin x) + \frac{x+1}{2} + \frac{e^x \sin x}{-1}$$

Q. 2(b) ①

$$I = \oint_C \frac{e^z}{\cos \pi z}$$

$$|z| = 1$$

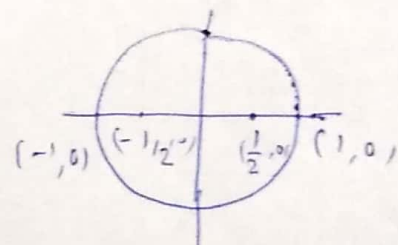
Singular pt.

$$\cos \pi z = 0$$

$$\pi z = \pm (2n+1) \frac{\pi}{2}$$

$$z = \pm (2n+1) \frac{1}{2}$$

$$= \pm \frac{1}{2}, \pm \frac{3}{2}, \dots$$



②

lies inside the unit circle

Residue for  $z = \frac{1}{2}$  :  $R_1 = \lim_{z \rightarrow \frac{1}{2}} (z - \frac{1}{2}) \frac{e^z}{\cos \pi z}$   $\frac{0}{0}$  form

By L-Hospital

$$= \lim_{z \rightarrow \frac{1}{2}} \frac{e^z + (z - \frac{1}{2}) e^z}{-\pi \sin \pi z}$$

$$R_1 = \frac{e^{1/2} + 0}{-\pi} = -\frac{e^{1/2}}{\pi}$$

$$\begin{aligned} \text{Residue for } z = -\frac{1}{2} : R_2 &= \lim_{z \rightarrow -\frac{1}{2}} (z + \frac{1}{2}) \frac{e^z}{\cos \pi z} \\ &= \lim_{z \rightarrow -\frac{1}{2}} \frac{e^z + (z + \frac{1}{2})e^z}{-\pi \sin \pi z} \\ &= \frac{e^{-1/2}}{-\pi} \end{aligned}$$

By Cauchy residue theorem -

$$\oint_C \frac{e^z}{\cos \pi z} dz = 2\pi j (\text{Sum of residue lies inside the unit circle})$$

$$= 2\pi j \left( -\frac{e^{1/2}}{\pi} - \frac{e^{-1/2}}{\pi} \right)$$

$$= -2j (e^{1/2} + e^{-1/2})$$

$$\boxed{\oint_C \frac{e^z}{\cos \pi z} dz = -4.51j}$$

(ii) By using unit step fun<sup>n</sup>  $f(t)$  can be written as -

$$\begin{aligned} f(t) &= \sin t [u(t) - u(t - \pi)] + \sin 2t [u(t - \pi) - u(t - 2\pi)] \\ &\quad + \sin 3t u(t - 2\pi) \end{aligned}$$

$$\begin{aligned} &= \sin t u(t) - \sin(t + \pi - \pi) u(t - \pi) + \sin 2(t - \pi + \pi) u(t - \pi) \\ &\quad - \sin 2(t + 2\pi - 2\pi) u(t - 2\pi) + \sin 3(t - 2\pi + 2\pi) u(t - 2\pi) \end{aligned}$$



(9)

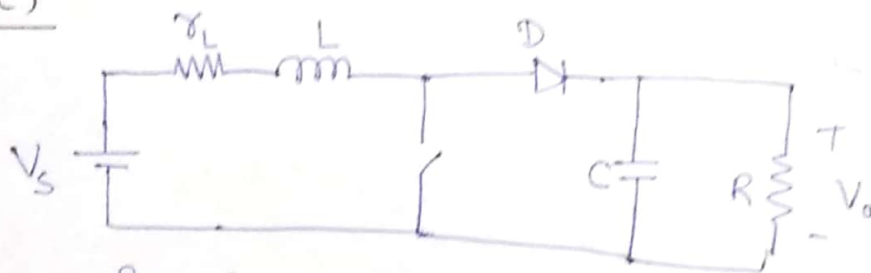
$$= 2\sin t u(t) + 2\sin(t-\pi) u(t-\pi) + 2\sin 2(t-\pi) u(t-\pi) - 2\sin 2(t-2\pi) u(t-2\pi) + 2\sin 3(t-\pi) u(t-\pi)$$

$\downarrow \int \int LT$

$$= \frac{1}{s^2+1} + \frac{e^{-\pi s}}{s^2+1} + \frac{e^{-\frac{\pi s}{2}}}{(\frac{s}{2})^2+1} - \frac{e^{-\frac{2\pi s}{2}}}{(\frac{s}{2})^2+1} + \frac{e^{-\frac{2\pi s}{3}}}{(\frac{s}{3})^2+1}$$

$$F(s) = \frac{1 + e^{-\pi s}}{s^2+1} + \frac{e^{-\frac{\pi s}{2}} - e^{-\pi s}}{(\frac{s}{2})^2+1} + \frac{e^{-\frac{2\pi s}{3}}}{(\frac{s}{3})^2+1}$$

Q. 2(c)



By Power balance -

$$P_s = P_o + P_L$$

$$V_s I_L = V_o I_D + I_L^2 r_L \quad \text{--- (1)}$$

$$\therefore I_D = (1-D) I_L$$

Substitute  $I_D$  in eq<sup>n</sup> (1)

$$V_s I_L = V_o (1-D) I_L + I_L^2 r_L$$

$$V_s = V_o (1-D) + I_L^2 r_L \quad \text{--- (2)}$$

$$\therefore I_D = \frac{V_o}{R}$$

$$I_L = \frac{V_o}{R(1-D)}$$

from eq<sup>n</sup> (2)

$$V_s = V_o (1-D) + \frac{V_o^2 r_L}{R^2 (1-D)^2}$$

$$\frac{V_s}{1-D} = V_o \left[ 1 + \frac{r_L}{R(1-D)^2} \right]$$

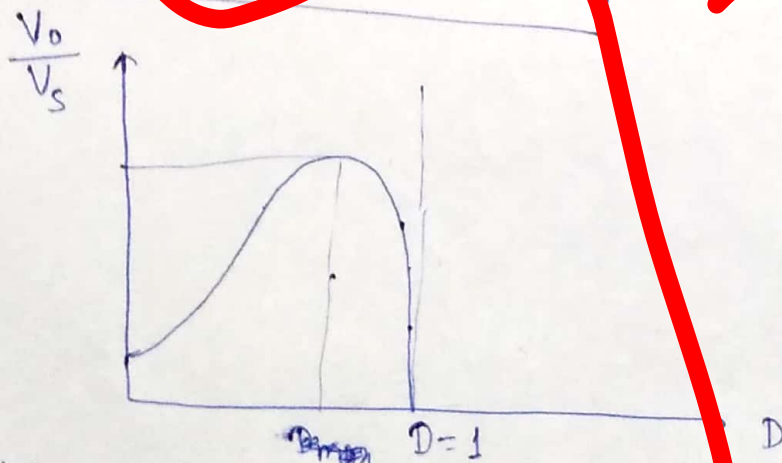
$$V_o = \frac{V_s}{1-D} \times \left[ \frac{1}{1 + \frac{r_L}{R(1-D)^2}} \right]$$

$$\therefore \eta = \frac{P_o}{P_o + P_L}$$

$$= \frac{V_o^2 / R}{\frac{V_o^2}{R} + I_L^2 r_L}$$

$$= \frac{V_o^2 / R}{\frac{V_o^2}{R} + \frac{V_o^2 r_L}{R^2 (1-D)^2}}$$

$$\eta = \frac{1}{1 + \frac{r_L}{R(1-D)^2}}$$



Q.4(b)

Given -

$$V_s = 220 \text{ V} \quad R = 0.1 \Omega \quad L = 10 \text{ mH} \quad E_b = 100 \text{ V}$$

$\therefore$  Chopper operated in 1st & 4th quadrant  
it means it is class D chopper.

for motoring mode -

(11)

$$V_o = E_b + I_o R_a$$

$$I_o = \frac{V_o - E_b}{R_a}$$

$$10 = \frac{(2\alpha_m - 1)V_s - E_b}{R_a}$$

$$10 = \frac{(2\alpha_m - 1) \times 220 - 100}{0.1}$$

$$\alpha_m = 0.7295$$

$$\therefore \alpha_c = 1 - \alpha_m = 0.27045$$

for regenerative braking -

$$V_o = E_b - I_o R_a$$

$$I_o R_a = E_b - [(2\alpha_R - 1)V_s]$$

$$10 \times 0.1 = 100 - (2\alpha_R - 1) \times 220$$

$$\alpha_R = 0.275$$

$$\begin{aligned} \text{Power returned to the source} &= E_b I_o - I_o^2 R_a \\ &= 100 \times 10 - 10^2 \times 0.1 \\ &= 990 \text{ W} \end{aligned}$$

$\therefore$  It is a class D chopper.

$$\therefore \text{Switching freq} = \frac{5 \text{ kHz}}{2} = 2.5 \text{ kHz}$$



Q. 4(a) (ii)

(12)

Given fun<sup>n</sup>

$$f(z) = \frac{1 - e^{pz}}{z^4}$$

$$\text{Residue at its pole} = \lim_{z \rightarrow 0} \frac{1}{(4-1)!} \frac{d^{4-1}}{dz^{4-1}} \left( z^4 \times \frac{1 - e^{pz}}{z^4} \right)$$

$$= \lim_{z \rightarrow 0} \frac{1}{3!} \frac{d^3}{dz^3} (1 - e^{pz})$$

$$= \lim_{z \rightarrow 0} \frac{1}{6} \left[ \frac{d^2}{dz^2} (0 - p e^{pz}) \right]$$

$$= \lim_{z \rightarrow 0} \frac{1}{6} \left[ \frac{d}{dz} (-p^2 e^{pz}) \right]$$

$$= \lim_{z \rightarrow 0} \frac{1}{6} [-p^3 e^{pz}]$$

$$= -\frac{p^3}{6}$$

Acc to ques.

$$\text{Residue at its pole} = -4/3$$

$$+ \frac{p^3}{6} = -4/3$$

$$p^3 = 8$$

$$p = \sqrt[3]{8} = 2$$

(iii) Lagrange's Mean Value theorem -

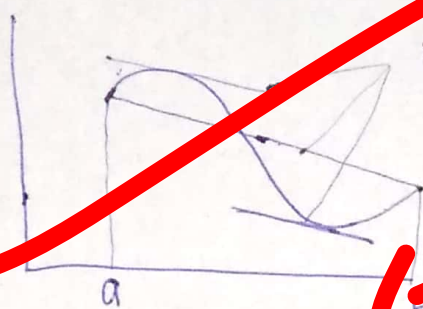
It state that if any fun<sup>n</sup> -

(i) Continuous in  $[a, b]$

(ii) Differentiable in  $(a, b)$

(iii) Then there exist a pt

$$f'(c) = \frac{f(b) - f(a)}{b - a}$$



118 to each other

← Physical significance of this theorem.

- ① Prob. of throwing 6 by A  
 (1, 5) (2, 4) (3, 3) (4, 2) (5, 1)

$$P_A = \frac{5}{36}$$

Prob. of throwing 7 by B

- (1, 6) (2, 5) (3, 4) (4, 3) (5, 2) (6, 1)

$$P_B = \frac{6}{36}$$

Prob. of winning A -

A (or)  $\bar{A} \bar{B} A$  (or)  $\bar{A} \bar{B} \bar{A} B$  (or) —

$$\frac{5}{36} + \left(1 - \frac{5}{36}\right) \left(1 - \frac{6}{36}\right) \times \frac{5}{36} + \left(1 - \frac{5}{36}\right) \left(1 - \frac{6}{36}\right) \left(1 - \frac{5}{36}\right) \left(1 - \frac{6}{36}\right) \times \frac{5}{36} + \dots$$

$$P(A) = \frac{5/36}{1 - \left(1 - \frac{5}{36}\right) \left(1 - \frac{6}{36}\right)} = \frac{30}{61}$$

Prob. of winning B -

$\bar{A} B$  (or)  $\bar{A} \bar{B} \bar{A} B$  (or)  $\bar{A} \bar{B} \bar{A} \bar{B} \bar{A} B$  (or) —

$$\left(1 - \frac{5}{36}\right) \times \frac{6}{36} + \left(1 - \frac{5}{36}\right) \left(1 - \frac{6}{36}\right) \left(1 - \frac{5}{36}\right) \times \frac{6}{36} + \dots$$

$$P(B) = \frac{\left(1 - \frac{5}{36}\right) \times \frac{6}{36}}{1 - \left(1 - \frac{5}{36}\right) \left(1 - \frac{6}{36}\right)} = \frac{31}{61}$$

Q. 4(c) ①

Given -

$$f = x^2 - y^2 + 2z^2$$

$$\Delta f = 2xi - 2yj + 4zk$$

$$\Delta f|_{(1,2,3)} = 2i - 4j + 12k$$

$$\overrightarrow{PQ} = \overrightarrow{P} - \overrightarrow{Q}$$

$$= (1-5)i - (2-0)j + (3-4)k$$

$$= -4i + 2j - k$$

Unit vector  $\hat{a} = \frac{\overrightarrow{PQ}}{|\overrightarrow{PQ}|} = \frac{-4i + 2j - k}{\sqrt{4^2 + 2^2 + 1}}$

Dir<sup>n</sup> derivative =  $\nabla f \cdot \hat{a}$

$$= (2i - 4j + 12k) \cdot \frac{-4i + 2j - k}{\sqrt{21}}$$

$$= \frac{-8 - 8 - 12}{\sqrt{21}} = -\frac{28}{\sqrt{21}}$$

Max<sup>n</sup> value =  $|2i - 4j + 12k| = \sqrt{2^2 + 4^2 + 12^2}$   
 $= 2\sqrt{41}$

①

Given -

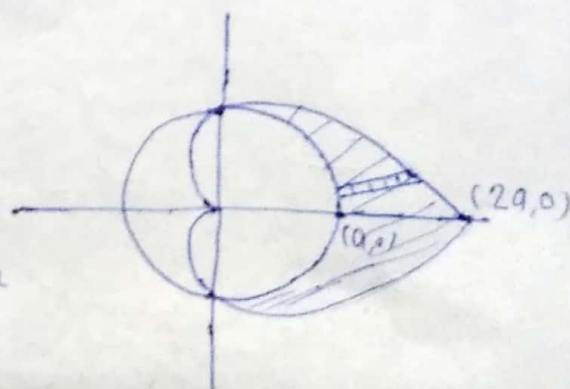
$$r = a(1 + \cos \theta)$$

$$r = a$$

Intersection of the curve

$$r = a(1 + \cos \theta)$$

$$\theta = (2n+1)\pi$$





$$I = 2 \int_0^{\pi/2} \int_{\gamma=a}^{\gamma=a(1+\cos\theta)} \gamma \, d\gamma \, d\theta$$

$$= 2 \int_0^{\pi/2} \left. \frac{\gamma^2}{2} \right|_{\gamma=a}^{a(1+\cos\theta)} d\theta$$

$$= \int_0^{\pi/2} \left[ (a(1+\cos\theta))^2 - a^2 \right] d\theta$$

$$= a^2 \int_0^{\pi/2} (1 + \cos^2\theta - 2\cos\theta - 1) d\theta$$

$$= a^2 \int_0^{\pi/2} \left[ \frac{1 + \cos 2\theta}{2} + 2\cos\theta \right] d\theta$$

$$= \frac{a^2}{2} \int_0^{\pi/2} (1 + \cos 2\theta + 4\cos\theta) d\theta$$

$$= \frac{a^2}{2} \left[ \frac{\pi}{2} + \frac{\sin 2\theta}{2} \Big|_0^{\pi/2} + 4\sin\theta \Big|_0^{\pi/2} \right]$$

$$= \frac{a^2}{2} \left[ \frac{\pi}{2} + 0 + 4(1-0) \right]$$

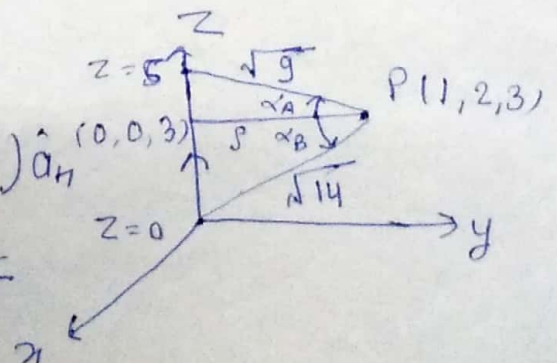
$$I = \frac{a^2}{2} \left[ \frac{\pi}{2} + 4 \right] = \frac{(\pi + 8)a^2}{4} \quad 89. \text{ unit}$$

Q. 5(a)

As we know -

$$H = \frac{I}{4\pi r^3} (\sin\alpha_B - \sin\alpha_A) \hat{a}_H$$

where  $r = \sqrt{1^2 + 2^2} = \sqrt{5}$



$$\tan \alpha_A = \frac{3-5}{\sqrt{5}} = -\frac{2}{\sqrt{5}}$$

$$\sin \alpha_A = -\frac{2}{3}$$

$$\sin \alpha_B = \frac{3}{\sqrt{14}}$$

$$\hat{a}_n = \hat{a}_x \times \hat{a}_{\perp r}$$

$$= \hat{a}_z \times \frac{\hat{a}_x + 2\hat{a}_y}{\sqrt{5}}$$

$$H = \frac{10}{4\pi \times 10^{-7}} \left( \frac{2}{\sqrt{14}} + \frac{2}{3} \right) \hat{a}_z \times \frac{\hat{a}_x + 2\hat{a}_y}{\sqrt{5}}$$

$$H = -0.468 \hat{a}_x + 0.234 \hat{a}_y \text{ A/m}$$

Q.5(b)

Given -

$$J = 4.5 e^{-2r} \hat{a}_z \text{ A/m}^2 \quad 0 < r < 0.5$$

$$I = \iint J \cdot d\mathbf{s}$$

$$= \int_0^{2\pi} \int_0^{0.5} 4.5 e^{-2r} \hat{a}_z \cdot r dr d\phi \hat{a}_z$$

$$= 4.5 \int_0^{2\pi} \int_0^{0.5} r e^{-2r} dr d\phi$$

$$= 4.5 \times 2\pi \int_0^{0.5} r e^{-2r} dr$$

$$= -9\pi \left[ \frac{r e^{-2r}}{2} + \frac{e^{-2r}}{4} \right]_0^{0.5}$$

$$= -9\pi \left[ \frac{0.5 e^{-1}}{2} + \frac{e^{-1}}{4} - \frac{1}{4} \right] = 1.8678 \text{ A}$$

By Ampere circuital law

(17)

$$\oint \mathbf{H} \cdot d\mathbf{l} = I$$

$$H \times 2\pi r = \frac{I}{\pi \times 0.5^2} \times \pi r^2$$

$$\overline{H} = \frac{4.5 e^{-2r} \hat{a}_z \times r}{2\pi \times 0.5}$$

$$\overline{H} = 2.8648 r e^{-2r} \hat{a}_z$$

Q. 5(c)

Given —

$$m(t) = A \tanh(\beta t)$$

$$\frac{dm(t)}{dt} = A\beta \operatorname{sech}^2(\beta t)$$

$$\left. \frac{dm(t)}{dt} \right|_{\max} = A\beta$$

To avoid slope overload error

$$\left. \frac{dm(t)}{dt} \right|_{\max} \leq S \cdot f_s$$

$$S \geq \frac{A\beta}{f_s}$$

$$S_{\min} = A\beta T_s$$

Q. 5(d)

Given —

$$f_m = 10 \text{ kHz}$$

$$A_m = 1 \text{ Volt} \quad \text{Peak to Peak}$$

$$A_m = \frac{1}{2} \text{ Volt}$$

To avoid slope overload error —



$$\left. \frac{dm(x)}{dt} \right|_{\max} \leq S \cdot f_s$$

$$A_m \omega_m \leq S \cdot f_s$$

$$\frac{1}{2} \times 2\pi \times 10 \text{ kHz} \leq S \cdot 10 \times 2 \times 10^3 \text{ Hz}$$

$$S \geq \frac{11}{20} = 0.55$$

$$\text{SNR} = \left( \frac{1}{2} \right) \frac{0.5^2}{\frac{0.5^2}{12}} = 6.854$$

$$\text{in dB} = 17.84 \text{ dB}$$

Q.5(e) In file di

In Computer different kind of file allocations are available which is given below -

(i) Contiguous allocation

(ii) Linked "

(iii) Indexed "

Contiguous allocation - In this file is store at different track. To access the data we have to access the individual track. In this we can access only one track data at a time. It is time consuming.

Linked Allocation - In this file is stored in linklist form. It eliminate the disadvantage of contiguous allocation. To access the data we have to access the address of the track.

## Indexed allocation -

(19)

In indexed allocation, data is stored in the indexed pointer in the form of block. Here we ~~can~~ <sup>can</sup> access multiple file data simultaneously.

Q.6(a) ① Different types of ~~binary~~ digital binary modulation scheme are given below -

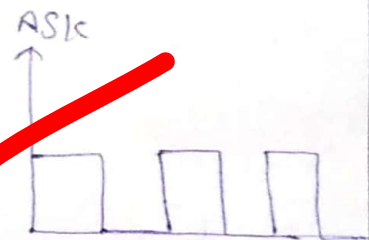
- ASK
- FSK
- PSK

### ASK

• It is just like AM in analog modulation.

$$P_e = \frac{1}{2} \operatorname{erfc} \sqrt{\frac{E_b}{4\eta_0}}$$

$$S(t) = \begin{cases} A_m \cos 2\pi f_c t & s \rightarrow 1 \\ 0 & s \rightarrow 0 \end{cases}$$

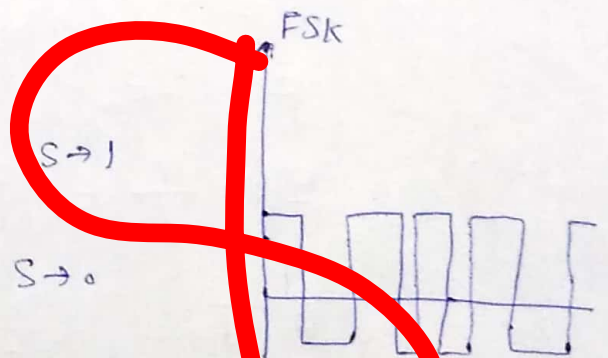


### FSK

• It is just like FM in analog modulation.

$$P_e = \frac{1}{2} \operatorname{erfc} \sqrt{\frac{E_b}{2\eta_0}}$$

$$S(t) = \begin{cases} A_m \cos 2\pi f_{c1} t & s \rightarrow 1 \\ A_m \cos 2\pi f_{c2} t & s \rightarrow 0 \end{cases}$$

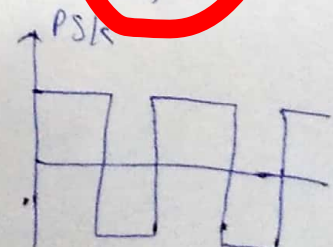


### PSK -

• It is just like PM in analog modulation

$$P_e = \frac{1}{2} \operatorname{erfc} \sqrt{\frac{E_b}{\eta_0}}$$

$$S(t) = \begin{cases} A_m \cos 2\pi f_c t & s \rightarrow 1 \\ -A_m \cos 2\pi f_c t & s \rightarrow 0 \end{cases}$$





# ⑪ Difference b/w PPM & PCM

25

PPM	PCM
<ul style="list-style-type: none"> <li>It is band pass modulation</li> <li>It is similar to PM in analog modulation</li> <li>Quantizer is not used</li> <li>Accuracy is not accurate as PCM</li> <li>Noise does not affect much.</li> </ul>	<ul style="list-style-type: none"> <li>It is base band modulation</li> <li>It encodes the JIP signal into corresponding binary value.</li> <li>Quantizer is used</li> <li>More accurate</li> <li>Quantizer error is main problem.</li> </ul>

Q. 5 (c) ①

Given -

$$A = 5 \text{ cm}^2$$

$$d = 3 \text{ mm}$$

$$V = 50 \sin 10^3 t$$

$$\epsilon = 2\epsilon_0$$

$$E = \frac{V}{d} = \frac{50 \sin 10^3 t}{3 \times 10^{-3}} = \frac{50 \times 10^3}{3} \sin 10^3 t$$

$$\textcircled{B} I_d = \frac{\partial D}{\partial t}$$

$$\frac{I_d}{A} = \epsilon \frac{\partial E}{\partial t}$$

$$I_d = 5 \times 10^{-4} \times 2 \times 8.854 \times 10^{-12} \times \frac{50 \times 10^3 \times 10^3}{3} \cos 10^3 t$$

$$I_d = 1.4757 \times 10^{-7} \cos 10^3 t \text{ A}$$



11) Given =

$$E = \frac{10^6}{r} \hat{a}_r$$

$$a = 50 \text{ mm}$$

$$b = 100 \text{ mm}$$

$$E = 10E_0$$

$$V = - \int E \cdot dr$$

$$= - \int \frac{10^6}{r} \hat{a}_r \cdot d\vec{r} \hat{a}_r$$

$$= - \int_b^a \frac{10^6}{r} dr$$

$$= -10^6 \ln r \Big|_b^a$$

$$V = 10^6 \ln \frac{b}{a} = 10^6 \ln \frac{100}{50} = 0.6931 \times 10^6 \text{ V}$$

$$C = \frac{Q}{V} = \frac{\iiint \rho \cdot ds}{-\int E \cdot dr}$$

$$= \frac{\iiint \epsilon \vec{E} \cdot ds}{V} = \frac{\epsilon \int_0^1 \int_0^{2\pi} \frac{10^6}{r} \hat{a}_r \cdot \vec{r} dr d\phi dz \hat{a}_r}{V}$$

$$= \frac{10 \times 8.854 \times 10^{-12} \times 10^6 \times 2\pi \times 200 \times 10^{-3}}{0.6931 \times 10^6}$$

$$C = 160.53 \text{ pF}$$

$$E = \frac{1}{2} CV^2 = \frac{1}{2} \times 160.53 \times 10^{-12} \times 0.6931^2 \times 10^{12}$$

$$E = 38.5583 \text{ Joule}$$

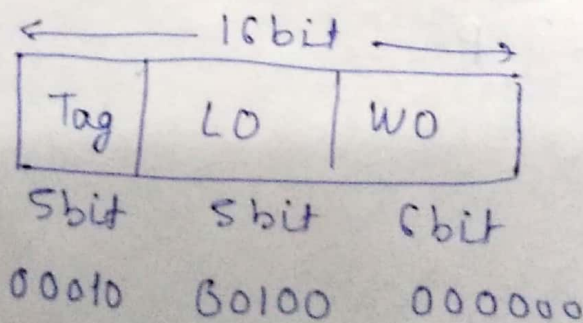
Optical fibre -

- It is used Now a day in communication for transferring the information from one pt. to another pt.
- It works on the principle of total internal reflection.
- It has mainly 3 components -
  - Core
  - Cladding
  - Buffer.

Advantage -

- In this ~~no~~ losses are min<sup>m</sup> as compare to conducting Cu wire.
- It is less costly as compare to conducting Cu wire.
- It has less chances of information leakage as compare to conducting Cu wire.

Q. ⑪



$$LO = (00100)_B = 4$$

Data is start from 4<sup>th</sup> row -

0		B <sub>28</sub>	B <sub>28</sub>
1		B <sub>29</sub>	B <sub>29</sub>
2		B <sub>30</sub>	
3		B <sub>31</sub>	
4	B <sub>0</sub>	B <sub>32</sub>	
5	B <sub>1</sub>	B <sub>33</sub>	
6	B <sub>2</sub>	B <sub>34</sub>	
7	B <sub>3</sub>	B <sub>35</sub>	
8	B <sub>4</sub>	B <sub>36</sub>	
9	B <sub>5</sub>	B <sub>37</sub>	
10	B <sub>6</sub>	B <sub>38</sub>	
11	B <sub>7</sub>	B <sub>39</sub>	
12			
13			
14			
15			
16			
17			
18			
19			
20			
21			
22			
23			
24			
25			
26			
27			
28	B <sub>24</sub>		
29	B <sub>25</sub>		
30	B <sub>26</sub>		
31	B <sub>27</sub>		

1<sup>st</sup>                      2<sup>nd</sup>

B<sub>0</sub>  
B<sub>1</sub>

miss

miss

Total missy  
= 40 + 16 = 56