



MADE EASY
Leading Institute for ESE, GATE & PSUs

ESE 2026 : Mains Test Series

UPSC ENGINEERING SERVICES EXAMINATION

Electronics & Telecommunication Engineering

Test-2 : Digital Circuits + Microprocessors and Microcontroller [All topics]

Network Theory-1 + Signals and Systems-1 [Part Syllabus]

Name :

Roll No :

Test Centres	Student's Signature
Delhi <input checked="" type="checkbox"/> Bhopal <input type="checkbox"/> Pune <input type="checkbox"/> Hyderabad <input type="checkbox"/> Jaipur <input type="checkbox"/>	

- Instructions for Candidates**
- Do furnish the appropriate details in the answer sheet (viz. Name & Roll No).
 - There are Eight questions divided in TWO sections.
 - Candidate has to attempt FIVE questions in all in English only.
 - Question no. 1 and 5 are compulsory and out of the remaining THREE are to be attempted choosing at least ONE question from each section.
 - Use only black/blue pen.
 - The space limit for every part of the question is specified in this Question Cum Answer Booklet. Candidate should write the answer in the space provided.
 - Any page or portion of the page left blank in the Question Cum Answer Booklet must be clearly struck off.
 - There are few rough work sheets at the end of this booklet. Strike off these pages after completion of the examination.

FOR OFFICE USE	
Question No.	Marks Obtained
Section-A	
Q.1	24
Q.2	
Q.3	25
Q.4	35
Section-B	
Q.5	34
Q.6	
Q.7	
Q.8	27
Total Marks Obtained	145

Signature of Evaluator

Cross Checked by

14/26

• Work on your accuracy.

• Practice more to avoid silly mistakes

IMPORTANT INSTRUCTIONS

CANDIDATES SHOULD READ THE UNDERMENTIONED INSTRUCTIONS CAREFULLY. VIOLATION OF ANY OF THE INSTRUCTIONS MAY LEAD TO PENALTY.

DONT'S

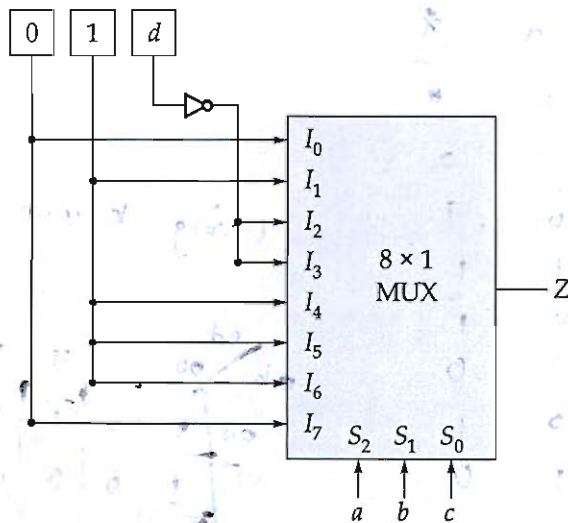
1. Do not write your name or registration number anywhere inside this Question-cum-Answer Booklet (QCAB).
2. Do not write anything other than the actual answers to the questions anywhere inside your QCAB.
3. Do not tear off any leaves from your QCAB, if you find any page missing do not fail to notify the supervisor/invigilator.
4. Do not leave behind your QCAB on your table unattended, it should be handed over to the invigilator after conclusion of the exam.

DO'S

1. Read the Instructions on the cover page and strictly follow them.
2. Write your registration number and other particulars, in the space provided on the cover of QCAB.
3. Write legibly and neatly.
4. For rough notes or calculation, the last two blank pages of this booklet should be used. The rough notes should be crossed through afterwards.
5. If you wish to cancel any work, draw your pen through it or write "Cancelled" across it, otherwise it may be evaluated.
6. Handover your QCAB personally to the invigilator before leaving the examination hall.

Section A : Digital Circuits + Microprocessors & Microcontroller

- (a) Consider the combinational circuit shown below has four inputs (a, b, c, d) and one output Z .



For the above given combinational circuit,

- (i) construct the truth table.
- (ii) write the minimized logic expression for output $Z = f(a, b, c, d)$.

[12 marks]

Draw the output for each possible combination of select lines.

Sol:

(i)

S_2	S_1	S_0	Z
(a)	(b)	(c)	
0	0	0	0
0	0	1	1
0	1	0	\bar{d}
0	1	1	d
1	0	0	1
1	0	1	1
1	1	0	1
1	1	1	0

→ This is truth table of the given 8x1 MUX.

(ii) Using K-map reduction technique

	bc	00	01	11	10
a	0	0	1	\bar{d}	\bar{d}
	1	1	1	0	1

$$Z = \bar{a}\bar{b}c + \bar{a}b\bar{c}d + \bar{a}b\bar{c}\bar{d} + a\bar{b}\bar{c} + a\bar{b}c + abc$$

Converting 3-Variable K-map into 4-Variable K-map

a	b	c	d	\bar{z}
0	0	0	0	0
0	0	0	1	0
0	0	1	0	1
0	0	1	1	1
0	1	0	0	1
0	1	0	1	0
0	1	1	0	1
0	1	1	1	0
1	0	0	0	1
1	0	0	1	1
1	0	1	0	1
1	0	1	1	1
1	1	0	0	1
1	1	0	1	1
1	1	1	0	0
1	1	1	1	0

Using K-map

		cd	00	01	11	10
ab	00		0	0	1	1
	01		1	0	0	1
	11		1	1	0	0
	10		1	1	1	1

$\bar{z} = f(a, b, c, d)$

$\bar{z} = \bar{a}\bar{b}c + \bar{a}b\bar{d} + a\bar{c} + a\bar{b}$

∴ minimized logic expression for output \bar{z} is

$\bar{z} = \bar{a}\bar{b}c + \bar{a}b\bar{d} + a\bar{c} + a\bar{b}$

12

- (b) (i) Convert n -bit base-3 number to n -bit base-9 number.
(ii) Convert $(211101222211122)_3$ to $()_9$ using the result obtained in part (i).

[6 + 6 marks]

- Q.1 (c) Write an assembly language program using 8086 microprocessor to add two 16-bit hexadecimal numbers stored in memory at addresses 0200 H and 0202 H. Store the result in memory.

[12 marks]

1 (d) Using 8085 microprocessor, write an assembly language program to find the 9's complement of a decimal digit stored in memory at address location 2050 H.

[12 marks]

[Handwritten assembly code and diagrams are present in this area, but they are extremely faint and difficult to read. The code appears to include instructions like MOV, MVI, and RAR, and there is a diagram of a 7447 BCD-to-7-segment decoder.]

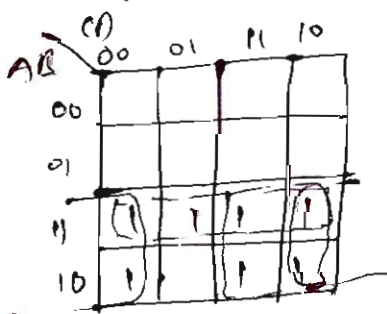
Q.1 (e) Consider the logic function given below:

$$F = ABCD + \overline{A}\overline{B}\overline{C}\overline{D} + \overline{A}\overline{B}C + AB$$

- Simplify the above function using K-map.
- Realize the logic function using only NAND gates.
- Realize the logic function using only NOR gates.

[12 marks]

Ans: (i) Give $F = ABCD + \overline{A}\overline{B}\overline{C}\overline{D} + \overline{A}\overline{B}C + AB$
Drawing the function 'F' onto the k-map for simplification



$$F = A\overline{D} + AB + AC$$

(ii) Using only NAND Gates.

$$F = A\overline{D} + AB + AC$$

$$F = X + C$$

Taking double complement

$$F = \overline{\overline{X+C}} = \overline{\overline{X} \cdot \overline{C}}$$

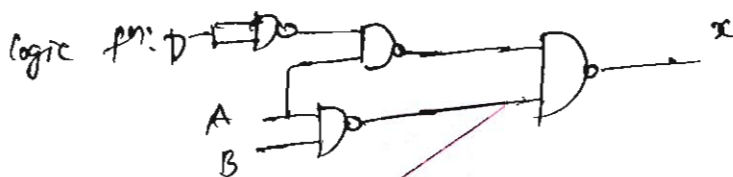
logic function



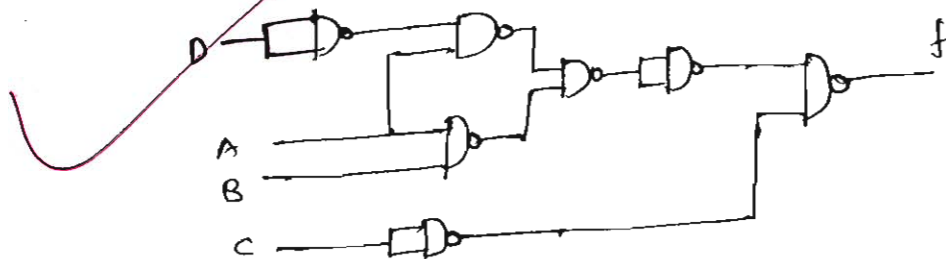
wkt $x = A\bar{D} + AB$

Taking double complement, $x = \overline{\overline{A\bar{D} + AB}}$

$x = \overline{A\bar{D} \cdot AB}$



Final logic fn



(iii) using only NOR Gates
Using maxterms from a K-map

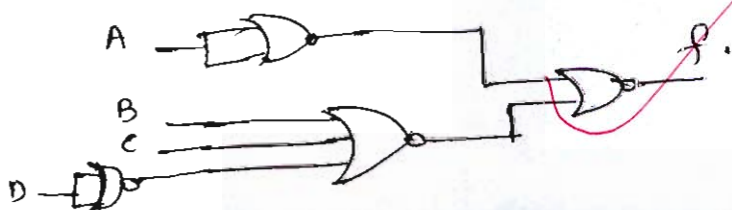
CD \ AB	00	01	11	10
00	0	0	0	0
01	0	0	0	0
11				
10		0		

$f = A(B + C + \bar{D})$

Taking double complement,

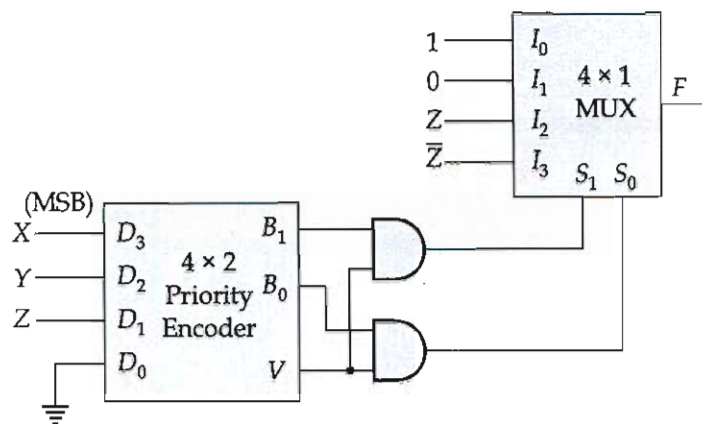
$f = \overline{\overline{A(B + C + \bar{D})}} = \overline{A + (B + C + \bar{D})}$

logic fn using only NOR gates:



12

- Q.2 (b) For the following combinational circuit, construct the truth table and obtain the simplified SOP expression of the output function (F).



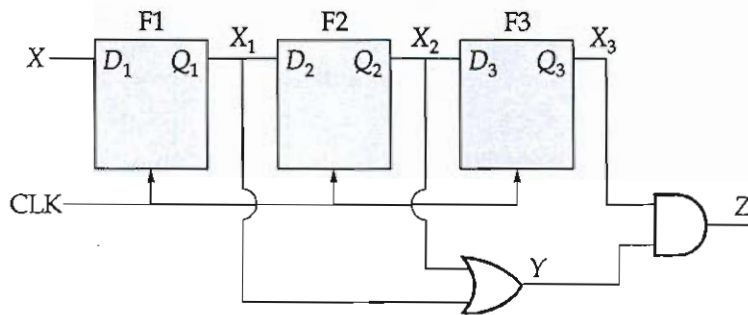
[20 marks]

Q.2 (c) Explain different transfer modes of an 8237 DMA controller in active cycle.

[20 marks]

[Faint, illegible handwritten text, possibly bleed-through from the reverse side of the page]

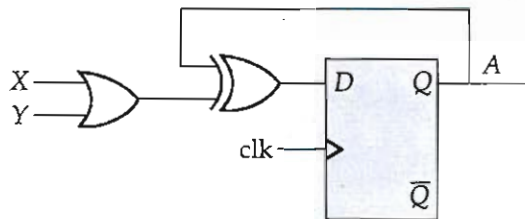
Q.3 (a) (i) A digital design is implemented by the circuit given below:



The design has D-type flip flops, F1, F2 and F3 driven by the clock 'CLK'. It has one input 'X' and one output 'Z'.

1. Find output logic expression for 'Z'.
2. Identify the functionality of the given circuit.

(ii) Analyze the logic circuit shown below and also draw the state diagram for the given circuit.



[10 + 10 marks]

Ans: (1) From the figure,

$$Y = X_1 + X_2, \quad Z = X_3 Y$$

$$\Rightarrow Z = (X_1 + X_2) X_3$$

Since $X_1 = Q_1, X_2 = Q_2, X_3 = Q_3$

$$\Rightarrow \text{Output } Z = (Q_1 + Q_2) Q_3$$

X	Q ₁	Q ₂	Q ₃	Z
0	0	0	0	0
1	1	0	0	0
0	0	1	0	0
1	1	0	1	0

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C/K	X	θ_1	θ_2	θ_3	Z
✓	0	0	0	0	0
	0	0	0	1	0
	0	0	1	0	0
	0	0	1	1	1
	0	0	0	0	0
	0	1	0	1	1
	0	1	1	0	0
	0	1	1	1	1
	1	0	0	0	0
	1	0	0	1	0
	1	0	1	0	1
	1	0	1	1	0
	1	1	0	0	1
	1	1	0	1	0
	1	1	1	0	1
	1	1	1	1	1

no need.



(11) Input $D = A \oplus (X+Y)$

B_n	A	X	Y	D	B_n	D	Out
	A	X	Y		A	$X+Y$	
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	1
0	0	1	0	0	1	0	
0	0	1	1	0	1	1	
0	1	0	0	0	0	0	
0	1	0	1	0	1	0	
0	1	1	0	0	0	1	
0	1	1	1	0	1	1	
1	0	0	0	0	1	0	
1	0	0	1	0	0	1	
1	0	1	0	0	1	0	
1	0	1	1	0	0	1	
1	1	0	0	0	0	0	
1	1	0	1	0	1	1	
1	1	1	0	0	0	0	
1	1	1	1	0	1	1	

(Note: A large red 'X' is drawn over the bottom half of the table.)

- 3 (b) Write an assembly language program using 8051 microcontroller (with clock frequency 12 MHz) for a simple traffic light control system using LEDs connected to port 2 of the microcontroller.

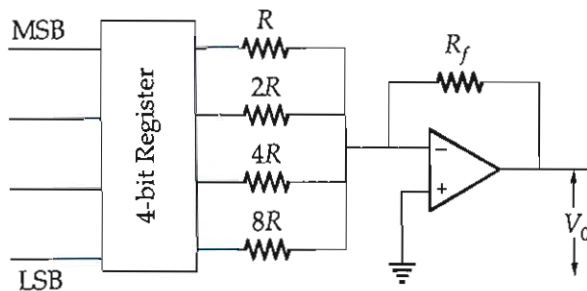
Assume LED connections

- P2.0 → Red LED (ON for 5 sec).
- P2.1 → Yellow LED (ON for 5 sec).
- P2.2 → Green LED (ON for 2 sec).

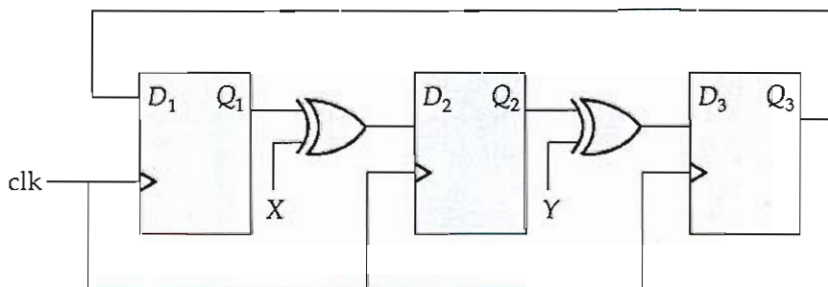
Assume this program cycles through Red-Green-Yellow lights with delays.

[20 marks]

- Q.3 (c) (i) Calculate the output voltage for an input code word 0110 if a logic 1 is 10 V and logic 0 is 0 V. Assume $R = R_f = 1 \text{ k}\Omega$.



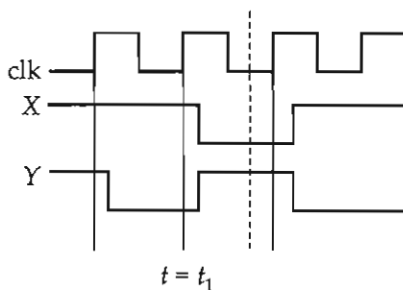
- (ii) Consider the sequential circuit shown below:



1. Fill in the table for the next state values of the three flip-flops for the given current state of the flip-flops and the inputs X and Y. Assume setup and hold times are synchronized with flip-flop inputs.

Q_1	Q_2	Q_3	X	Y	Q_1^+	Q_2^+	Q_3^+
0	0	0	0	1			
1	1	0	1	1			
0	0	1	1	0			

2. For the timing diagram shown below, what is the value of Q_1 , Q_2 and Q_3 at the time indicated by the dashed line in the figure if the value at $t = t_1$ for $Q_1Q_2Q_3 = 001$? (Assume the flip-flops are negative edge triggered)

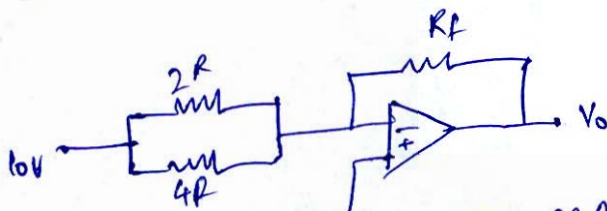


[10 + 10 marks]

Ans: (1) Given 1/4 code word 0110

only 2R and 4R resistors are connected

Equivalent CRT



Inverted op Amp
Circuit op, $\therefore R_f = R$

$$V_o = -\frac{R_f}{R} \left[\frac{1}{2} + \frac{1}{4} \right] \times 10$$

$$V_o = -\left[\frac{3}{4} \right] \times 10 \text{ V} = -7.5 \text{ V}$$

$$\therefore \boxed{V_o = -7.5 \text{ V}}$$

20

(11)

Q_1	Q_2	Q_3	X	Y	Q_1^+	Q_2^+	Q_3^+
0	0	0	0	1	0	0	1
1	1	0	1	1	0	0	0
0	0	1	1	0	1	1	0

At t_2 to t_3 ,

Q_1	Q_2	Q_3	X	Y	Q_1^+	Q_2^+	Q_3^+
0	0	1	1	0			

Since the flip flops are negative edge triggered
X & Y values changed to 01 from 10 after
 t_2 to t_3 to the next negative edge of clock

Q_1	Q_2	Q_3	X	Y	Q_1^+	Q_2^+	Q_3^+
0	0	1	0	1	1	0	1

Q. 1. A particle of mass m is moving in a circular path of radius r with a constant speed v . The change in its velocity vector when it has moved through an angle θ is Δv . Find the magnitude of Δv .

Sol. The initial velocity vector is \vec{v}_1 and the final velocity vector is \vec{v}_2 . The angle between them is θ .

From the vector diagram, we can see that the magnitude of the change in velocity is given by:

$$|\Delta v| = 2v \sin\left(\frac{\theta}{2}\right)$$

Q. 2. A particle of mass m is moving in a circular path of radius r with a constant speed v . The change in its velocity vector when it has moved through an angle θ is Δv . Find the magnitude of Δv .

Sol. The initial velocity vector is \vec{v}_1 and the final velocity vector is \vec{v}_2 . The angle between them is θ .

From the vector diagram, we can see that the magnitude of the change in velocity is given by:

$$|\Delta v| = 2v \sin\left(\frac{\theta}{2}\right)$$

Q. 3. A particle of mass m is moving in a circular path of radius r with a constant speed v . The change in its velocity vector when it has moved through an angle θ is Δv . Find the magnitude of Δv .

Sol. The initial velocity vector is \vec{v}_1 and the final velocity vector is \vec{v}_2 . The angle between them is θ .

From the vector diagram, we can see that the magnitude of the change in velocity is given by:

$$|\Delta v| = 2v \sin\left(\frac{\theta}{2}\right)$$

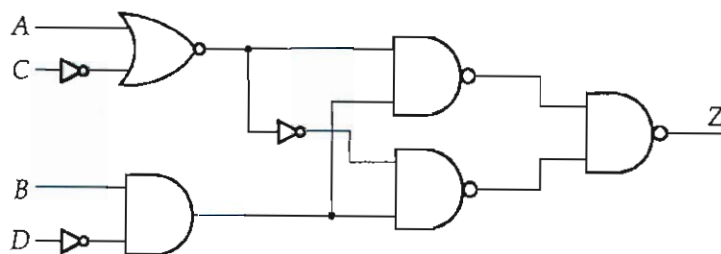
प्रश्न संख्या 124

1	0	0	0	0	0	0	0	0	0
2	0	0	0	0	0	0	0	0	0
3	0	0	0	0	0	0	0	0	0
4	0	0	0	0	0	0	0	0	0
5	0	0	0	0	0	0	0	0	0
6	0	0	0	0	0	0	0	0	0
7	0	0	0	0	0	0	0	0	0
8	0	0	0	0	0	0	0	0	0
9	0	0	0	0	0	0	0	0	0
10	0	0	0	0	0	0	0	0	0
11	0	0	0	0	0	0	0	0	0
12	0	0	0	0	0	0	0	0	0
13	0	0	0	0	0	0	0	0	0
14	0	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0	0
16	0	0	0	0	0	0	0	0	0
17	0	0	0	0	0	0	0	0	0
18	0	0	0	0	0	0	0	0	0
19	0	0	0	0	0	0	0	0	0
20	0	0	0	0	0	0	0	0	0

प्रश्न संख्या 125

प्रश्न संख्या 126

- Q.4 (a) (i) Design an Excess-3 to BCD code converter (Use don't cares for unused codes).
 (ii) The simplified logic expression for output in the circuit shown in below figure is



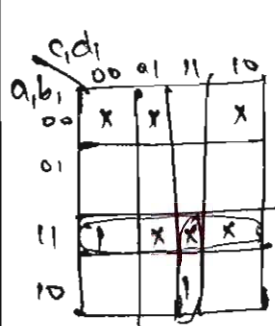
[15 + 5 marks]

Ans:

Excess-3 to BCD Converter

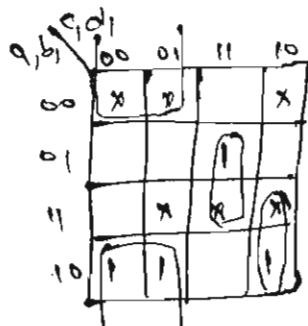
a_1	b_1	c_1	d_1	a_2	b_2	c_2	d_2
0	0	1	1	0	0	0	0
0	1	0	0	0	0	0	1
0	1	0	1	0	0	1	0
0	1	1	0	0	0	1	1
0	1	1	1	0	1	0	0
1	0	0	0	0	1	0	1
1	0	0	1	0	1	1	0
1	0	1	0	0	1	1	1
1	0	1	1	1	0	0	0
1	1	0	0	1	0	0	1
1	1	0	1	x	x	x	x
1	1	1	0	x	x	x	x
1	1	1	1	x	x	x	x
0	0	0	0	x	x	x	x
0	0	0	1	x	x	x	x
0	0	1	0	x	x	x	x

Draw k-map for a_2, b_2, c_2, d_2 for simplification
and final logic



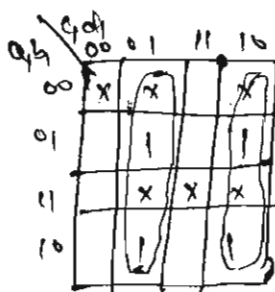
for a_2

$$a_2 = a_1 b_1 + a_1 c_1 d_1$$



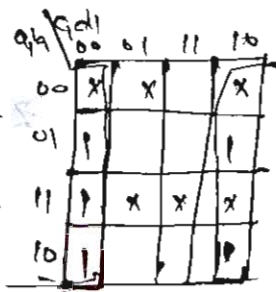
for b_2

$$b_2 = \bar{b}_1 \bar{c}_1 + b_1 c_1 d_1 + a_1 c_1 \bar{d}_1$$



for c_2

$$c_2 = \bar{c}_1 d_1 + c_1 \bar{d}_1$$



for d_2

$$d_2 = \bar{d}_1$$

∴

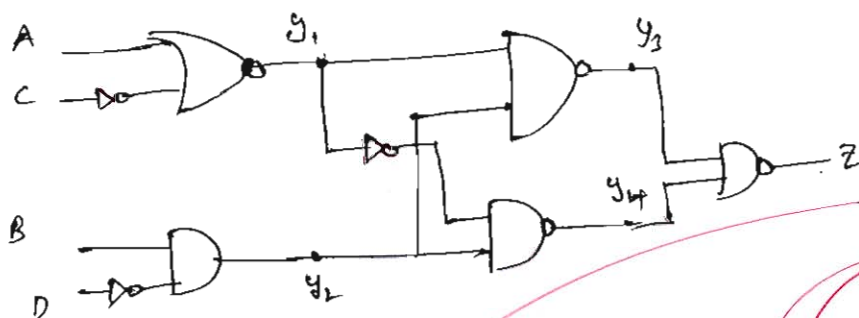
$$a_2 = a_1 b_1 + a_1 c_1 d_1$$

$$b_2 = \bar{b}_1 \bar{c}_1 + b_1 c_1 d_1 + a_1 c_1 \bar{d}_1$$

$$c_2 = \bar{c}_1 d_1 + c_1 \bar{d}_1 = c_1 \oplus d_1$$

$$d_2 = \bar{d}_1$$

(11) Given circuit



$$y_1 = \overline{A + C} = \bar{A} \bar{C}$$

$$y_2 = \boxed{B \bar{D}}$$

$$y_3 = \overline{y_1 y_2}$$

$$y_4 = \overline{y_1 y_2}$$

$$Z = \overline{y_3 y_4} = y_3 + y_4$$

$$\Rightarrow Z = \overline{\overline{y_1 y_2}} + \overline{\overline{y_1 y_2}} = y_1 y_2 + \overline{y_1 y_2}$$

$$\Rightarrow Z = y_2 (y_1 + \bar{y}_1) = y_2 (1) = y_2$$

20

$$\vec{z} = \vec{y}_2 = \vec{BD}$$

The page contains several handwritten diagrams illustrating vector operations. At the top, a vector \vec{z} is equated to \vec{y}_2 and \vec{BD} . Below this, there are three grid-based diagrams showing vector addition and subtraction. The first diagram shows $\vec{z} = \vec{y}_2 = \vec{BD}$ with a double underline. The second diagram shows a vector \vec{z} being the sum of two other vectors. The third diagram shows a vector \vec{z} being the difference of two other vectors. Below these are several more diagrams showing vector addition and subtraction using the triangle rule and parallelogram rule. The bottom part of the page shows a vector diagram with points A, B, C, D and vectors AB, BC, AC, and a resultant vector.

4 (b) Implement the following functions using single (3 × 6 × 4) programmable logic array (PLA) with programmable output polarity feature.

$$F_1(A, B, C) = \sum m(1, 2, 4, 6)$$

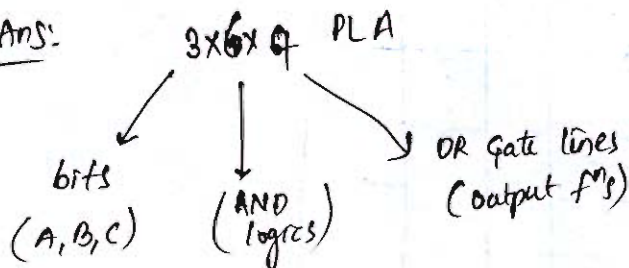
$$F_2(A, B, C) = \sum m(0, 1, 6, 7)$$

$$F_3(A, B, C) = \sum m(2, 6)$$

$$F_4(A, B, C) = \sum m(1, 2, 3, 5, 7)$$

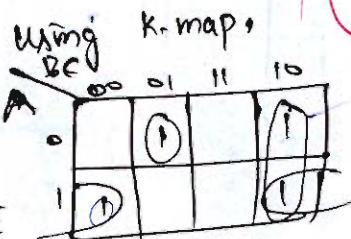
[20 marks]

Ans:



15

$$F_1(A, B, C) = \sum m(1, 2, 4, 6)$$



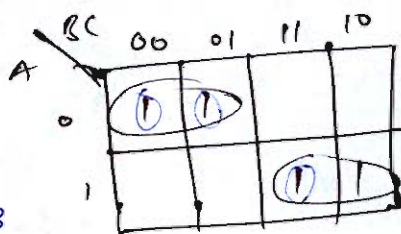
$$F_1(A, B, C) = \overline{A}C + \overline{A}BC + \overline{A}B\overline{C}$$

$$F_1 = A\overline{B}\overline{C} + A\overline{B}C + \overline{A}B\overline{C} + \overline{A}BC$$

$$F_2(A, B, C) = \sum m(0, 1, 6, 7)$$

$$F_2(A, B, C) = \overline{A}B + AB$$

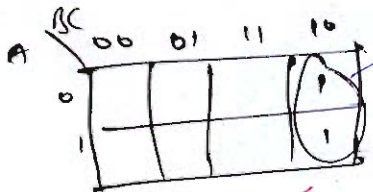
$$= \overline{A}B\overline{C} + \overline{A}B\overline{C} + AB$$



$$F_2 = \overline{A}B\overline{C} + \overline{A}BC + ABC + AB\overline{C}$$

$$F_3(A, B, C) = \sum m(2, 6)$$

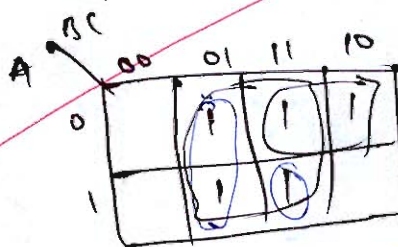
$$F_3(A, B, C) = \overline{A}BC$$



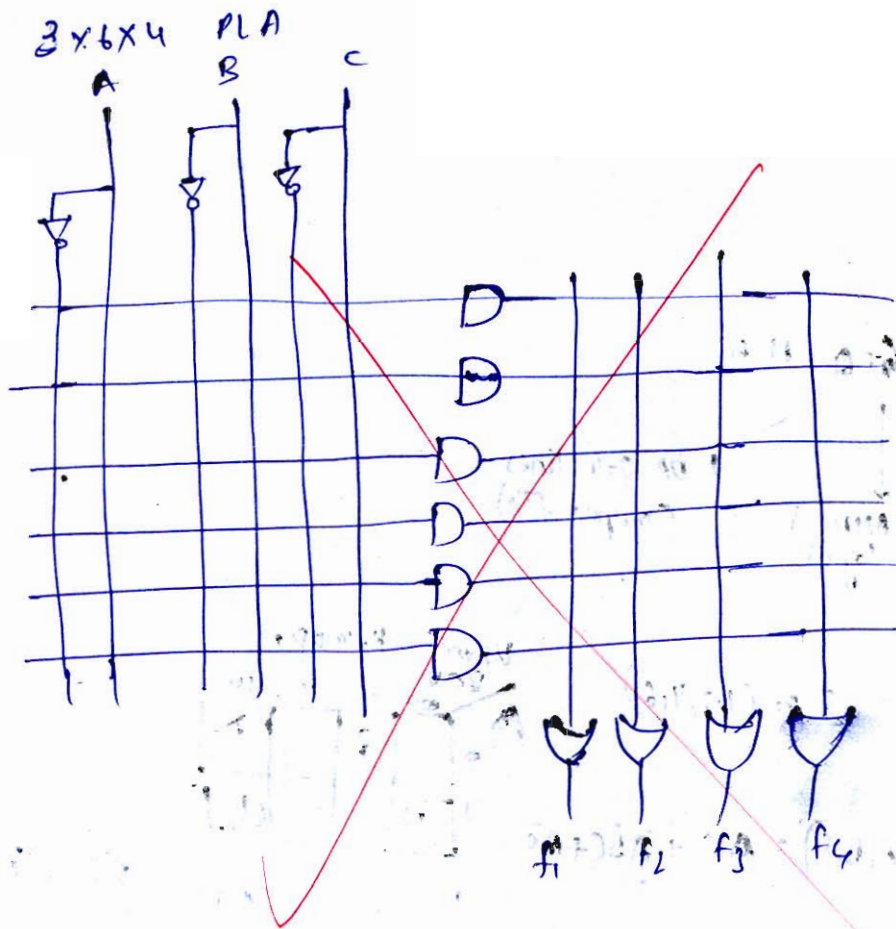
$$F_3 = \overline{A}B\overline{C} + \overline{A}BC$$

$$F_4(A, B, C) = \sum m(1, 2, 3, 5, 7)$$

$$F_4(A, B, C) = C + \overline{A}B$$



$$F_4 = \overline{A}B\overline{C} + \overline{A}BC + A\overline{B}\overline{C} + A\overline{B}C + ABC + AB\overline{C}$$



- 1.4 (c) (i) Describe memory segmentation in 8086 microprocessor with the help of block diagram.
- (ii) What are the different addressing modes of 8051 microcontroller?

[10 + 10 marks]

Section B : Network Theory-1 + Signals and Systems-1

- Q.5 (a) A triangular wave shown in figure (a) is applied as an input to a series RL circuit shown in figure (b). Find the current $i(t)$.

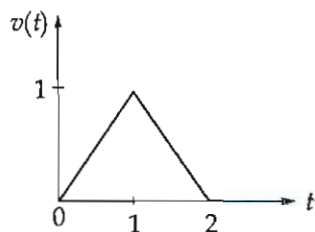


Fig. (a)

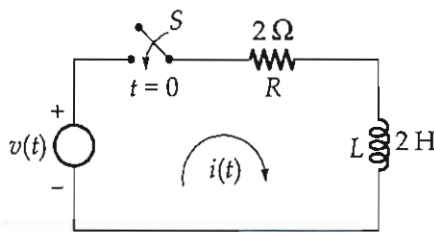


Fig. (b)

[12 marks]

Sol:

Given $v(t)$ in fig (a).Representing $v(t)$ with help of unit functions.

$$v(t) = u(t) - 2u(t-1) + u(t-2)$$

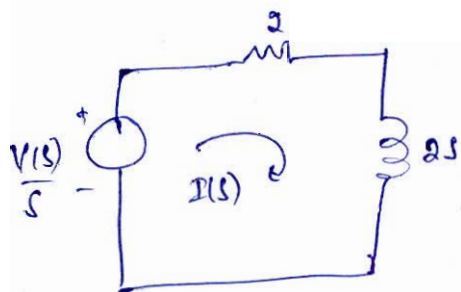
Taking Laplace on both sides and applying time shifting property.

$$V(s) = \left(\frac{1}{s^2} - \frac{2}{s^2} e^{-s} + \frac{1}{s^2} e^{-2s} \right)$$

Since
 $v(t)$ is available
for circuit for
 $t > 0$

$$\Rightarrow V(s) = \frac{1}{s^2} (1 - 2e^{-s} + e^{-2s}) \quad \text{--- (1)}$$

Converting Fig (b) network using Laplace transform



Using KVL in the network,

$$\frac{V(s)}{s} = (2 + 2s) I(s)$$

$$\Rightarrow I(s) = \frac{V(s)}{2(s+1)s} \quad \text{--- (2)}$$



Using ① and ②,

$$I(s) = \frac{1}{s^2} (1 - 2e^{-s} + e^{-2s}) \frac{1}{2s(s+1)}$$

$$I(s) = (1 - 2e^{-s} + e^{-2s}) \left[\frac{1}{2s^3(s+1)} \right]$$

$$I(s) = \frac{1}{2} (1 + e^{-2s} - 2e^{-s}) \left[\frac{A}{s} + \frac{B}{s^2} + \frac{C}{s^3} + \frac{D}{s+1} \right]$$

using residue function and calculating values of

A, B, C, D

12

$$I(s) = \frac{1}{2} [1 + e^{-2s} - e^{-s}] \left[\frac{1}{2} \left(\frac{1}{s} - \frac{1}{s^2} + \frac{1}{s^3} + \frac{1}{s+1} \right) \right]$$

$$I(s) = \frac{1}{4} (1 + e^{-2s} - e^{-s}) \left[\frac{1}{s} - \frac{1}{s^2} + \frac{1}{s^3} + \frac{1}{s+1} \right]$$

Taking Inverse Laplace transform and applying time shifting property

$$i(t) = \frac{1}{4} [u(t) - 2u(t-1) + u(t-2)]$$

$$- \frac{1}{4} [2u(t) - 2u(t-1) + u(t-2)]$$

$$- \frac{1}{8} [p(t) - 2p(t-1) + p(t-2)]$$

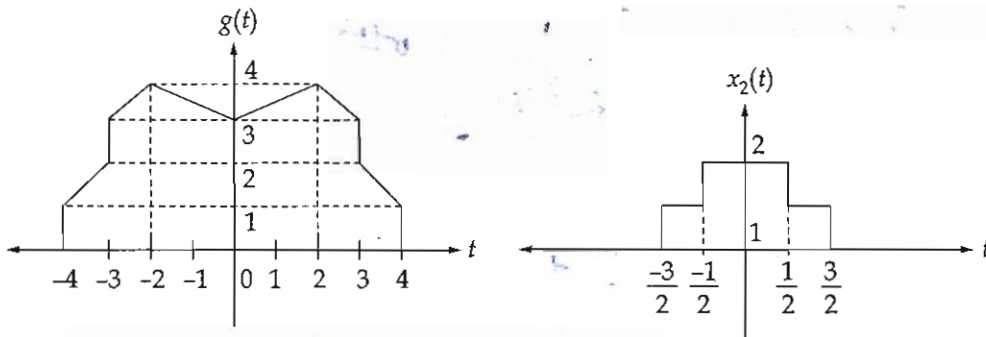
$$+ \frac{1}{4} e^{-t} [u(t) - u(t-1) + u(t-2)]$$

$$\therefore p(t) = \frac{2}{s^3}$$

Q.5 (b) (i) Find whether the following system is static, linear, time-invariant, causal, invertible.

$$y(t) = \int_t^{t+1} x(\tau - \alpha) d\tau \text{ where, '}\alpha\text{' is a constant.}$$

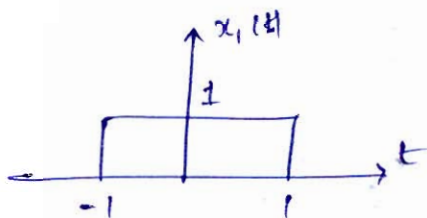
(ii) The response of an LTI system to an input signal $x_1(t) = u(t+1) - u(t-1)$ is denoted as $g(t)$, as illustrated in the figure below. If a new input $x_2(t)$ is applied to the same system, resulting in an output $y(t)$. Determine the value of the output at $t = 0$.



Ans) (A)

[6 + 6 marks]

Given $x_1(t) = u(t+1) - u(t-1)$



$g(t)$ is response of LTI system to input $x_1(t)$

$g(t) = x_1(t) * h(t) \rightarrow$ given.

$y(t) = x_2(t) * h(t) = ?$

$g(t)$ is symmetric about y-axis

positive half for $t > 0$,

$g(t) = 3u(t) + 2x(t) - 3x(t-2) - x(t-3) + x(t-4) - x(t-3) - u(t-3) - u(t-4)$

$g(t) = 3u(t) + 2x(t) - 3x(t-2) - u(t-3) - x(t-3) - u(t-4) + x(t-4)$



$$x_2(t) = u(t + \frac{3}{2}) + u(t + \frac{1}{2}) - u(t - \frac{1}{2}) - u(t - \frac{3}{2})$$

$$x_2(t) = x_1(2t) + x_1(\frac{2t}{3})$$

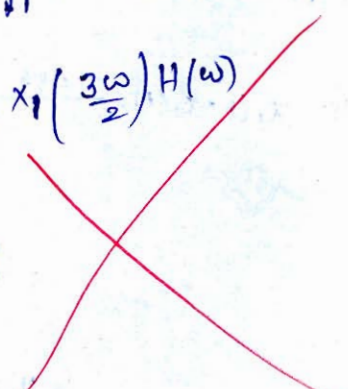
$$\Rightarrow y(t) = x_2(t) * h(t) = \left[x_1(2t) + x_1(\frac{2t}{3}) \right] * h(t)$$

Using distributive property of convolution,

$$\Rightarrow y(t) = x_1(2t) * h(t) + x_1(\frac{2t}{3}) * h(t)$$

$$Y(\omega) = \overset{\text{FT}}{\downarrow} \frac{1}{2} X_1(\frac{\omega}{2}) H(\omega) + \overset{\text{FT}}{\downarrow} \frac{3}{2} X_1(\frac{3\omega}{2}) H(\omega)$$

$$Y(\omega) = X_1(\omega) H(\omega)$$



(1) $y(t) = \int_t^{t+1} x(\tau - \alpha) d\tau$ α is constant.

At $\tau = t$, $y(t)$ needs $x(t - \alpha)$
 part value of input
 \Rightarrow Memory (or) dynamic system

\Rightarrow system is not static

$x_1(t) \xrightarrow{\text{sys}} y_1(t) = \int_t^{t+1} x_1(\tau - \alpha) d\tau$

$x_2(t) \xrightarrow{\text{sys}} y_2(t) = \int_t^{t+1} x_2(\tau - \alpha) d\tau$

$x'(t) = x_1(t) + x_2(t) \xrightarrow{\text{sys}} y'(t) = \int_t^{t+1} x'(\tau - \alpha) d\tau$

$y'(t) = \int_t^{t+1} [x_1(\tau - \alpha) + x_2(\tau - \alpha)] d\tau$

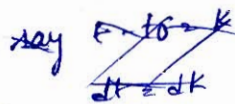
$y'(t) = \int_t^{t+1} x_1(\tau - \alpha) d\tau + \int_t^{t+1} x_2(\tau - \alpha) d\tau$

$y'(t) = y_1(t) + y_2(t)$

\Rightarrow system is linear

Say $x_1(t) \xrightarrow{\text{sys}} y_1(t) = \int_t^{t+1} x_1(\tau - \alpha) d\tau$

Time shifted output $y'(t) = y_1(t - t_0) = \int_{t-t_0}^{t-t_0+1} x_1(\tau - \alpha) d\tau$



$x_2(t) = x(t - t_0) \xrightarrow{\text{sys}} y_2(t) = \int_t^{t+1} x_2(\tau - \alpha) d\tau$

$y_2(t) = \int_t^{t+1} x_2(\tau - t_0 - \alpha) d\tau$

Say $T-t_0 = k \Rightarrow dT = dk$ $t+t_0$

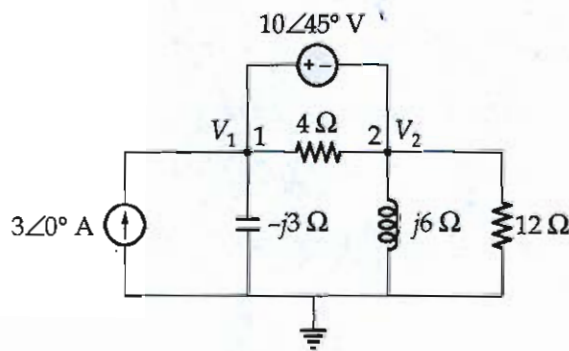
$$\tau = k+t_0 \Rightarrow y_2(t) = \int_{t+t_0}^{t+t_0} x(k-\alpha) dk$$

$\neq y_1(t)$

\Rightarrow system is Time-Variant

3

Q.5 (c) Compute V_1 and V_2 in the below circuit:



[12 marks]

Ans: Using SuperNodal analysis at Node '1' & Node '2' Combined

$$\frac{V_1 - V_2}{4} + \frac{V_1}{-j3} + \frac{V_2}{12} + \frac{V_2}{6j} = 3 \angle 0^\circ$$

$$V_1 \left[\frac{1}{4} - \frac{1}{3j} \right] + V_2 \left[\frac{1}{12} - \frac{1}{4} + \frac{1}{6j} \right] = 3 \angle 0^\circ \quad \text{--- (1)}$$

and $V_1 - V_2 = 10 \angle 45^\circ \Rightarrow V_1 - V_2 = 10 \left(\frac{1+j}{\sqrt{2}} \right) = 5\sqrt{2} + j5\sqrt{2} \quad \text{--- (2)}$

Substitute $V_1 = V_2 + 5\sqrt{2}(1+j)$ in Eqn (1)

$$V_2 + 5\sqrt{2}(1+j) \frac{(3j-4)}{12j} + V_2 \left[\frac{1}{6j} - \frac{1}{6} \right] = 3$$

$$V_2 \left[\frac{5-j}{6} \right] + 5\sqrt{2} \frac{(-7-j)}{12j} = 3 \Rightarrow V_2 \left(\frac{5-j}{6} \right) = 3 + 5\sqrt{2} \frac{(5+j)}{12j}$$

$$2V_2(5-j) = 36 + 5\sqrt{2}(7+j)(-j)$$

$$V_2(10-2j) = 36 + 5\sqrt{2}(1-7j)$$

$$\Rightarrow V_2 = \frac{(36 + 5\sqrt{2}) - 35\sqrt{2}j}{(10-2j)}$$

$$\Rightarrow V_2 = \frac{43.07 - 49.49j}{10-2j}$$

$$V_1 = V_2 + 5\sqrt{2}(1+j) = \frac{43.07 - 49.49j}{10-2j} + 5\sqrt{2}(1+j)$$

$$\Rightarrow V_1 = \frac{(43.07 - 49.49j) + 14.14(1+j)(5-j)}{(10-2j)} = \frac{(43.07 - 49.49j) + 84.85 + 56.56j}{10-2j}$$

$$\Rightarrow V_1 = \frac{127.92 + 7.07j}{10-2j}$$

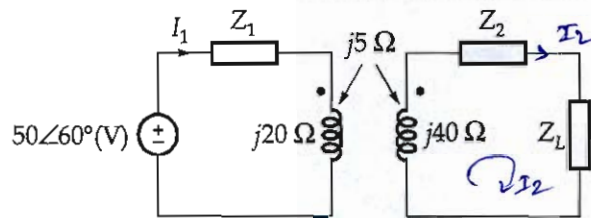
- Q.5 (d)
- What are eigen functions?
 - Express $\sin t + \cos 2t$ in terms of exponential eigen functions.
 - Using the eigen functions obtained above, calculate the response of the system having difference equation $\frac{d^2y}{dt^2} + 6\frac{dy}{dt} + y(t) = 5\frac{dx}{dt} + x(t)$ for the input $\sin t + \cos 2t$?

[12 marks]

$\frac{1}{x^2} = x^{-2}$
 $\frac{d}{dx} x^{-2} = -2x^{-3}$
 $= -2x^{-3}$
 $= -\frac{2}{x^3}$

The given function is $y = \frac{1}{x^2}$
 $y = x^{-2}$
 $\frac{d}{dx} x^{-2} = -2x^{-3}$
 $= -\frac{2}{x^3}$

- Q.5 (e) For a linear transformer shown in figure below, with $Z_1 = (60 - j100) \Omega$, $Z_2 = (30 + j40) \Omega$ and $Z_L = (80 - j60) \Omega$; find the input impedance and the current I_1 .



[12 marks]

Ans: Consider I_2 in the above direction.

KVL in loop ①, Considering mutual inductance component,

$$50\angle 60^\circ - Z_1 I_1 - 20j I_1 - j5 I_2 = 0$$

$$50 \left(\frac{1 + j\sqrt{3}}{2} \right) - [(60 - 100j) + 20j] I_1 - j5 I_2 = 0$$

$$\Rightarrow (80j + 60) I_1 + j5 I_2 = 25(1 + \sqrt{3}j)$$

$$\Rightarrow (12 + 16j) I_1 + j I_2 = 5(1 + \sqrt{3}j) \quad \text{--- (1)}$$

KVL in loop ②

$$j5 I_1 = I_2 [j40 + Z_2 + Z_L]$$

$$\Rightarrow j5 I_1 = I_2 [j40 + 30 + j40 + 80 - 60j] \Rightarrow j5 I_1 = I_2 [110 + 20j]$$

$$\Rightarrow I_1 = -j(22 + 4j) I_2 \quad \text{--- (2)}$$

Substitute (2) in (1),

$$I_1 = (4 - 22j) I_2$$

$$\Rightarrow (12 - 16j)(4 - 22j) I_2 + j I_2 = 5(1 + \sqrt{3}j)$$

$$\Rightarrow (-304 - 328j + j) I_2 = 5(1 + \sqrt{3}j)$$

$$\therefore I_2 = \frac{5(1 + \sqrt{3}j)}{-304 - 327j} \text{ Amp}$$

$$I_1 = \frac{(4 - 22j) 5(1 + \sqrt{3}j)}{-(304 + 327j)} = \frac{5(42.1 - 15.07j)}{-(304 + 327j)}$$

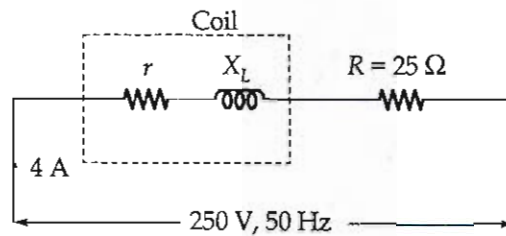
$$\therefore I_1 = \frac{5(42.1 - 15.07j)}{-(304 + 327j)} \text{ Amp}$$

12

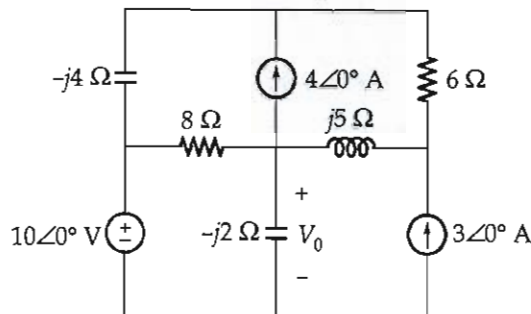
- Q.6 (a) (i) Consider the discrete time signals $x[n] = a^n u[n]$, $0 < a < 1$ and $h[n] = u[n]$. Explain the graphical method for computing the discrete-time convolution. Illustrate the steps to obtain the analytical expression for $y[n]$ graphically. Sketch the output signal $y[n]$.
- (ii) Let $y[n]$ denote the convolution of $h[n]$ and $g[n]$, where $h[n] = \left(\frac{1}{2}\right)^n u[n]$ and $g[n]$ is a causal sequence. If $y[0] = 1$ and $y[1] = \frac{1}{2}$, determine the value of $g[1]$.

[12 + 8 marks]

- Q.6 (b) (i) A resistance of 25Ω is connected in series with a choke coil. The series combination when connected across a 250 V , 50 Hz supply, draw a current of 4 A which lags behind the voltage by 65° . Calculate: total power ($VA = W \pm jVAR$), Power consumed by resistance ($R = 25 \Omega$), Power consumed by choke coil, and resistance and inductance of the coil.



- (ii) Solve for V_0 in the below circuit using mesh analysis.



[10 + 10 marks]

- Q.6 (c) (i) If $i_s = 2 \cos 10t$ (A), find the total energy stored in the passive network shown in figure (a) at $t = 0$ for coefficient of coupling, $k = 0.6$ and terminals x and y left open-circuited.

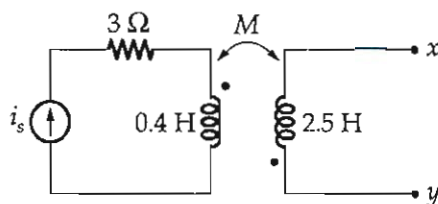


Fig. (a)

- (ii) Determine the amount of energy stored after 0.5s, when the primary side of the circuit shown in figure (b) is connected to a dc source of 15 V and the secondary is short-circuited. Given: $L_1 = 2$ H, $L_2 = 3$ H and $M = 1$ H.

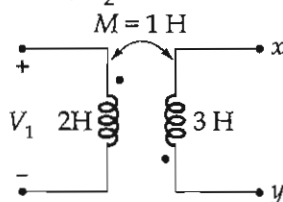


Fig. (b)

[5 + 15 marks]

- (a) (i) Find the Inverse Fourier Transform $x(t)$ for the given frequency domain expression:

$$X(j\omega) = e^{-j5\omega/2} \left[\frac{\sin\left(\frac{\omega}{2}\right) + 2\sin\left(\frac{3\omega}{2}\right)}{\omega} \right]$$

- (ii) Evaluate the following integral involving the doublet function:

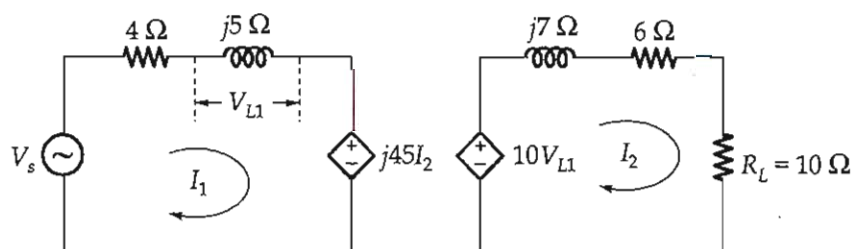
$$I = \int_{-\infty}^2 \cos \frac{\pi}{2} t [\delta'(2t-1) + \delta(t-4)] dt$$

[12 + 8 marks]

- Q.7 (b) (i) A continuous-time signal $x(t) = e^{2t}u(-t)$ is applied to the input of a continuous-time Linear Time-Invariant system. The system is characterized by its unit impulse response $h(t) = u(t - 3)$. Determine the mathematical expression for the output $y(t)$ of the system using convolution integral. Sketch the resulting output signal $y(t)$ labelling all critical time instances and the steady state value.
- (ii) The unit sample response of a LTI system is $h(n) = 3\left(\frac{1}{2}\right)^n u(n) - 2\left(\frac{1}{3}\right)^{n-1} u(n)$ and the output of the system is $y(n)$ when unit step $u(n)$ is applied at the input. Determine the steady state value of the output as $n \rightarrow \infty$.

[10 + 10 marks]

Q.7 (c) In the circuit shown below, if the source voltage $V_s = 110 \angle 53.13^\circ \text{V}$.



With the help of Norton and Maximum power transfer theorem, determine whether the maximum power is transferred to load for $R_L = 10 \Omega$, and also calculate the power delivered to load for $R_L = 10 \Omega$.

[20 marks]

The first part of the question is about the
 $\frac{1}{x^2} = x^{-2}$

Differentiating with respect to x

$$\frac{d}{dx} x^{-2} = -2x^{-3}$$

$$= -\frac{2}{x^3}$$

The second part of the question is about the
 $\frac{1}{x^3} = x^{-3}$

Differentiating with respect to x

$$\frac{d}{dx} x^{-3} = -3x^{-4}$$

$$= -\frac{3}{x^4}$$

The third part of the question is about the
 $\frac{1}{x^4} = x^{-4}$

Differentiating with respect to x

$$\frac{d}{dx} x^{-4} = -4x^{-5}$$

$$= -\frac{4}{x^5}$$

The fourth part of the question is about the
 $\frac{1}{x^5} = x^{-5}$

Differentiating with respect to x

$$\frac{d}{dx} x^{-5} = -5x^{-6}$$

$$= -\frac{5}{x^6}$$

- Q.8 (a) (i) When connected to a 120 V (rms), 60 Hz power line, a load absorbs 4 kW at a lagging power factor of 0.8. Find the value of capacitance required to be added in parallel to raise the pf to 0.95 while the load absorbs the same power.
- (ii) A series-connected circuit has $R = 4 \Omega$ and $L = 25 \text{ mH}$.
1. Calculate the value of C that will produce a quality factor of 50.
 2. Find half power frequencies ω_1, ω_2 and BW.
 3. Determine the average power dissipated at $\omega = \omega_0, \omega_1, \omega_2$.
- (Take $V_m = 100 \text{ V}$.)

[10 + 10 marks]

Sol: (ii) Series RLC CRT
 $R = 4 \Omega$ $L = 25 \text{ mH}$

1. To produce quality factor of 50. C required is

$$\text{WKT } Q = \frac{\omega L}{R} = \frac{1}{\omega CR}$$

For a series RLC ckt, at resonance,

$$\omega = \frac{1}{\sqrt{LC}}$$

$$Q = \frac{\omega L}{R} = \frac{1}{R} \sqrt{\frac{L}{C}} \Rightarrow 50 = \frac{1}{4} \sqrt{\frac{25 \times 10^{-3}}{C}}$$

$$\Rightarrow C = \frac{(200)^{-2} \times 25 \times 10^{-3}}{40} \Rightarrow C = \frac{25}{40} \times 10^{-6} \text{ F}$$

$$\Rightarrow C = 0.625 \mu\text{F}$$

2. Half power frequencies ω_1, ω_2 and BW

$$\text{Band width} = \text{BW} = \frac{R}{L} = \frac{4}{25 \times 10^{-3}} = 160 \text{ Hz}$$

$$\omega_1 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{25 \times 10^{-3} \times 0.625 \times 10^{-6}}} = 252.9 \text{ kHz}$$

- (b) (i) An LTI system S is defined by its impulse response:

$$h(t) = \frac{\sin(4(t-1))}{\pi(t-1)}$$

The system is excited by an input signal $x(t) = \cos\left(6t + \frac{\pi}{2}\right)$. Using frequency-domain analysis, determine the mathematical expression for the output $y(t)$.

- (ii) The impulse response of a causal discrete time LTI system is given by $h[n] = a^n u[n]$, where $a > 0$ and $u[n]$ is the unit step function. Derive the expression for the unit step response $s[n]$ of the system. It is given that the step response at $n = 2$ is $s[2] = 7$. Determine the value of the parameter a .

[10 + 10 marks]

Ans:

(ii) $h(n) = a^n u(n), a > 0$

Impulse response ↗

unit step response, $s[n] = ?$

Given $s[2] = 7$.

Derive?

unit step response is Integration of unit impulse response

$$s[n] = \sum_{m=0}^n h(m)$$

$$\Rightarrow s[n] = \sum_{m=0}^n a^m$$

Given, $n = 2$

$$s[2] = 7$$

$$\Rightarrow 7 = a^0 + a^1 + a^2 \Rightarrow a^2 + a - 6 = 0$$

$$\Rightarrow (a-2)(a+3) = 0 \Rightarrow a = 2, -3$$

Since $a > 0$ is given, $a = 2$.

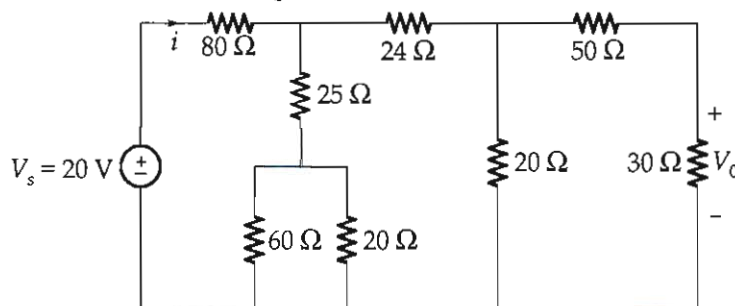
\therefore The value of parameter $a = 2$

(S)

[Faint, illegible handwritten text, likely bleed-through from the reverse side of the page]

(a) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (b) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (c) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (d) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (e) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (f) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (g) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (h) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (i) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (j) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (k) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (l) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (m) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (n) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (o) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (p) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (q) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (r) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (s) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (t) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (u) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (v) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (w) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (x) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (y) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$
 (z) $\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \frac{1}{8}$

Q.8 (c) (i) For the circuit shown in figure below:



Calculate:

1. Input current, i
2. Output voltage, V_0
3. Power Efficiency of the system if V_s and i is considered as input and P_0 is considered as output power.

(ii) Let $u(t)$ be the unit step function and $r(t) = tu(t)$ be the unit ramp function. Derive the expression for the convolution $z(t) = u(t+1) * r(t-2)$. Simplify the result and sketch the waveform of $z(t)$.

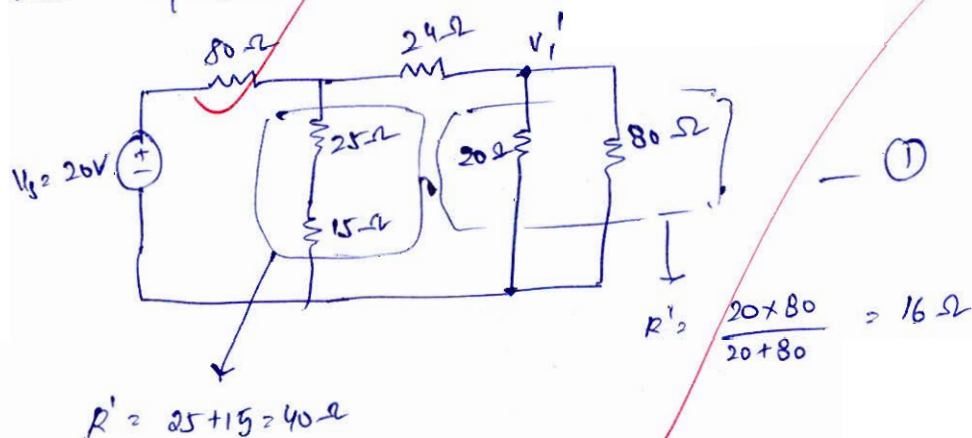
[12 + 8 marks]

Ans: (i) To calculate input current ' i ',
we need to calculate Equivalent Resistance

$$\text{Solving: (i) } 60\Omega \parallel 20\Omega = \frac{60 \times 20}{60 + 20} = 15\Omega$$

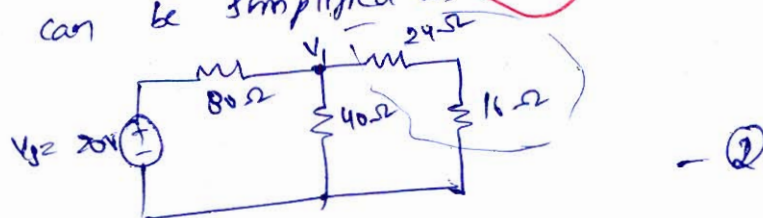
$$(ii) 50\Omega + 30\Omega = 80\Omega$$

Draw Equivalent CKT



$$R' = 25 + 15 = 40\Omega$$

CKT can be simplified as



$$\text{Equivalent Resistance} = R_{eq} = 80\Omega + 40\Omega \parallel 40\Omega$$

$$\Rightarrow R_{eq} = 100\Omega$$

$$\therefore i = \frac{V_s}{R_{eq}} = \frac{20}{100} = \underline{\underline{0.2 \text{ Amp}}}$$

$$\therefore \text{Input Current, } i = 0.2 \text{ Amp}$$

(2) Output Voltage V_o

From Equivalent circuit (2),
Using Voltage divider rule,

$$\text{Voltage } V_1 = \frac{20}{100} \times V_s = \underline{4V}$$

this V_1 gets distributed in circuit (1)

Using Voltage divider rule,

$$\text{Voltage } V_1' = \frac{16}{40} \times 4 = \underline{1.6V}$$

Hence this voltage V_1' divides between 50Ω & 30Ω resistors.

Using voltage divider rule,

$$V_o = \frac{30}{80} \times 1.6 = 0.6V$$

$$\therefore \text{Output Voltage, } V_o = 0.6V$$

(3) Input power $(P_i) = V_s \times i$
 $= 20 \times 0.2 = 4 \text{ W.}$

Output power $= P_o = V_o \times i' = \frac{V_o^2}{30}$

$\therefore P_o = \frac{(0.6)^2}{30} = \frac{0.36}{30} = 0.012 \text{ W.}$

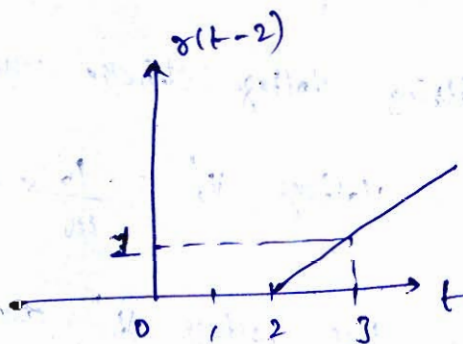
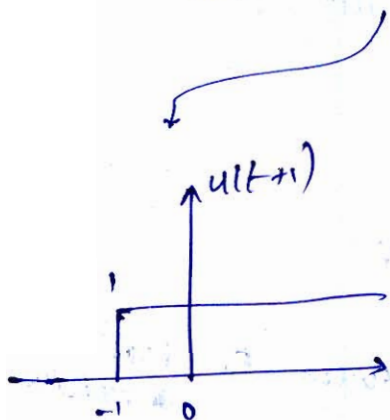
Efficiency of System $= \eta = \frac{P_o}{P_i} \times 100$

$\eta = \frac{0.012}{4} \times 100 = 0.3\%$


12

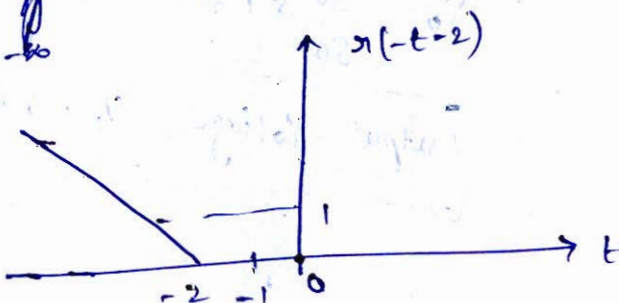
(11) $x(t) = t u(t) \Rightarrow$ unit ramp fn

$z(t) = u(t+1) * x(t-2)$



Using convolution property formula,

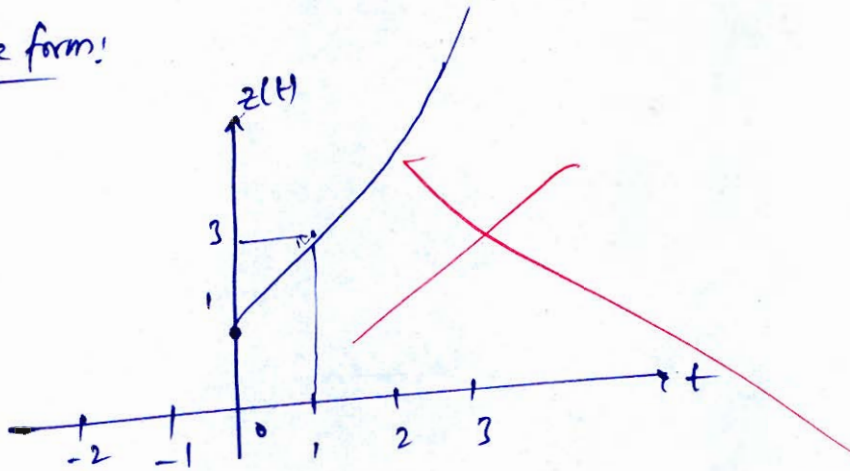
~~$z(t)$~~ =  fold and shift $x(t-2)$



Shifting the $x(-t-2)$ right side and multiplying with $u(t+1)$

$$z(t) = \begin{cases} 0 & t < -1 \\ \sum |t| & t \geq -1 \end{cases}$$

Wave form!



$$z(t) = \frac{t(t+1)}{2} u(t)$$

(S)



$$x(t) \iff X(s)$$

$$x\left(\frac{t}{2}\right) \iff \frac{1}{2} X\left(\frac{s}{2}\right)$$

$$x(2t) \iff \frac{1}{2} X\left(\frac{s}{2}\right)$$

$$B \Rightarrow \frac{A(s+1)s^2}{s^3(s+1)}$$

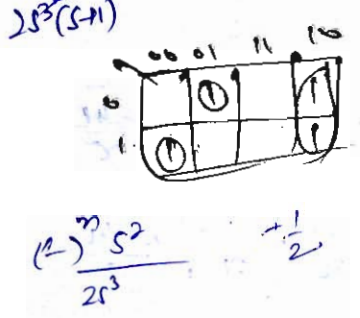
Partial Fraction Decomposition:

$$\frac{1}{s} + \frac{1}{2s^2} + \frac{1}{2s^3} + \frac{1}{s+1}$$

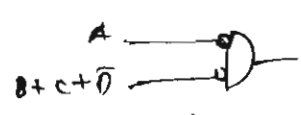
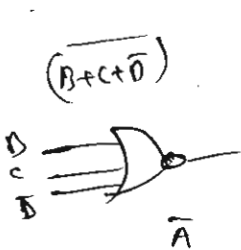
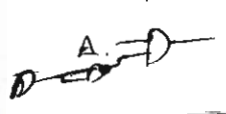
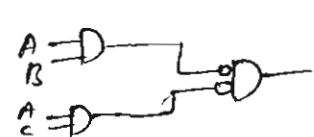
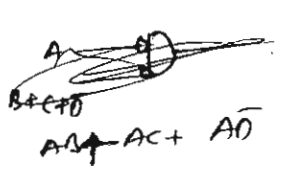
Residue at $s = -1$: $D = 1/2$

Truth Table for Bubbled AND:

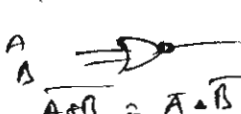
A	B	C	D
0	0	0	0
0	0	0	1
0	0	1	0
0	0	1	1
0	1	0	0
0	1	0	1
0	1	1	0
0	1	1	1
1	0	0	0
1	0	0	1
1	0	1	0
1	0	1	1
1	1	0	0
1	1	0	1
1	1	1	0
1	1	1	1



$A(B+C+D)$



$\overline{A(B+C+D)}$

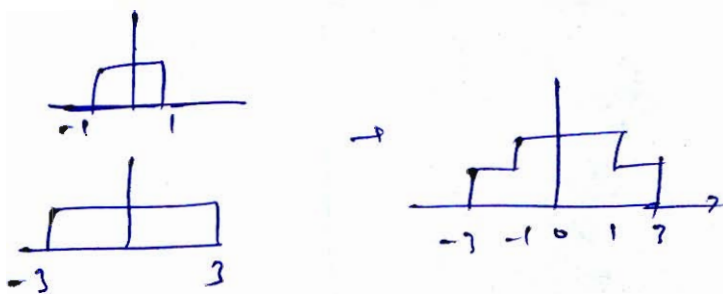


$A+B = \overline{A \cdot B}$

$A(B+C+D)$

$\overline{A + (B+C+D)}$

Space for Rough Work



$x_1(t)$
 $x_2(t/2)$
 $x_1(2t) + x_1(\frac{2t}{3})$

$s^2 + s\frac{R}{L} + \frac{1}{LC} = 0$

$s = \frac{1}{2} \left(-\frac{R}{L} \pm \sqrt{\left(\frac{R}{L}\right)^2 - \frac{4}{LC}} \right)$

$s^2 + 2\zeta\omega_n s + \omega_n^2 = 0$

$\omega_n^2 = \frac{-2\zeta\omega_n \pm \sqrt{4\zeta^2\omega_n^2 - 4\omega_n^2}}{2}$

$\frac{R}{L} = 2\zeta\omega_n$

$R + sL + \frac{1}{sC}$

$s^2 LC + sCR + 1$

$s^2 + s\frac{R}{L} + \frac{1}{LC}$

$\omega_n = \frac{1}{\sqrt{LC}}$

$\sqrt{\frac{L}{RC}}$

$s = -\frac{R}{2L} \pm \frac{1}{2} \sqrt{\frac{R^2 - 4L}{L^2 C}}$

$= -\zeta\omega_n \pm \sqrt{(\zeta^2 - 1)\omega_n^2}$

$s = -\frac{R}{2L} \pm \frac{1}{2L} \sqrt{\frac{R^2 - 4L}{C}}$

$-2\zeta\omega_n$

$s^2 + s \times \frac{25 \times 10^{-3}}{4} + \frac{1}{LC}$

$\omega_n = \frac{R}{L}$

$2\zeta\omega_n = \frac{R}{L}$

6.4×10^4
 1.90×10^2
 $\sqrt{6.4}$

$\frac{10^6}{15.625}$

$\frac{0.625 \times 25}{15.625 \times 10^{-6}}$

$(2.53) \times 1000$

253 Hz