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CLASS TEST 2019-2020

ELECTRICAL ENGINEERING

Date of Test : 06/09/2019**ANSWER KEY ➤ Signal and Systems**

- | | | | | |
|--------|---------|---------|---------|---------|
| 1. (c) | 7. (c) | 13. (c) | 19. (c) | 25. (d) |
| 2. (d) | 8. (a) | 14. (d) | 20. (c) | 26. (a) |
| 3. (c) | 9. (d) | 15. (d) | 21. (b) | 27. (c) |
| 4. (b) | 10. (b) | 16. (c) | 22. (b) | 28. (a) |
| 5. (a) | 11. (b) | 17. (d) | 23. (a) | 29. (b) |
| 6. (d) | 12. (d) | 18. (a) | 24. (a) | 30. (b) |

DETAILED EXPLANATIONS

1. (c)

From the given figure of $x(t)$ and $y(t)$, we get conclude that,

$$\begin{aligned}x(0) &= y(5) \\ \text{at } t = 5 \text{ sec,} \quad y(5) &= x(-5a + 20) = x(0) \\ \therefore -5a + 20 &= 0 \\ \therefore a &= 4\end{aligned}$$

2. (d)

Given, signal $x(t)$ has energy ' E '

$$\text{for } ax(t) \xrightarrow{E} a^2 E$$

$$\therefore ax(bt + c) \xrightarrow{E} \frac{a^2 E}{b}$$

From the given signal $a = 2, b = 5$ and hence

\therefore The energy of signal $2x(5t - 6)$ is

$$E = \frac{(2)^2 \times 10}{5} = 8 \text{ J}$$

3. (c)

We know that, unit impulse let $x(t)$,

$$\begin{aligned}x(t) &= \delta(t) \\ \text{for } \delta(t) &\xrightarrow{LT} 1 \\ \text{for } \frac{d}{dt}x(t) &\xrightarrow{LT} sX(s) \\ \frac{d}{dt}\delta(t) &\xrightarrow{LT} s \\ \frac{d^2}{dt^2}\delta(t) &\xrightarrow{LT} s^2\end{aligned}$$

4. (b)

$$\text{Given, } x(t) = \frac{\sin(10\pi t)}{\pi t}$$

Taking Fourier transform

$$X(j\omega) = \begin{cases} 1 & ; |\omega| \leq 10\pi \\ 0 & ; |\omega| > 10\pi \end{cases}$$

or

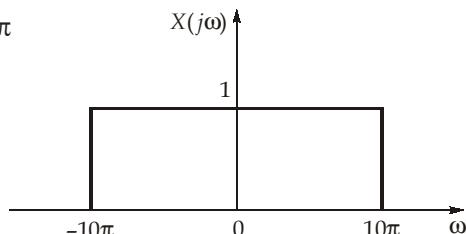
\therefore The maximum frequency ' ω_m ' present in $x(t)$ is $\omega_m = 10\pi$

Hence we require,

$$\frac{2\pi}{T_s} > 2\omega_m$$

$$\frac{2\pi}{T_s} > 20\pi$$

$$\therefore T_s < \frac{1}{10}$$



6. (d)

Given, $x(t) = \delta(t) * 2\delta(t - 1) * 3\delta(t - 2)$

From the convolution property of impulse,

$$x(t) * \delta(t - t_0) = x(t - t_0)$$

$$\therefore x(t) = \delta(t) * 6\delta(t - 3)$$

$$x(t) = 6\delta(t - 3)$$

7. (c)

Given, $H(z) = \frac{z}{z - 0.2} = \frac{1}{1 - 0.2z^{-1}}$ ROC: $|z| > 0.2$

Since the ROC: $|z| > 0.2$, which includes unit circle.

\therefore The impulse response will be stable.

9. (d)

$$\int_{-\infty}^{\infty} \delta(at) dt = \frac{1}{a}$$

Since $\delta(at) = \frac{1}{|a|} \delta(t)$

10. (b)

For sequence $X_1[n] \xrightarrow{Z} X_1[z]$; ROC = R

For sequence $X_2[n] = X_1[-n] \xrightarrow{Z} X_1[1/z]$; ROC = $1/R$

\therefore ROC's are reciprocal of each other.

11. (b)

By the differentiation property of Fourier transform,

$$\frac{dx(t)}{dt} \xleftrightarrow{\text{F.T.}} j\omega X(\omega)$$

$$\frac{d^2x(t)}{dt^2} \xleftrightarrow{\text{F.T.}} -\omega^2 X(\omega)$$

By the time shifting property,

$$-\frac{d^2x(t+2)}{dt^2} \xleftrightarrow{\text{F.T.}} \omega^2 e^{j2\omega} X(\omega)$$

12. (d)

Let us consider two signals,

$$x_1(t) = 1, \quad \forall t$$

$$x_2(t) = -1, \quad \forall t$$

Clearly $x_1(t) \neq x_2(t)$ but $(x_1(t))^2 = (x_2(t))^2$

Therefore different inputs gives the same output hence the system is non invertible.
And also it is non linear system.

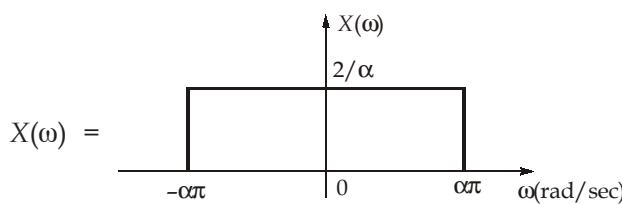
13. (c)

We know that,

Energy,

$$E = \int_{-\infty}^{\infty} x^2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega$$

Now,



$$E = \frac{1}{2\pi} \int_{-\alpha\pi}^{\alpha\pi} \left| \frac{2}{\alpha} \right|^2 d\omega$$

$$0.5 = \frac{1}{2\pi} \times \frac{4}{\alpha^2} [2\alpha\pi]$$

$$0.5 = \frac{4}{\alpha}$$

$$\therefore \alpha = 8$$

14. (d)

Given,

$$x[n] = \cos \frac{\pi}{4} n + \sin \left(\frac{\pi}{3} n + \frac{1}{2} \right)$$

Let

$$x[n] = x_1[n] + x_2[n]$$

Let N_1 be the period of $x_1[n]$.

$$\frac{\pi/4}{2\pi} = \frac{m}{N_1}$$

$$\Rightarrow N_1 = 8$$

Let N_2 be the period of $x_2[n]$.

$$\frac{\pi/3}{2\pi} = \frac{m}{N_2}$$

$$\Rightarrow N_2 = 6$$

Overall time period, $N = \text{LCM}(N_1, N_2) = \text{LCM}(6, 8)$

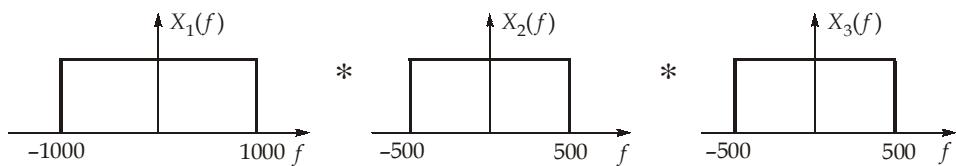
$$\therefore N = 24$$

15. (d)

We know that,

For

$$X(f) = X_1(f) * X_2(f) * X_3(f)$$



Sampling frequency, $f_s = 2(1000 + 500 + 500)$

$$f_s = 4000 \text{ samples/sec}$$

16. (c)

Consider a right sided signal $x(t)$

So, that $x(t) = 0$ for $t < t_0$ and $X(s)$ converges for $\text{Re}\{s\} = \sigma_0$, then

$$|X(s)| \leq \int_{-\infty}^{\infty} |x(t)e^{-st}| dt = \int_{-\infty}^{\infty} |x(t)| e^{-\sigma_0 t} dt = \int_{t_1}^{\infty} |x(t)| e^{-\sigma_0 t} dt < \infty$$

Let $\text{Re}\{s\} = \sigma_1 > \sigma_0$. Then

$$\begin{aligned} \int_{t_1}^{\infty} |x(t)| e^{-\sigma_1 t} dt &= \int_{t_1}^{\infty} |x(t)| e^{-\sigma_0 t} e^{-(\sigma_1 - \sigma_0)t} dt \\ &< e^{-(\sigma_1 - \sigma_0)t_1} \int_{t_1}^{\infty} |x(t)| e^{-\sigma_0 t} dt < \infty \end{aligned}$$

Thus, $X(s)$ converges for $\text{Re}\{s\} = \sigma_1$ and the ROC of $X(s)$ is of the form $\text{Re}\{s\} > \sigma_0$. Since the ROC of $X(s)$ cannot include any poles of $X(s)$, we conclude that it is of the form $\text{Re}\{s\} > \sigma_{\max}$.

17. (d)

Given signal, Let $x(t) = \frac{1}{\pi(1+t^2)}$

We know that,

$$e^{-a|t|} \xleftrightarrow{\text{FT}} \frac{2a}{a^2 + \omega^2}$$

Put $a = 1$

$$e^{-|t|} \xleftrightarrow{\text{FT}} \frac{2}{1 + \omega^2}$$

By using duality property,

$$\begin{aligned} \frac{2}{1+t^2} &\xleftrightarrow{\text{FT}} 2\pi e^{-|\omega|} \\ \frac{2}{1+t^2} &\xleftrightarrow{\text{FT}} 2\pi e^{-|\omega|} \\ \frac{1}{\pi(1+t^2)} &\xleftrightarrow{\text{FT}} e^{-|\omega|} \end{aligned}$$

18. (a)

Given, $y(t) = \frac{1}{2}x\left(\frac{t}{2}\right)^* \delta(t-4) = \frac{1}{2}x\left(\frac{t-4}{2}\right) = \frac{1}{2}x\left(\frac{1}{2}t-2\right)$

at $t = 2$; $y(2) = \frac{1}{2}x\left(\frac{1}{2}(2)-2\right) = \frac{1}{2}x(-1)$

Slope of given signal $x(t)$ is 2.

$$x(-1) = -2$$

$$y(2) = \frac{1}{2}(-2) = -1$$

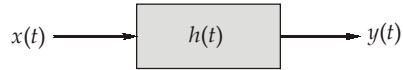
19. (c)

Given, the Causal LTI system,

$$H(j\omega) = \frac{1}{3+j\omega}$$

and output,

$$y(t) = e^{-3t} u(t) - e^{-4t} u(t)$$



We know that,

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)}$$

$$Y(j\omega) = \frac{1}{3+j\omega} - \frac{1}{4+j\omega} = \frac{1}{(3+j\omega)(4+j\omega)}$$

$$\therefore X(j\omega) = \frac{Y(j\omega)}{H(j\omega)} = \frac{1}{4+j\omega}$$

By inverse Fourier transform of $X(j\omega)$, we have,

$$x(t) = e^{-4t} u(t)$$

20. (c)

Given, sinusoidal pulse

$$z(t) = \begin{cases} e^{j10t} ; & |t| < \pi \\ 0 ; & |t| > \pi \end{cases}$$

We may express $z(t)$ as the product of a complex sinusoid e^{j10t} and a rectangular pulse $x(t)$.

$$\text{Let, } x(t) = \begin{cases} 1 ; & |t| < \pi \\ 0 ; & |t| > \pi \end{cases}$$

Fourier transform of $x(t)$ is $X(j\omega)$

$$\begin{aligned} \therefore X(j\omega) &= \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt = \int_{-\pi}^{\pi} 1 \cdot e^{-j\omega t} dt = \left[\frac{e^{-j\omega t}}{-j\omega} \right]_{-\pi}^{\pi} \\ &= -\frac{1}{j\omega} [e^{-j\pi\omega} - e^{+j\pi\omega}] = \frac{e^{j\omega\pi} - e^{-j\omega\pi}}{j\omega} = \frac{2}{\omega} \left[\frac{e^{j\omega\pi} - e^{-j\omega\pi}}{2j} \right] \\ \therefore X(j\omega) &= \frac{2}{\omega} \sin(\omega\pi) \end{aligned}$$

By using frequency shift property of Fourier transform, we get,

$$z(t) = e^{j10t} \cdot x(t) \xrightarrow{\text{FT}} X(j(\omega - 10))$$

$$\therefore z(t) \xrightarrow{\text{FT}} \frac{2}{\omega - 10} \sin((\omega - 10)\pi)$$

21. (b)

$$\text{Given, } X(s) = \log(s + 2) - \log(s + 3)$$

Differentiating both the sides with respect to s

$$\frac{d}{ds} X(s) = \frac{1}{s+2} - \frac{1}{s+3} \quad \dots(i)$$

From the properties of Laplace transform, we know that,

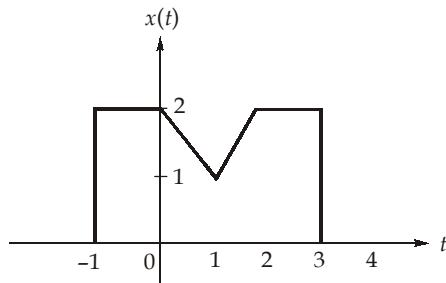
$$tx(t) \longleftrightarrow -\frac{d}{ds} X(s)$$

Thus equation (i) can be written as,

$$\begin{aligned} -tx(t) &= [e^{-2t} - e^{-3t}]u(t) \\ \text{or, } x(t) &= \left[\frac{e^{-3t} - e^{-2t}}{t} \right] u(t) \end{aligned}$$

22. (b)

Given,



By the definition of Fourier transform,

$$\begin{aligned} X(j\omega) &= \int_{-\infty}^{\infty} x(t) \cdot e^{-j\omega t} dt \\ x(t) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) \cdot e^{j\omega t} d\omega \end{aligned}$$

at $t = 0$,

$$\begin{aligned} x(0) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) d\omega \\ \therefore \int_{-\infty}^{\infty} X(j\omega) d\omega &= 2\pi x(0) = 2\pi(2) = 4\pi \approx 12.57 \end{aligned}$$

23. (a)

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n} = \sum_{n=0}^{\infty} \frac{2^{-n}}{n!} z^{-n}$$

$$= \sum_{n=0}^{\infty} \frac{(2z)^{-n}}{n!} = \sum_{n=0}^{\infty} \frac{\left(\frac{1}{2z}\right)^n}{n!}$$

$$X(z) = 1 + \frac{\frac{1}{2z}}{1!} + \frac{\left(\frac{1}{2z}\right)^2}{2!} + \frac{\left(\frac{1}{2z}\right)^3}{3!} + \dots$$

$$X(z) = e^{1/2z}$$

$$X(1) = e^{1/2} = \sqrt{e} = 1.648 \approx 1.65$$

24. (a)

By Parsevals theorem,

$$\text{Energy of a signal } x[n] \text{ is, } E = \frac{1}{2\pi} \int_{-\pi}^{\pi} |X(e^{j\omega})|^2 d\omega$$

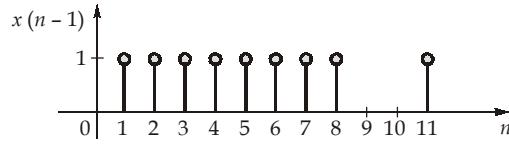
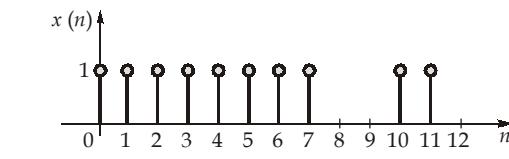
where $X(e^{j\omega})$ is discrete time Fourier transform of $x[n]$,

$$\text{So, } \frac{\sin(2n)}{\pi n} \xleftrightarrow{\text{DTFT}} X(e^{j\omega}) = \begin{cases} 1; & |\omega| \leq 2 \\ 0; & \text{otherwise} \end{cases}$$

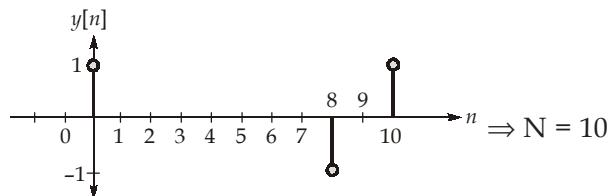
$$\therefore \text{Energy, } E = \frac{1}{2\pi} \int_{-2}^2 1 \cdot d\omega = \frac{1}{2\pi} [4]$$

$$\therefore E = \frac{2}{\pi} = 0.64 \text{ J}$$

25. (d)



Subtracting the two signals, we get



26. (a)

Given,

$$x[n] = [1, 2, 3, 4]$$

$$h[n] = \delta[n-1]$$

$$y[n] = x[n] * h[n] \quad [\text{* denotes convolution}]$$

$$= x[n] * \delta[n-1] = x[n-1]$$

$$\therefore y[0] = x(-1) = 1 \quad (\because n=0)$$

27. (c)

We know that the Laplace transform of

$$\cos(at)u(t) = \frac{s}{s^2 + a^2}$$

$$\therefore \cos(\pi t)u(t) = \frac{s}{s^2 + \pi^2}$$

now, the given function $x(t)$ can be written as,

$$\begin{aligned}
 &= \cos\pi t[u(t) - u(t-1)] \\
 &= \cos(\pi t)u(t) - \cos\pi t u(t-1) \\
 &= \cos\pi t u(t) - \cos\pi(t-1+1)u(t-1) \\
 &= \cos\pi t u(t) - \cos[\pi(t-1) + \pi]u(t-1) \\
 x(t) &= \cos(\pi t)u(t) + \cos[\pi(t-1)]u(t-1)
 \end{aligned}$$

By taking Laplace transform,

$$\begin{aligned}
 X(s) &= \frac{s}{s^2 + \pi^2} + \frac{se^{-s}}{s^2 + \pi^2} \quad [\because x(t-t_0) = X(s) \cdot e^{-st_0}, \text{ by shifting property}] \\
 X(s) &= \frac{s[1+e^{-s}]}{s^2 + \pi^2}
 \end{aligned}$$

28. (a)

We know that,

$$\begin{aligned}
 x[n] &\xleftarrow{\text{DTFT}} X(\omega) \\
 X(\omega) &= \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n} = \sum_{n=-2}^3 x[n]e^{-j\omega n} \\
 X(\omega) &= e^{j2\omega} + 2e^{j\omega} + 3 + 2e^{-j\omega} + e^{-j2\omega} \\
 X(\omega) &= 3 + 4\cos\omega + 2\cos 2\omega \quad \dots(i) \\
 H(k) &= \sum_{n=0}^5 h[n]e^{-j\frac{2\pi}{6}nk} \\
 H(k) &= \sum_{n=0}^5 h[n]e^{-j\frac{\pi}{3}nk} = 3 + 2e^{-j\frac{\pi}{3}k} + e^{-j\frac{\pi}{3}2k} + 0 + e^{-j\frac{\pi}{3}4k} + 2e^{-j\frac{\pi}{3}5k} \\
 &= 3 + 2e^{-j\frac{\pi}{3}k} + 2e^{+j\frac{\pi}{3}k} + e^{-j\frac{2\pi}{3}k} + e^{j\frac{2\pi}{3}k} \\
 &= 3 + 4\cos\frac{\pi k}{3} + 2\cos\frac{2\pi k}{3} \quad \dots(ii)
 \end{aligned}$$

By comparing equation (i) and equation (ii), we get,

$$\omega = \frac{\pi k}{3}$$

29. (b)

Given signals, $x(t) = \sin\omega_0 t$
 $h(t) = \text{sgn}t$

from the multiplication property of Fourier transform,

$$x(t)h(t) = \frac{1}{2\pi} [X(\omega) * H(\omega)]$$

Fourier transform of $x(t)$ is $X(\omega)$,

$$X(\omega) = \frac{\pi}{j} [\delta(\omega - \omega_0) - \delta(\omega + \omega_0)]$$

Fourier transform of $h(t)$ is $H(\omega)$,

$$H(\omega) = \frac{2}{j\omega}$$

$$\begin{aligned}
 \therefore x(t) h(t) &\xleftarrow{\text{FT}} \frac{1}{2\pi} \left[\frac{\pi}{j} (\delta(\omega - \omega_0) - \delta(\omega + \omega_0)) * \frac{2}{j\omega} \right] \\
 &\xleftarrow{\text{FT}} \frac{1}{2\pi} \left[\left[\frac{\pi}{j} \times \frac{2}{j(\omega - \omega_0)} \right] - \left[\frac{\pi}{j} \times \frac{2}{j(\omega + \omega_0)} \right] \right] \\
 &\quad (\because X(\omega) * \delta(\omega - \omega_0) = X(\omega - \omega_0)) \\
 &\xleftarrow{\text{FT}} \left[\frac{-1}{\omega - \omega_0} + \frac{1}{\omega + \omega_0} \right] = \frac{-\omega - \omega_0 + \omega - \omega_0}{\omega^2 - \omega_0^2} \\
 \therefore x(t) h(t) &\xleftarrow{\text{FT}} \frac{-2\omega_0}{\omega^2 - \omega_0^2}
 \end{aligned}$$

30. (b)

Given,

$$\begin{aligned}
 X(z) &= \frac{1}{1 - 2.5z^{-1} + z^{-2}} = \frac{1}{(z^{-1} - 2)\left(z^{-1} - \frac{1}{2}\right)} \\
 \frac{1}{(z^{-1} - 2)\left(z^{-1} - \frac{1}{2}\right)} &= \frac{A}{z^{-1} - 2} + \frac{B}{z^{-1} - \frac{1}{2}} \\
 \therefore A &= \frac{1}{2 - \frac{1}{2}} = \frac{1}{3/2} = \frac{2}{3} \\
 B &= \frac{1}{\frac{1}{2} - 2} = -\frac{2}{3} \\
 \therefore X(z) &= \frac{\frac{2}{3}}{z^{-1} - 2} + \frac{-\frac{2}{3}}{z^{-1} - \frac{1}{2}} \\
 &= \frac{-\frac{1}{3}}{1 - \frac{1}{2}z^{-1}} + \frac{\frac{4}{3}}{1 - 2z^{-1}}
 \end{aligned}$$

Given $X(z)$ is a causal system, the ROC is right of the right most pole.

$$\therefore |z| > 2$$

hence,

$$\begin{aligned}
 x[n] &= -\frac{1}{3} \left(\frac{1}{2} \right)^n u[n] + \frac{4}{3} (2)^n u[n] \\
 \therefore x(0) &= -\frac{1}{3} + \frac{4}{3} = \frac{3}{3} = 1
 \end{aligned}$$

