

CLASS TEST

S.No. : 10 LS1_EE_T_140819

Engineering Mathematics



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CLASS TEST 2019-2020

ELECTRICAL ENGINEERING

Date of Test : 14/08/2019

ANSWER KEY > Engineering Mathematics

- | | | | | |
|--------|---------|---------|---------|---------|
| 1. (b) | 7. (a) | 13. (c) | 19. (b) | 25. (d) |
| 2. (b) | 8. (a) | 14. (a) | 20. (d) | 26. (b) |
| 3. (c) | 9. (a) | 15. (c) | 21. (a) | 27. (a) |
| 4. (c) | 10. (b) | 16. (b) | 22. (a) | 28. (c) |
| 5. (b) | 11. (d) | 17. (c) | 23. (c) | 29. (d) |
| 6. (c) | 12. (d) | 18. (a) | 24. (a) | 30. (b) |

Detailed Explanations

1. (b)

Solution of laplace equation having continuous

Second order partial derivating

$$\therefore \nabla^2 \phi = 0$$

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0$$

 $\therefore \phi$ is harmonic function.

2. (b)

Median speed is the speed at the middle value in series of spot speeds that are arranged in ascending order. 50% of speed values will be greater than the median 50% will be less than the median.

Ascending order of spot speed studies are

32, 39, 45, 51, 53, 56, 60, 62, 66, 79

$$\text{Median speed} = \frac{53 + 56}{2} = 54.5 \text{ km/hr}$$

3. (c)

$$\int_{-\infty}^{\infty} \rho(x) \cdot dx = 1$$

$$\int_{-\infty}^{\infty} K \cdot e^{-\alpha|x|} \cdot dx = 1$$

$$\int_{-\infty}^0 K \cdot e^{\alpha x} \cdot dx + \int_0^{\infty} K \cdot e^{-\alpha x} = 1$$

$$\Rightarrow \frac{K}{\alpha} (e^{\alpha x})_{-\infty}^0 + \frac{K}{-\alpha} (e^{-\alpha x})_0^{\infty} = 1$$

$$\Rightarrow \frac{K}{\alpha} + \frac{K}{\alpha} = 1$$

$$2K = \alpha$$

$$\Rightarrow K = 0.5 \alpha$$

4. (c)

Since, $\cos 2x = \cos^2 x - \sin^2 x$, therefore $\cos 2x$ is a linear combination of $\sin^2 x$ and $\cos^2 x$ and hence these are linearly dependent.

5. (b)

$$\ddot{x} + 3x = 0$$

Auxiliary equation is

$$D^2 + 3 = 0$$

$$\text{i.e. } D = \pm \sqrt{3} i$$

$$\begin{aligned} \therefore & x = A\cos\sqrt{3}t + B\sin\sqrt{3}t \\ \text{at } & t = 0, x = 1 \\ \Rightarrow & A = 1 \\ \text{Now, } & \dot{x} = \sqrt{3}(B\cos\sqrt{3}t - A\sin\sqrt{3}t) \\ \text{At } & t = 0, \dot{x} = 0 \\ \Rightarrow & B = 0 \\ \text{So, } & x = \cos\sqrt{3}t \\ & x(1) = \cos\sqrt{3} = 0.99 \end{aligned}$$

6. (c)

Intermediate value theorem states that if a function is continuous and $f(a) \cdot f(b) < 0$, then surely there is a root in (a, b) . The contrapositive of this theorem is that if a function is continuous and has no root in (a, b) then surely $f(a) \cdot f(b) \geq 0$. But since it is given that there is no root in the closed interval $[a, b]$ it means $f(a) \cdot f(b) \neq 0$.

So surely $f(a) \cdot f(b) > 0$ which is choice (c).

7. (a)

$$\begin{aligned} u &= 2xy \\ u_x &= 2y \quad u_y = 2x \end{aligned}$$

In option (a)

$$\begin{aligned} V_x &= -2x \quad u_y = -V_x \\ V_y &= 2y \end{aligned}$$

(-R equation are satisfied only in option a)

8. (a)

$$\begin{aligned} f(x, y) &= x^2 + 3y^2 \\ \phi &= x^2 + y^2 - 2 \text{ and point } P \Rightarrow (1, 1) \end{aligned}$$

Normal to the surface,

$$\nabla\phi = \hat{i} \frac{\partial\phi}{\partial x} + \hat{j} \frac{\partial\phi}{\partial y} = 2x\hat{i} + 2y\hat{j}$$

$$\nabla\phi|_{\text{at } P(1,1)} = 2\hat{i} + 2\hat{j}$$

the normal vector is $\vec{a} = 2\hat{i} + 2\hat{j}$

Magnitude of directional derivative of f along \vec{a} at $(1, 1)$ is $\Rightarrow \nabla \cdot f \cdot \hat{a}$

$$\nabla f = \hat{i} \frac{\partial f}{\partial x} + \hat{j} \frac{\partial f}{\partial y} = 2x\hat{i} + 6y\hat{j}$$

$$\nabla f|_{(1,1)} = 2\hat{i} + 6\hat{j}$$

$$|\vec{a}| = \sqrt{4+4} = 2\sqrt{2}$$

$$\hat{a} = \frac{2\hat{i} + 2\hat{j}}{2\sqrt{2}} = \frac{\hat{i} + \hat{j}}{\sqrt{2}}$$

\therefore Magnitude of directional derivative

$$\begin{aligned} &= (2\hat{i} + 6\hat{j}) \left(\frac{\hat{i} + \hat{j}}{\sqrt{2}} \right) \\ &= \frac{2+6}{\sqrt{2}} = \frac{8}{\sqrt{2}} = 4\sqrt{2} \end{aligned}$$

9. (a)

$$I = \oint_c \frac{-3z+4}{(z^2+4z+5)} dz = 2\pi i \text{ (sum of residues)}$$

Poles of $\frac{-3z+4}{(z^2+4z+5)}$ are given by

$$z^2 + 4z + 5 = 0$$

$$z = \frac{-4 \pm \sqrt{16-20}}{2} = \frac{-4 \pm 2i}{2} = -2 \pm i$$

Since the poles lie outside the circle $|z| = 1$.

So $f(z)$ is analytic inside the circle $|z| = 1$.

$$\text{Hence } \oint_c f(z) dz = 2\pi i (0) = 0$$

10. (b)

Given that the partial differential equation is parabolic.

$$\therefore B^2 - 4AC = 0$$

$$\therefore B^2 - 4(3)(3) = 0$$

$$B^2 - 36 = 0$$

$$B^2 = 36$$

$$\text{Here } A = 3$$

$$C = 3$$

11. (d)

The differential equation is $3y''(x) + 27y(x) = 0$

The auxillary equation is

$$3m^2 + 27 = 0$$

$$m^2 + 9 = 0$$

$$m = \pm 3i$$

Solution is $y = c_1 \cos 3x + c_2 \sin 3x$

given that

$$y(0) = 0$$

$$\therefore 0 = c_1$$

$$y' = 3c_2 \cos 3x$$

$$y'(0) = 2000$$

$$2000 = 0 + 3c_2$$

$$c_2 = \frac{2000}{3}$$

$$\therefore y = \frac{2000}{3} \sin 3x$$

$$\text{when } x = 1 \quad y = \frac{2000}{3} \sin 3 = 94.08$$

12. (d)

$$x + y + z = 4 \quad \dots(1)$$

$$x - y + z = 0 \quad \dots(2)$$

$$2x + y + z = 5 \quad \dots(3)$$

Adding (1) and (2) & (2) and (3) gives

$2x + 2z = 4$ and $3x + 2z = 5$ which gives $x = 1$, $z = 1$ and $y = 2$

Alt: Option (b) can be eliminated since they do not satisfy 1st condition. Only (d) satisfies 3rd equation.

13. (c)

$$\begin{aligned} \text{Trace of } A &= 14 \\ a + 5 + 2 + b &= 14 \\ a + b &= 7 \end{aligned} \quad \dots(i)$$

$$\begin{aligned} \det(A) &= 100 \\ 5 \begin{vmatrix} a & 3 & 7 \\ 0 & 2 & 4 \\ 0 & 0 & b \end{vmatrix} &= 100 \\ 5 \times 2 \times a \times b &= 100 \\ 10ab &= 100 \\ ab &= 10 \end{aligned} \quad \dots(ii)$$

From equation (i) and (ii)

$$\begin{aligned} \text{either} & \quad a = 5, \quad b = 2 \\ \text{or} & \quad a = 2, \quad b = 5 \\ |a - b| &= |5 - 2| = 3 \end{aligned}$$

14. (a)

Given differential equation is

$$x \frac{dy}{dx} + y = x^4$$

$$\Rightarrow \frac{dy}{dx} + \left(\frac{y}{x}\right) = x^3 \quad \dots(i)$$

Standard form of Leibnitz linear equation is

$$\frac{dy}{dx} + Py = Q \quad \dots(ii)$$

where P and Q function of x only and solution is given by

$$y(\text{I.F.}) = \int Q(\text{I.F.}) dx + C$$

where, integrating factor (I.F.) = $e^{\int P dx}$

Here in equation (i),

$$P = \frac{1}{x} \text{ and } Q = x^3$$

$$\text{I.F.} = e^{\int \frac{1}{x} dx} = e^{\ln x} = x$$

Solution

$$y(x) = \int x^3 \cdot x dx + C$$

$$yx = \frac{x^5}{5} + C$$

given condition

$$y(1) = \frac{6}{5}$$

means at

$$x = 1; y = \frac{6}{5}$$

\Rightarrow

$$\frac{6}{5} \times 1 = \frac{1}{5} + C$$

\Rightarrow

$$C = \frac{6}{5} - \frac{1}{5} = 1$$

Therefore

$$yx = \frac{x^5}{5} + 1$$

\Rightarrow

$$y = \frac{x^4}{5} + \frac{1}{x}$$

15. (c)

$$\begin{aligned} F(s) &= \int_0^{\infty} f(t)e^{-st} dt \\ &= \int_0^1 2e^{-st} dt + \int_1^{\infty} 0 \cdot e^{-st} dt \\ &= 2 \left[\frac{e^{-st}}{-s} \right]_0^1 = \frac{2}{-s} [e^{-s} - 1] \\ &= \frac{2(1 - e^{-s})}{s} = \frac{2 - 2e^{-s}}{s} \end{aligned}$$

16. (b)

From the diagram C is $y = x$

$$\begin{aligned} I &= \int_C (x^2 + iy^2) dz \\ &= \int_C (x^2 + iy^2)(dx + idy) \\ &= \int_C (x^2 + ix^2)(dx + idx) \\ &= \int x^2 dx + ix^2 dx + ix^2 dx - x^2 dx \\ &= 2i \int_0^1 x^2 dx = 2i \left(\frac{x^3}{3} \right) \Big|_0^1 = \frac{2i}{3} \end{aligned}$$

17. (c)

$$x(ydx + xdy) \cos \frac{y}{x} = y(xdy - ydx) \sin \frac{y}{x}$$

$$\frac{ydx + xdy}{x dy - y dx} = \frac{y}{x} \tan \frac{y}{x}$$

Let

$$y = v \cdot x$$

$$dy = v dx + x dv$$

$$\frac{v x dx + v x dx + x^2 dv}{v x dx + x^2 dv - v x dx} = v \tan v$$

$$\frac{x dv + 2v dx}{x dv} = v \tan v$$

$$1 + \frac{2v}{x} \frac{dx}{dv} = v \tan v$$

$$\frac{2v}{x} \frac{dx}{dv} = v \tan v - 1$$

$$2 \frac{dx}{x} = \left(\tan v - \frac{1}{v} \right) dv$$

Integrating both sides.

$$2 \log x = \log |\sec v| - \log v + \log c$$

$$\Rightarrow x^2 = \frac{c \sec v}{v}$$

$$\Rightarrow x^2 \frac{y}{x} = c \sec \frac{y}{x}$$

$$\Rightarrow xy \cos \frac{y}{x} = c$$

19. (b)

Let P be the probability that six occurs on a fair dice,

$$\therefore P = \frac{1}{6}$$

$$\therefore q = \frac{5}{6}$$

Let X , be the number of times 'six' occurs,

Probability of obtaining at least two 'six' in throwing a fair dice 4 times is

$$\begin{aligned} &= 1 - \{P(X=0) + P(X=1)\} \\ &= 1 - \{ {}^4C_0 p^0 q^4 + {}^4C_1 p^1 q^3 \} \\ &= 1 - \left\{ \left(\frac{5}{6} \right)^4 + \left[4 \times \frac{1}{6} \times \left(\frac{5}{6} \right)^3 \right] \right\} \\ &= 1 - \left\{ \frac{125}{144} \right\} = \frac{19}{144} \end{aligned}$$

20. (d)

Since negative and positive are equally likely, the distribution of number of negative values is binomial with

$$n = 5 \text{ and } p = \frac{1}{2}$$

Let X represent number of negative values in 5 trials.

p (at most 1 negative value)

$$\begin{aligned} &= p(x \leq 1) \\ &= p(x=0) + p(x=1) \\ &= {}^5C_0 \left(\frac{1}{2} \right)^0 \left(\frac{1}{2} \right)^5 + {}^5C_1 \left(\frac{1}{2} \right)^1 \left(\frac{1}{2} \right)^4 \\ &= \frac{6}{32} \end{aligned}$$

21. (a)

$$\begin{aligned} \int_0^\pi x^2 \cos x \, dx &= x^2 (\sin x) - 2x (-\cos x) + 2(-\sin x) \Big|_0^\pi \\ &= \pi^2 \cdot 0 + 2\pi(-1) - 0 = -2\pi \end{aligned}$$

22. (a)

Let,

$$\sin^{-1}x = t$$

$$\frac{dx}{\sqrt{1-x^2}} = dt$$

$$I = \int_0^{\pi/2} t^2 dt = \left[\frac{t^3}{3} \right]_0^{\pi/2} = \frac{\pi^3}{24}$$

23. (c)

To calculate $\frac{1}{a}$ using N-R method,
set up the equation as

$$x = \frac{1}{a}$$

i.e.

$$\frac{1}{x} = a$$

⇒

$$\frac{1}{x} - a = 0$$

i.e.

$$f(x) = \frac{1}{x} - a = 0$$

Now,

$$f'(x) = -\frac{1}{x^2}$$

$$f(x_k) = \frac{1}{x_k} - a$$

$$f'(x_k) = -\frac{1}{x_k^2}$$

For N-R method,

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

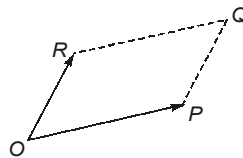
⇒

$$x_{k+1} = x_k - \frac{(1/x_k - a)}{-\frac{1}{x_k^2}}$$

Simplifying which we get,

$$x_{k+1} = 2x_k - ax_k^2$$

24. (a)



The area of parallelogram $OPQR$ in figure shown above, is the magnitude of the vector product

$$= |\overline{OP} \times \overline{OR}|$$

$$\overline{OP} = a\hat{i} + b\hat{j}$$

$$\overline{OR} = e\hat{i} + d\hat{j}$$

$$\overline{OP} \times \overline{OR} = \begin{vmatrix} i & j & k \\ a & b & 0 \\ e & d & 0 \end{vmatrix} = 0\hat{i} + 0\hat{j} + (ad - bc)\hat{k}$$

$$|\overline{OP} \times \overline{OR}| = \sqrt{0^2 + 0^2 + (ad - bc)^2} = ad - bc$$

25. (d)

$$f = u + iv$$

$$u = 3x^2 - 3y^2$$

for f to be analysis, we have Cauchy-Riemann conditions,

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} \quad \dots(i)$$

$$\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x} \quad \dots(ii)$$

From (i) we have,

$$6x = \frac{\partial v}{\partial y}$$

\Rightarrow

$$\int \partial v = \int 6x \partial y$$

$$v = 6xy + f(x)$$

i.e.

$$v = 6xy + f(x)$$

$\dots(iii)$

Now applying equation (ii) we get,

$$\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$$

\Rightarrow

$$-6y = -\left[6x + \frac{df}{dx}\right]$$

\Rightarrow

$$6x + \frac{df}{dx} = 6y$$

$$\frac{df}{dx} = 6y - 6x$$

By integrating,

$$f(x) = 6yx - 3x^2 + K$$

Substitute in equation (iii)

$$v = 3x^2 + 6yx - 3x^2 + K$$

\Rightarrow

$$v = 6yx + K$$

26. (b)

Result, Rank ($A^T A$) = Rank (A)

27. (a)

$$V = \int_0^{2\pi} \int_0^{\pi/3} \int_0^1 r^2 \sin \phi \cdot dr \cdot d\phi \cdot d\theta = \int_0^{2\pi} \int_0^{\pi/3} \left[\frac{r^3}{3} \right]_0^1 \sin \phi \, d\phi \, d\theta$$

$$= \frac{1}{3} \int_0^{2\pi} [-\cos \phi]_0^{\pi/3} d\theta = \frac{1}{3} \times \frac{1}{2} \times \int_0^{2\pi} d\theta = \frac{1}{3} \times \frac{1}{2} \times 2\pi = \frac{\pi}{3}$$

28. (c)

$$I = \int_1^3 \frac{1}{x} dx$$

x	$f(x) = \frac{1}{x}$
1	1
2	$\frac{1}{2}$
3	$\frac{1}{3}$

$$I = \frac{h}{3}(f_0 + 4f_1 + f_2) = \frac{1}{3}\left(1 + 4 \times \frac{1}{2} \times \frac{1}{3}\right) = 1.111$$

29. (d)

$$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s)$$

Given that,

$$F(s) = \left[\frac{3s + 1}{s^3 + 4s^2 + (K - 3)s} \right]$$

$$\lim_{t \rightarrow \infty} f(t) = 1$$

$$\Rightarrow \lim_{s \rightarrow 0} s \left[\frac{3s + 1}{s^3 + 4s^2 + (K - 3)s} \right] = 1$$

$$\Rightarrow \lim_{s \rightarrow 0} \left[\frac{3s + 1}{s^2 + 4s + (K - 3)} \right] = 1$$

$$\Rightarrow \frac{1}{K - 3} = 1$$

$$\Rightarrow K - 3 = 1$$

$$\Rightarrow K = 4$$

30. (b)

The augmented matrix for the given system is $\left[\begin{array}{ccc|c} 2 & 1 & -4 & \alpha \\ 4 & 3 & -12 & 5 \\ 1 & 2 & -8 & 7 \end{array} \right]$.

Performing Gauss-Elimination on the above matrix

$$\left[\begin{array}{ccc|c} 2 & 1 & -4 & \alpha \\ 4 & 3 & -12 & 5 \\ 1 & 2 & -8 & 7 \end{array} \right] \xrightarrow[\substack{R_2 - 2R_1 \\ R_3 - 1/2 R_1}]{R_2 - 2R_1} \left[\begin{array}{ccc|c} 2 & 1 & -4 & \alpha \\ 0 & 1 & -4 & 5 - 2\alpha \\ 0 & 3/2 & -6 & 7 - \alpha/2 \end{array} \right]$$

$$\xrightarrow{R_3 - 3/2 R_2} \left[\begin{array}{ccc|c} 2 & 1 & -4 & \alpha \\ 0 & 1 & -4 & 5 - 2\alpha \\ 0 & 0 & 0 & \frac{5\alpha - 1}{2} \end{array} \right]$$

Now for infinite solution it is necessary that at least one row must be completely zero.

$$\therefore \frac{5\alpha - 1}{2} = 0$$

$$\alpha = 1/5 \text{ is the solution}$$

\(\therefore\) There is only one value of \(\alpha\) for which infinite solution exists.

