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DC MACHINE										
ELECTRICAL ENGINEERING										
Date of Test : 04/08/2022										
AN	SWER K	EY >	•							
<b>AN</b> :	SWER K		(c)	13.	(b)	19.	(b)	25.	(b)	
1.	(b)	7.	(c)							
1. 2.	(b) (a)	7. 8.	(c) (b)	14.	(a)	20.	(b)	26.	(c)	
1.	(b)	7.	(c)	14.			(b)		(c)	
1. 2.	(b) (a)	7. 8. 9.	(c) (b)	14. 15.	(a)	20.	(b) (a)	26.	(c) (b)	
1. 2. 3.	(b) (a) (b)	7. 8. 9. 10.	(c) (b) (d)	14. 15.	(a) (d) (b)	20. 21.	(b) (a) (a)	26. 27.	(c) (b) (a)	

## **DETAILED EXPLANATIONS**

### 1. (b)

Back emf is given by,

$$E_{b} = \frac{NP\phi Z}{A \times 60}$$

$$= \frac{1000 \times 0.15 \times 100}{60} = 250 \text{ V}$$

$$I_{f} = \frac{280 - 250}{0.2} = 150 \text{ A}$$

### 2. (a)

Let, induced emf = x $x + I_a r_a = 300 \text{ V}$ When load is reduced to half,

$$x + \frac{I_a r_a}{2} = 250 \text{ V}$$
 ...(ii)

Solving equation (i) and (ii), we get Induced emf, x = 200 V

### 3. (b)

For maximum efficiency,

Constant loss = losses proportional to square of variable Cu loss =  $I^2R$ Brush loss  $\propto I$  (so it is not included in constant losses) So, Constant loss =  $150 + 200 + P_i$   $150 + 200 + P_i = 400$  $P_i = 50 \text{ W}$ 

### 4. (a)

For series DC motor,

$$T \propto I^2$$

as torque is constant means current also remains constant

$$T = \frac{E_b I_a}{\omega}$$

 $T \propto I_a^2$  $I_a \propto \sqrt{T}$ 

as both T and  $I_a$  as constant

 $E_b \propto \omega$ In case of series connection  $E_b \approx V/2$ for parallel connection,  $E_b \approx V$ So speed becomes double

### 5. (d)

or,

For series motor,

 $T \rightarrow \text{Torque}$ 

...(i)

...(i)

and also,  
or  

$$E_b \propto N \phi$$

$$E_b \propto N I_a$$

$$N \propto \frac{E_b}{I_a}$$
From equation (i),  

$$N \propto \frac{E_b}{\sqrt{T}}$$
(a)  

$$T = K \phi I_a = 300$$

$$E = V - I_a R_a = K \phi \omega$$

$$600 - 0.5 I_a = 2\pi \times \frac{1500}{60} \times \frac{300}{I_a}$$

$$0.5 I_a^2 - 600 I_a + 47123.8 = 0$$

$$I_a = 84.49 \text{ A}$$

$$K \phi = 3.55 \text{ Nm/A}$$

$$I'_a = \frac{T}{(K \phi)'} = \frac{300}{0.9 \times 3.55} = 93.89 \text{ A}$$

7. (c)

6.

We know that,

So,  

$$\begin{array}{rcl}
T_{1} &=& \frac{\phi_{1}I_{a1}}{\phi_{2}I_{a2}} \\
T_{2} &=& \frac{\phi_{2}I_{a2}}{\phi_{1}I_{a1}} \times T_{1} \\
\phi_{2} &=& 1.2 \phi_{1}, I_{a1} = 40 \text{ A}, I_{a2} = 60 \text{ A} \\
T_{2} &=& 1.2 \times \frac{60}{40} \times 20 = 36 \text{ N-m}
\end{array}$$

(b) 8.

$$N = \frac{600}{60} = 10 \text{ rev/sec}$$

Peripheral velocity of commutator,

$$V_p = \pi DN$$
  
=  $\pi \times 50 \times 10 \text{ cm/sec}$   
As we know,  $V_p \times t_c$  = Brush width  
 $\therefore$  Time of commutation,  $t_c = \frac{2}{2} = 1.273 \text{ m}$ 

$$\therefore \qquad \text{Time of commutation, } t_c = \frac{2}{\pi \times 50 \times 10} = 1.273 \text{ msec}$$

9. (d)

We know that, emf generated,

$$E = \frac{P\phi NZ}{60A} = \phi \times 50 \times 18 \times \frac{9000}{60} \times \frac{4}{2}$$

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$$357 = \phi \times 50 \times 18 \times \frac{9000}{60} \times \frac{4}{2}$$

 $\phi = 1.32 \text{ mWb}$ 

Flux per pole,

### 10. (b)

Field current,  $I_{f} = \frac{250}{125} = 2 \text{ A}$ No load armature current, Constant losses,  $I_{a0} = 16 - 2 = 14 \text{ A};$   $P_{K} = (250 \times 14 - (14)^{2} \times 0.2) + 250 \times 2 = 3960.8 \text{ W}$   $I_{a} = 152 - 2 = 150 \text{ A}$   $P_{L} = I_{a}^{2}R_{a} + P_{K} = (150)^{2} \times 0.2 + 3960.8$  = 8.461 kW  $P_{in} = 250 \times 152 = 38 \text{ kW}$   $\therefore \text{ Efficiency, } \eta_{n} = \frac{38 - 8.461}{38} \times 100 = 77.73\%$ 

### 11. (b)

The motor and generator are identical DC supply given to motor,

$$V = 1 \text{ p.u.}$$

Current in both motor and generator

$$I_{am} = I_{ag} = 1 \text{ p.u.}$$

$$R_{am} = R_{ag} = 0.02 \text{ p.u.}$$
Back emf in motor,  $E_m = V - I_{am} R_{am}$ 

$$E_m = 1 - 1 \times 0.02 = 0.98 \text{ p.u.}$$
Also
$$E_m I_{am} = E_g I_{ag}$$

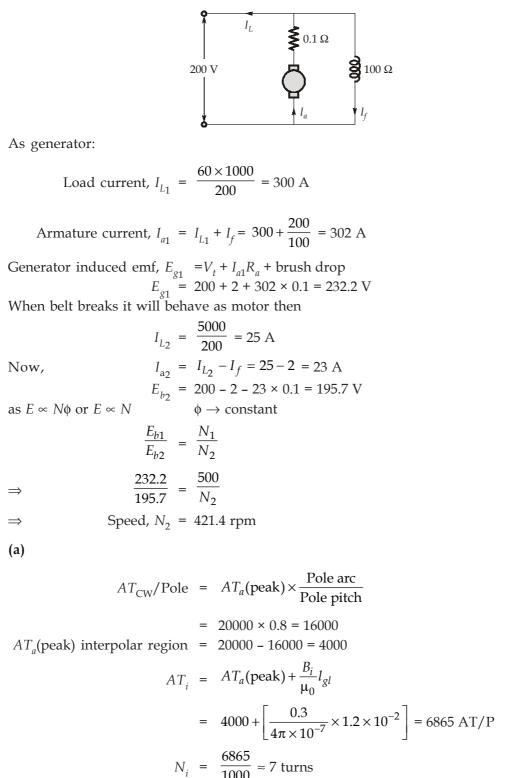
$$\Rightarrow \qquad E_m = E_g - I_{ag} \cdot R_{ag}$$

$$= 0.98 - 1 \times 0.02 = 0.96 \text{ p.u.}$$
Load resistance  $= \frac{V_g}{I_{ag}} = \frac{0.96}{1.0} = 0.96 \text{ p.u.}$ 

## 12. (c)

Compensating winding, AT/pole = armature AT/pole 
$$\times \frac{\text{Pole arc}}{\text{Pole pitch}}$$
  
= 19000 × 0.7 = 13300  
Turn/pole =  $\frac{AT_{cw} / \text{pole}}{\text{Armature current}} = \frac{13300}{1000} = 13.3 \approx 14$   
No. of compensating conductor per pole,  
 $14 \times 2 = 28$   
AT for airgap under interpole =  $\frac{B_g}{\mu_0} l_g = \frac{0.3}{4\pi \times 10^{-7}} \times 1 \times 10^{-2} = 2387.324 \text{ ATs}$   
Net AT for interpole = 19000 + 2387.324 - 14000  
No. of turns in interpole =  $\frac{19000 + 2387.324 - 14000}{1000} \approx 8$ 

### 13. (b)



14.

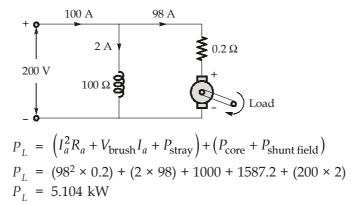
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15. (d)

No load loss = 
$$200 \times 10 = 2000$$
 W  
 $I_f = \frac{200}{100} = 2$  A  
Core loss =  $(200 \times 8) - (8^2 \times 0.2)$   
=  $1587.2$  W  
 $10A \qquad 8A$   
 $2A \qquad 0.2 \Omega$   
 $200$  V  
 $100 \Omega$ 

At load:

Stray load loss = 
$$0.5 \times 2000 = 1000$$
 W



16. (b)

At full load,

Armature current,

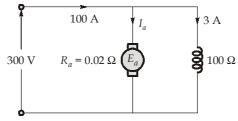
$$I_a = 165 + 5 = 170 \text{ A}$$
$$\theta_e = \frac{P}{2} \cdot \theta_m = \frac{12}{2} \times 4 = 24^{\circ}$$

Cross magnetizing AT/Pole

$$= \left(\frac{180^{\circ} - 2\theta_{e}}{180^{\circ}}\right) \times \frac{Z/2}{P} \times \frac{I_{a}}{A} \quad \text{(For lap connected windings } A = P = 12\text{)}$$
$$= \left(\frac{180 - 2 \times 24}{180^{\circ}}\right) \times \frac{662/2}{12} \times \frac{170}{12}$$

## 17. (c)

Case-I:



Armature current, Back emf,

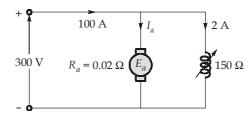
$$I_{a1} = 100 - 3 = 97 \text{ A}$$
  

$$E_{a1} = 300 - 97 \times 0.02$$
  

$$E_{a1} = 298.06 \text{ V}$$

## Case-II:

When 50  $\Omega$  external resistance added in field circuit,



Load torque is constant

$$T \propto \phi I_{a}$$
  

$$\phi_{2}I_{a2} = \phi_{1}I_{a1}$$
  

$$\phi \propto I_{f}$$
  

$$I_{a2} = I_{a1}\frac{\phi_{1}}{\phi_{2}} = 97 \times \frac{3}{2} = 145.5 \text{ A}$$
  

$$E_{a2} = 300 - 145.5 \times 0.02$$
  

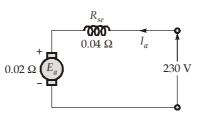
$$E_{a2} = 297.09 \text{ V}$$
  
We know that,  

$$\frac{E_{a2}}{E_{a1}} = \frac{\phi_{2}}{\phi_{1}} \times \frac{N_{2}}{N_{1}}$$
  

$$\frac{297.09}{298.06} = \frac{2}{3} \times \frac{N_{2}}{1600}$$
  

$$N_{2} = 2392.18 \text{ rpm}$$

18. (b)



Armature power developed,

$$= 1.5 \text{ kW} + 0.1 \text{ kW}$$

$$E_b I_a = 1.6 \text{ kW}$$

Back emf is given by,

$$E_{b} = \frac{NP\phi Z}{A \times 60} = \frac{N \times 0.035 \times 500}{60}$$
 (For lap  $A = P$ )  
and armature current,  $I_{a} = \frac{230 - E_{b}}{0.06}$   
$$E_{b} \left(\frac{230 - E_{b}}{0.06}\right) = 1600$$
  
$$230 E_{b} - E_{b}^{2} - 96 = 0$$
  
$$E_{b} = 229.58 V$$
  
Speed,  $N = \frac{60E_{b}}{\phi Z} = \frac{60 \times 229.58}{0.035 \times 500}$   
 $N = 787.13 \text{ rpm}$ 

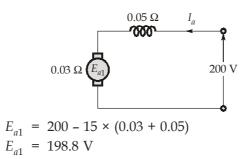
19. (b)

Load characteristic is

 $T_L \propto N^2$  For dc series motor, torque-current relation is given by  $T_d \propto I_a^2$ 

$$\frac{I_{a2}}{I_{a1}} = \frac{N_2}{N_1}$$
$$\frac{I_{a2}}{15} = \frac{750}{1500}$$
$$I_{a2} = 7.5 \text{ A}$$

Case-I:



### Case-II:

When additional resistance added in series with the armature circuit,

$$I_{a2} = 7.5 \text{ A},$$

$$N_{2} = 750 \text{ rpm}$$
Now,
$$E_{a} \propto \phi \omega_{m}$$

$$\frac{E_{a2}}{E_{a1}} = \frac{N_{2} I_{a2}}{N_{1} I_{a1}} \qquad \text{(In dc series motor } \phi \sim I_{a}\text{)}$$

$$\frac{E_{a2}}{I98.8} = \frac{750 \times 7.5}{1500 \times 15}$$

$$E_{a2} = 49.7 \text{ V}$$

### 20. (b)

At rated load, Motor counter emf,  $E_a = V_t - I_a r_a$ (or)  $K_m \cdot \omega_r = 230 - 100 \times 0.5 = 180 \text{ V}$ Where,  $\omega_r = \text{ rated motor speed in rad/sec}$ 

$$\therefore \quad \text{Motor constant, } K_m = \frac{180 \times 60}{2\pi \times 250}, \text{ V-s/rad}$$

Armature current at any speed  $\omega$  is given by

$$I_a = \frac{V_t - E_a}{r_a} = \frac{230 - K_m \omega}{0.5}$$

$$\therefore \qquad \text{Motor torque, } T_e = K_m I_a = \frac{K_m}{0.5} [230 - K_m \omega]$$

Under steady state,

Motor torque,  $T_e$  = load torque,  $T_L$ 

(or) 
$$\frac{K_m}{0.5} [230 - K_m \omega] = 500 - 10 \omega$$

(or) 
$$\frac{230}{0.5} \times \frac{180 \times 60}{2\pi \times 250} - \frac{1}{0.5} \left[ \frac{180 \times 60}{2\pi \times 250} \right]^2 \cdot \omega = 500 - 10 \omega$$

(or) 
$$3162.73 - 94.545 \omega = 500 - 10 \omega$$

(or) 
$$\omega = \frac{3162.73 - 500}{84.545} = 31.495 \text{ rad/sec}$$

$$\therefore \qquad \text{Motor speed, } N_m = \frac{31.495 \times 60}{2\pi} = 300.75 \text{ rpm}$$

### 21. (a)

Output power,	$P_0 = 240 \times 100$
	= 24000 W
Shunt field current,	$I_f = 3 \text{ A},$
Armature current,	$I_a = 100 + 3 = 103 \text{ A}$
Series field current,	$I_{se} = \frac{0.04}{0.04 + 0.01} \times 100 = 80 \text{ A}$
	$I_d = 100 - 80 = 20 \text{ A}$
	$E_a = V_t + I_L R_{fe} + I_s R_s + I_a R_a$
	$= 240 + 100 \times 0.03 + 80 \times 0.01 + 103 \times 0.05$
	= 248.95 V
	$V_f = E_a - I_a R_a$

		=	248.95 – 103 × 0.05 = 243.8 V		
Hence,	$R_{f}$	=	$\frac{243.8}{3} = 81.267 \ \Omega$		
Copper losses :					
Armature :	$I_a^2 R_a$	=	$103^2 \times 0.05 = 530.45$ W		
Series field :	$I_s^2 R_s$	=	$80^2 \times 0.01 = 64 \text{ W}$		
Shunt field :	$I_f^2 R_f$	=	$3^2 \times 81.267 = 731.4 \text{ W}$		
Diverter resistance:	$I_d^2 R_d$	=	$20^2 \times 0.04 = 16 \text{ W}$		
Feeder resistance:	$I_L^2 R_{fe}$	=	$100^2 \times 0.03 = 300 \text{ W}$		
Total copper loss :	P <sub>cu</sub>	=	530.45 + 64 + 731.4 + 16 + 300		
		=	1641.85 W		
Thus, the power developed is					
	$P_d$	=	$P_0 + P_{cu} = 24000 + 1641.85$		
		=	25641.85 W		
The power input is,					
	$P_{in}$	=	$P_d + P_r$		
		=	25641.85 + 2000		
		=	27641.85 W		

Hence, the efficiency is

$$\eta = \frac{P_0}{P_{\rm in}} = \frac{24000}{27641.85} = 0.8682 \text{ (or) } 86.82\%$$

### 22. (a)

Interpoles are placed to aid the commutating process by inducing emf in commutating coils to cancel reactance emf. So interpoles are located in the interpolar region along MNA of main pole and connected in series to field winding and should have polarity opposite to that of the next main pole in the direction of rotation of armature.

### 23. (a)

The shunt field current is

$$I_f = \frac{120}{40} = 3A$$

For maximum efficiency,

$$I_{Lm}^{2}(\mathbf{R}_{a} + \mathbf{R}_{s}) = P_{r} + I_{f}^{2}(\mathbf{R}_{a} + \mathbf{R}_{s} + \mathbf{R}_{f})$$

$$I_{Lm}^2(0.05 + 0.02) = 3^2(0.05 + 0.02 + 40) + 2000$$

or,

$$I_{\rm Lm} = 183.64 \; {\rm A}$$

Thus the power output at maximum efficiency is :

 $P_0 = 120 \times 183.64 = 22036.8 \text{ W}$ 

The total copper loss is

$$P_{cu} = I_a^2 (R_a + R_s) + I_f^2 R_f$$
  
= (183.64)<sup>2</sup> × 0.07 + (3)<sup>2</sup> × 40  
= 2720.65 W

The power

The power developed at maximum efficiency is

$$P_d = P_0 + P_{cu}$$
  
= 22036.8 + 2720.65 = 24757.45 W  
input :  $P_{in} = 24757.45 + 2000 = 26757.45$  W

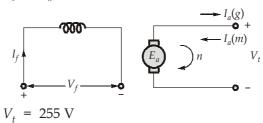
Hence, the maximum efficiency is :

$$\eta = \frac{22036.8}{26757.45} = 0.8235 \quad (or) \quad 82.35\%$$

### 24. (a)

Open circuit ( $I_a = 0$ ), then

$$V_t = E_a = 250 \text{ V at } 3000 \text{ rpm}$$



Now,

As  $V_t > E_a$ , the machine is acting as a motor

$$I_a = \frac{V_t - E_a}{R_a} = \frac{255 - 250}{0.05} = 100 \text{ A}$$

The current flowing into the positive terminal in opposition to  $E_{a'}$  therefore

Electromagnetic power = 
$$E_a I_a = 250 \times 100$$
  
= 25 kW = mechanical power output  
Speed = 3000 rpm  
or,  $\frac{3000 \times 2\pi}{60}$  = 314.16 rad/s

Electromagnetic torque,

$$T_{\rm em} = \frac{E_a I_a}{\omega_m} = \frac{25 \times 10^3}{314.16} = 79.58 \text{ N-m}$$

25. (b)

*.*..

$$AT_{cw/pole} = \frac{I_a Z}{2AP} \left( \frac{\text{Pole arc}}{\text{Pole pitch}} \right)$$
$$N_{cw/pole} = \frac{Z}{2AP} \left( \frac{\text{Pole arc}}{\text{Pole pitch}} \right) = \frac{286}{2 \times 6 \times 6} \times 0.7 = 2.78$$

Compensating conductor/pole

=  $2.78 \times 2 = 5.56 \approx 6$  (nearest integer)

26. (c)

Firing angle, 
$$\alpha = 0^{\circ}$$
  

$$\frac{3\sqrt{2}V_l}{\pi}\cos\alpha = 230$$

$$V_l = 170.31 \text{ V}$$
At Speed,  $N = 1500 \text{ rpm}$ 

Back emf,  $E_1 = 230 - 20 \times 0.6 = 218$  V At half rated torque, Current,  $I_2 = \frac{1}{2} \times 20 = 10 \text{ A}$ Back emf,  $E_2 = -\frac{900}{1500} \times 218 = -130.8 \text{ V}$  $\frac{3\sqrt{2}}{\pi}V_l \cos \alpha = -130.8 + 10 \times 0.6$  $\alpha = 122.86^{\circ}$ 27. (b)  $T = K \phi I_a$  $K\phi = \frac{10}{10} = 1 \text{ Nm/A}$ T = 25 NmNow,  $K\phi I_a = 25$  $I_a = 25 \text{ A}$  $V = E + I_a R_a$  $200 = K\phi\omega + 25 \times 0.2$  $\omega \times 1 = 195$  $\frac{2\pi N}{60} = 195$ N = 1862.11 rpm

### 28. (a)

At no load;

Back emf,  $E_{b0} = V_t - I_{a0} (R_a)$   $E_{b0} = 220 - 3(0.5)$   $E_{b0} = 218.5 \text{ V}$ At full load; Back emf,  $E_{b fl} = V_t - I_{a fl} (R_a)$ = 220 - 45 (0.5)

= 220 – 45 (0.5  $E_{b\ fl}$  = 197.5 V As flux is given constant;

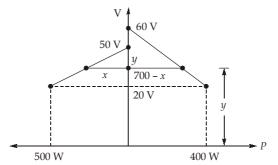
then, we can write;  $E_b \propto N$ 

or,

$$\frac{E_{b\,fl}}{E_{b0}} = \frac{N_{fl}}{N_0}$$

$$N_{fl} = \left(\frac{197.5}{218.5}\right) \times 1500$$
  
= 1355.83 \approx 1356 rpm

# 29. (a) The motor and generator are identical. DC supply given to motor V = 1 p.u.Current in both motor and generator $I_{am} = I_{ag} = 1 \text{ p.u.}$ Armature resistance, $R_{am} = R_{ag} = 0.015 \text{ p.u.}$ Back emf in motor, $E_m = V - I_{am} \cdot R_{am}$ $E_m = 1 - (1 \times 0.015)$ = 0.985 p.u.As rotational losses are negligible, Power output of motor = Power input to generator $E_m I_{am} = E_g \cdot I_{ag}$ $E_m = E_g = 0.985 \text{ p.u.}$ or, or, Terminal voltage of generator $V_g = E_g - I_{ag} \cdot R_{ag} = 0.985 - (1 \times 0.015) = 0.97$ p.u. Load resistance = $\frac{V_g}{I_g} = \frac{0.97}{1.0} = 0.97$ p.u. 30. (d)



From similarity of triangles for generator 1,

$$\frac{50 - y}{x} = \frac{50 - 20}{500}$$

$$50 - y = 0.06 x$$

$$0.06 x + y = 50$$
...(i)
For second triangle,
$$\frac{60 - y}{700 - x} = \frac{60 - 20}{400}$$

$$60 - y = 70 - 0.1 x$$

$$0.1 x - y = 10$$
Solving the equations (i) and (ii), we get
$$y = 27.5 V$$
Voltage = 27.5 V

###