S.No.: 02 SK1\_CS\_W+Y\_220619

**Computer Organization** 



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# CLASS TEST 2019-2020

# COMPUTER SCIENCE & IT

# **Computer Organization**

Date of Test: 22/06/2019

				_ Answ	er Key				
1.	(a)	8.	(b)	13.	(b)	19.	(d)	25.	(b)
2.	(c)	8.	(d)	14.	(a)	20.	(d)	26.	(d)
3.	(c)	9.	(c)	15.	(b)	21.	(b)	27.	(b)
4.	(d)	10.	(b)	16.	(d)	22.	(a)	28.	(b)
5.	(c)	11.	(c)	17.	(c)	23.	(b)	29.	(a)
6.	(b)	12.	(b)	18.	(b)	24.	(b)	30.	(c)



# **DETAILED EXPLANATIONS**

1. (a)

Since, it uses horizontal micro-programmed that requires 1 bit control / signal.

For 125 control signal, we need 125 bits.

Total number of micro-operation instruction =  $215 \times 6 = 1290$ 

It requires 11 bit.

2. (c)

Multiplier	Pair with $(q-1)$	Recorder
0	0	0
1	0	<b>–</b> 1
1	1	0
0	1	+1
1	0	<b>–</b> 1
0	1	+1
0	0	0
1	0	<b>–</b> 1
0	1	+1
1	0	<b>–</b> 1
1	1	0
0	1	+1

3. (c)

When instruction is a computation:

Memory reference: Fetch instruction

Fetch reference of the operand

Fetch operand

Total 3 memory references.

When instruction is a branch:

Memory reference : Fetch instruction

Fetch operand reference and loading program counter

Total 2 memory references.

4. (d)

**RAW hazards:**  $I_1 - I_2$ ,  $I_1 - I_4$ ,  $I_2 - I_3$ ,  $I_2 - I_4$ ,  $I_2 - I_5$ 

WAW hazards:  $I_2 - I_4$ 

**WAR hazards:**  $I_3 - I_4$  and  $I_2 - I_4$ 

5. (c)

- In pipelined CPU, there will be buffer delays. So, for single instruction non-pipelined CPU takes less time compared to pipelined CPU.
- Structural dependencies cause hazards during pipelining.

6. (b)

**Programmed I/O:** Processor issues an I/O command, on behalf of a processor, to an IO module; that process then busy-waits for the operation to be completed before proceeding.

**Interrupt driven I/O:** The processor isues an IO command on behalf of a process, continues to execute subsequent instruction, and is interrupted by the IO module when the latter has completed its work.

**Direct memory access:** A DMA module controls the exchange of data between main memory and IO module.



# 8. (b)

For 1 second it take 10<sup>9</sup> byte

So for 64 kbyte it takes = 
$$\frac{64 k}{10^9}$$
 = 64 µsec

Main memory latency =  $64 \mu sec$ 

Total time required to fetch =  $64 \mu sec + 64 \mu sec = 128 \mu sec$ 

#### 8. (d)

$$1 \text{ block} = 512 \text{ words}$$

$$= 32768 \times 512 \text{ words} = 2^{15} \times 2^9 = 2^{24} \text{ words}$$

Main memory takes 24 bits.

Block size = 512 words =  $2^9$  words

Number of bits for block size = 9 bits.

Number of blocks in set associative = 128

Number of blocks in one set = 4

Number of sets in cache = 
$$\frac{128}{4}$$
 = 32 =  $2^5$ 

Number of bits in set offset = 5 bits



Number of TAG bits = 24 - (9 + 5) = 10 bits.

#### 9. (c)

Consider each statement:

- $S_1$ : Microprogrammed control unit uses variable logic to interrupt instruction since its uses encoded scheme for the instruction.
- $S_2$ : Horizontal microprogramming control unit does not requires an additional hardware (like a decoder) because a fixed logic is associated with the instructions.
- $S_3$ : The performance of a system depends on the direct proportion of memory accesses satisfied by cache.

#### 10. (b)

Bias exponent value = 10000101

$$= 133 - 127 = 6$$

Decimal number = 
$$1.11000 \times 2^{6}$$

$$= -(1110000)_2$$

$$= -(112)_{10}$$



#### 11. (c)

Rate of transfer to or from any one disk = 30 MBps.

Maximum memory transfer rate = 
$$\frac{4 \text{ B}}{10 \times 10^{-9}}$$
 =  $400 \times 10^{6} \text{Bps}$  =  $400 \text{ MBps}$ 

Since rate of data transfer = 30 MBps

Here number of disk transfer = 
$$\left\lceil \frac{400}{30} \right\rceil = 13$$

Therefore, 13 disks can simultaneously transfer data to or from the main memory.

#### 12. (b)

Biased exponent = 
$$18 + 64 = 82$$

Representing 82 in binary

$$(82)_2 = (1010010)_2$$

Representing mantissa in binary

$$(0.625)_{10} = (0.10100000)$$

Floating point representation is as follows:

Sign bit	Exponent			Mantissa		
0		1010010		10100000		
	5	2	Α	A 0	_	

#### 13. (b)

Memory mapped I/O uses the same address bus to address both memory and I/O devices the memory and registers of the I/O devices are mapped to address values.

So, when an address is accessed by the CPU, it may refer to a portion of physical RAM, but it can also refer to memory of I/O device.

#### 14. (a)

Number of lines = 
$$\frac{64K}{32}$$
 =  $2^{11}$ 

Number of sets = 
$$\frac{2^{11}}{4} = \frac{2^{11}}{2^2} = 2^9$$

◄	32 bits	<u> </u>
Tag	SO	WO
18 bits	$\log_2 2^9 = 9$	$\log_2 32 = 5 \text{ bit}$

Tag memory size = 
$$S \times P \times \#$$
 tag bits  
=  $2^9 \times 4 \times (18 + 1 + 1 + 2)$   
=  $2^9 \times 2^2 \times 22$  bits  
=  $2^{10} \times 2 \times 22$  bits  
=  $44 \times 10^{10}$  K bits

#### 15. (b)

Considering each statement:

 $S_1$ : Delayed control transfer, also known as delayed branching, is an attempt to cope with control hazards.

 $S_2$ : The branch target stores the previous target address for the current branch, other algorithms for branch prediction also exist.

S<sub>3</sub>: For any given instruction set architecture implemented on a N-stage pipelined processor, N registers probably is not enough registers to completely prevent structural hazards involving a shortage of register hardware.

### 16. (d)

IF	ID	OF	PD & WB	
1 m-ref	3 m-ref	2 m-ref	_	
1 m-ref	1 m-ref	1 m-ref	_	
1 m-ref	_	1 m-ref	2 cycles	
1 m-ref	_	_	2 m-ref	
1 m-ref	3 m-ref	_	2 m-ref	
1 m-ref	_	_	_	
	1 m-ref 1 m-ref 1 m-ref 1 m-ref 1 m-ref	1 m-ref 3 m-ref 1 m-ref 1 m-ref 1 m-ref — 1 m-ref — 1 m-ref 3 m-ref	1 m-ref     3 m-ref     2 m-ref       1 m-ref     1 m-ref     1 m-ref       1 m-ref     —     1 m-ref       1 m-ref     —     —       1 m-ref     —     —       1 m-ref     3 m-ref     —	

Total time = 
$$80 \text{ cycles} \times 0.5 \text{ ns}$$
  
=  $40 \text{ ns}$ 

#### 17. (c)

2.5 memory reference per instruction  $\Rightarrow \frac{1000}{2.5}$  instruction per 1000 reference.

⇒ 400 instructions.

Now
$$200 = \left(\frac{260}{400}\right)x + \left(\frac{120}{400}\right)2x$$

$$x = \frac{400 \times 200}{500}$$

$$x = \frac{80000}{500}$$

$$x = 160$$

$$2x = 320$$

 $D_1$ : Number of stages, k = 5

 $\tau_i = 3, 2, 4, 2, 3 \text{ ns}$ 

i = 1 to 5

 $\tau = \max(\tau_i) + d$  here d is negligible

 $\tau = 4 \, \text{ns}$ 

 $D_2$ : Number of stages, k = 8

 $\tau_i = 2 \text{ ns each}$ 

i = 1 to 8

 $\tau = \max(\tau_0) = 2 \operatorname{nsec}$ 

Number of instructions, n = 100

$$D_1$$
:  $T_k = (n + k - 1)\tau$   
=  $(100 + 5 - 1) \times 4$   
=  $104 \times 4 = 416 \text{ ns}$ 

$$D_2$$
:  $T_k = (n + k - 1)\tau$   
=  $(100 + 8 - 1) \times 2$   
=  $107 \times 2 = 214 \text{ ns}$ 

Total time saved = 416 - 214 = 202 ns



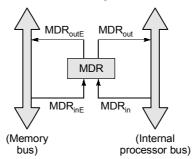
#### 19. (d)

Increasing the cache line size brings in more from memory when a miss occurs. If accessing a certain byte suggests that nearby bytes are likely to be accessed soon (locality), then increasing the cache line essentially prefetches those other bytes. This, in turn, forestalls a later cache miss on those other bytes. If misses occur because the cache is too small, then the designers should increase the size! Conflict misses occur when multiple memory locations are repeatedly accessed but map to the same cache location. Consequently, when they are accessed, they keep kicking one another out of the cache. Increasing the associativity implies that each chunk of the cache is effectively doubled so that more than one memory item can rest in the same cache chunk.

#### 20. (d)

Considering each statement:

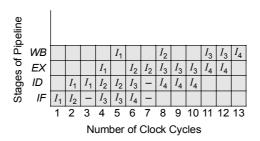
 $S_1$ : 4-control signals are needed for each data register.



MDR is directly connected to data lines of the processor. It has 2 input and 2 output. Data may be loaded into MDR either from memory or from internal bus. Data present in MDR may be placed on either bus are memory. It requires total 4 control signals.

 $S_2$ : The main disadvantage of direct mapping is that cache hit ratio decreases sharply if two or more frequently used blocks map on the same region.

#### 21. (b)



#### 22. (a)

Number of bits for control signals in vertical programming:

$$log_2(2) + log_2(1) + log_2(4) + log_2(27) + log_2(17)$$
  
= 1 + 1 + 2 + 5 + 5 = 14 bits

256 CW = 8 bits

VCW:	Branch condition	Flag	Control field	Control memory address
			1/	Ω

VCW size = 
$$14 + 8 = 22$$
 bits

Vertical control memory size =  $256 \times 22$  bits

$$= \frac{256 \times 22}{8} \text{ bytes} = 704 \text{ bytes}$$

# 23. (b)

The required probability =  ${}^{10}\text{C}_3(0.35)^3(0.65)^7 = 0.252$ 

# 24. (b)

Time taken by I/O device = 
$$\frac{16 \text{ MB}}{128 \text{ kB}}$$
 = 128 sec

Percentage time CPU is busy = 
$$\frac{128}{128 + 28} \times 100 = 82.05$$

# 25. (b)

I/O ports are placed at addresses on bus and are accessed just like other memory location in computers that uses memory mapped I/O.

$$Sum = \frac{10001110}{1000001110}$$

$$Z = 0, C = 1, O = 1, S = 0$$

#### 27. (b)

Register = 
$$5 = 3$$
 bits  
Modes =  $14 = 4$  bits

Type	Single operand or No operand	Double operand
Arithmetic (10)	2	8
Logic (15)	9	6
Data moving (20)	12	8
Branch (10)	5	5

Total 27 double operands = 5 bits

Size of instruction word = 5 + 7 + 7 = 19

#### 28. (b)

The device generates  $8 \times 1024 = 8192$  bytes/sec

i.e. 1 second 8192 bytes

for 1 byte 
$$\Rightarrow \frac{1}{8192}$$
sec  
 $\Rightarrow 122 \,\mu$ s

Given that each interrupt consumes  $100 \, \mu s$ .

 $\therefore \text{ Fraction of processor time consumed in } = \frac{100}{122} \text{ (for every byte)} = 0.82$ 

### 29. (a)

Average access time for both read and write operations.

$$\eta_{\text{memory}} \ = \ \frac{1}{61.952} = 161.4 \ \text{Mega words/sec}.$$

#### 30. (c)

- Main disadvantage of direct mapping is that cache hit ratio decreases sharply if two or more frequently used blocks map on to same region.
- Because each and every WRITE operation is done simultaneously on both cache and main memory. WRITE THROUGH results in more cache cycles than WRITE BACK.