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# ENGINEERING MECHANICS

## MECHANICAL ENGINEERING

Date of Test : 13/05/2022

### ANSWER KEY >

- |        |         |         |         |         |
|--------|---------|---------|---------|---------|
| 1. (b) | 7. (b)  | 13. (b) | 19. (c) | 25. (b) |
| 2. (c) | 8. (d)  | 14. (a) | 20. (b) | 26. (c) |
| 3. (d) | 9. (b)  | 15. (a) | 21. (c) | 27. (c) |
| 4. (b) | 10. (c) | 16. (b) | 22. (b) | 28. (b) |
| 5. (b) | 11. (b) | 17. (c) | 23. (d) | 29. (a) |
| 6. (b) | 12. (d) | 18. (c) | 24. (c) | 30. (b) |

## DETAILED EXPLANATIONS

1. (b)

As per given information,

$$h = 40 \text{ m}, u = 50 \text{ m/s}$$

Let the speed be 'v' when it strike to the ground

Apply law of conservation of energy

$$mgh + \frac{1}{2}mu^2 = \frac{1}{2}mv^2$$

$$m \times 10 \times 40 + \frac{1}{2} \times m \times (50)^2 = \frac{1}{2} \times m \times v^2$$

$$400 + 1250 = \frac{v^2}{2}$$

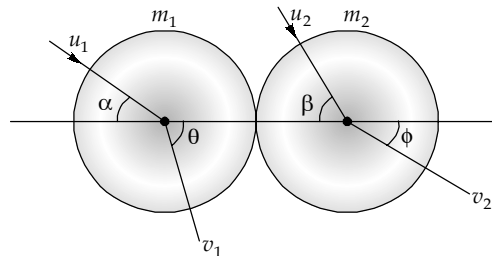
$$v = 57.44 \text{ m/s}$$

2. (c)

Force in member AH should be zero, as the AH is corner member with only two member connected to each other at  $90^\circ$ . Hence in both member AH and GH force is zero.

3. (d)

4. (b)

Sphere of mass  $m_1$  moving with velocity  $u_1$  impinges obliquely on another sphere of mass  $m_2$  moving with velocity  $u_2$  and if the directions of motions before impact make angle  $\alpha$  and  $\beta$  with the common normal.Let  $AB$  be the common normal,  $v_1$  and  $v_2$  be the velocities of the two sphere after impact making angles  $\theta$  and  $\phi$  with the common normal  $AB$  are  $u_1 \cos \alpha$  and  $u_2 \cos \beta$  and after impact  $v_1 \cos \theta$  and  $v_2 \cos \phi$ .

By the principal of conservation of momentum, the total momentum of two spheres along the common normal is unaltered by the impact.

$$\therefore m_1 v_1 \cos \theta + m_2 v_2 \cos \phi = m_1 u_1 \cos \alpha + m_2 u_2 \cos \beta$$

5. (b)

Given : Velocity  $\propto$  Distance i.e.  $\frac{dV}{dt} = -kx$  [where,  $x$  : distance]

$$V = \frac{dx}{dt}$$

$$\text{So, } \frac{d^2x}{dt^2} = -kx$$

$$\frac{dx}{dt} = -kxt + c_1$$

$$x = -kx \frac{t^2}{2} + c_1 t + c_2$$

From above equation, we can see that the distance covered will be quadratic in time.

6. (b)

By work-energy principle,

Work done by friction = Change in kinetic energy

**Case-1:**

From Newton first law,

$$N = mg$$

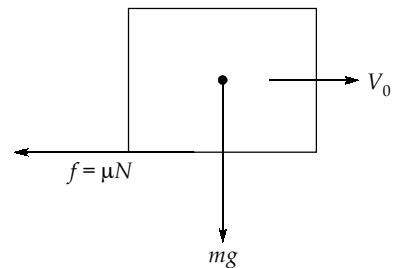
$$f = -\mu mg$$

$$-\mu mgd = 0 - \frac{1}{2} m V_0^2 \quad \dots (i)$$

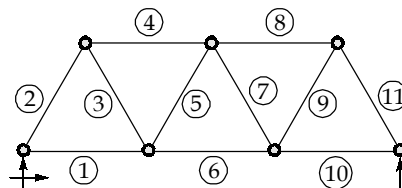
**Case-2:**

$$-\mu mgD = 0 - \frac{1}{2} m (2V_0^2) \quad \dots (ii)$$

Divide II/I, 
$$\frac{D}{d} = \frac{(2V_0)^2}{V_0^2} = 4$$



7. (b)



Total number of member,  $i = 11$

Number of reaction,  $r = 3$

Total number of points =  $2 \times j = 2 \times 7 = 14$

$$i + r = 2j$$

$$11 + 3 = 2 \times 7$$

$$14 = 14$$

Therefore, the truss is stable and internally determinate.

8. (d)

Let  $u, v, w$  be the components of velocity in  $x, y$  and  $z$  direction respectively.

$$u = \frac{dx}{dt} = 2 \cos t$$

Similarly,

$$v = -3 \sin t$$

$$w = \sqrt{5} \cos t$$

$$V = \sqrt{u^2 + v^2 + w^2} = \sqrt{(2 \cos t)^2 + (-3 \sin t)^2 + (\sqrt{5} \cos t)^2}$$

$$V = \sqrt{4 \cos^2 t + 9 \sin^2 t + 5 \cos^2 t}$$

$$V = \sqrt{9(\sin^2 t + \cos^2 t)} = 3 \text{ units}$$

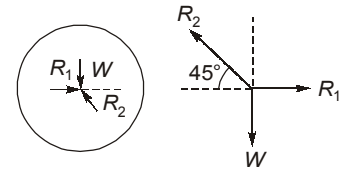
9. (b)

10. (c)

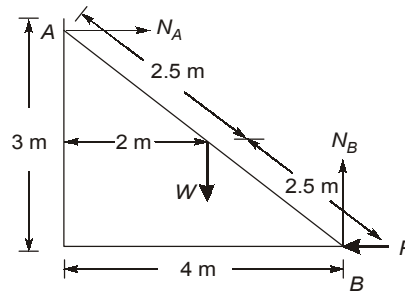
Normal reaction,  $N = 200 - P \sin 30^\circ = 200 - 100 \times 0.5 = 150 \text{ N}$   
 Frictional force,  $F = \mu N = 0.3 \times 150 = 45 \text{ N}$

11. (b)

$$\begin{aligned} R_2 \cos 45^\circ &= R_1 \\ R_2 \sin 45^\circ &= W \\ \Rightarrow R_2 &= W\sqrt{2} \\ \therefore R_1 &= W\sqrt{2} \times \frac{1}{\sqrt{2}} = W \\ W &= 50 \text{ N} \\ \therefore R_1 &= 50 \text{ N} \end{aligned}$$



12. (d)



Considering equilibrium of ladder

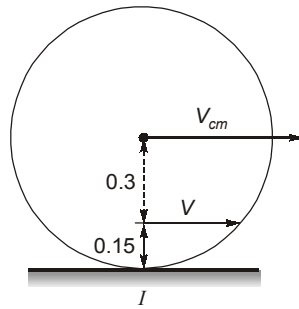
$$\begin{aligned} N_A &= P \\ W &= N_B \\ \Sigma M_B &= 0 \\ N_A \times 3 - W \times 2 &= 0 \\ W &= \frac{N_A \times 3}{2} = \frac{P \times 3}{2} = \frac{400 \times 3}{2} = 600 \text{ N} \end{aligned}$$

$$\begin{aligned} [\because \vec{F}_H = 0] \\ [\because \vec{F}_V = 0] \end{aligned}$$

13. (b)

$$\begin{aligned} I_B &= \frac{mL^2}{3} + \frac{mL^2}{3} = \frac{2mL^2}{3} \\ T &= \frac{mgL}{2} = I_B \alpha \\ \Rightarrow mg \frac{L}{2} &= \frac{2}{3} mL^2 \alpha \\ \alpha &= \frac{3g}{4L} \end{aligned}$$

14. (a)



$$V_{cm} = 0.45 \omega$$

$$\omega = \frac{3}{0.45} \text{ rad/s}$$

$$V = 0.15 \omega = \frac{0.15 \times 3}{0.45}$$

$$V = 1 \text{ m/s}$$

15. (a)

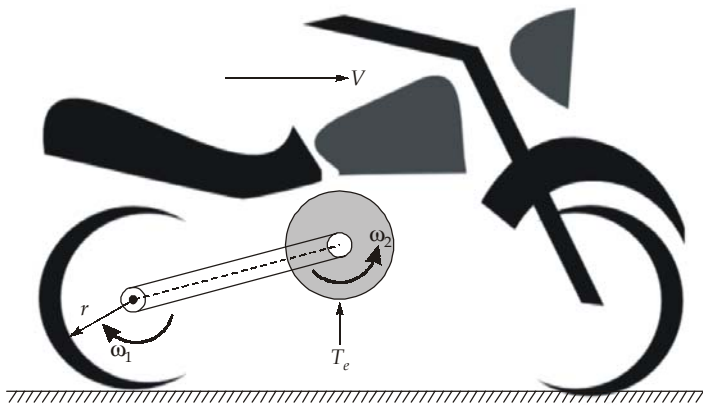


Fig. Actual System

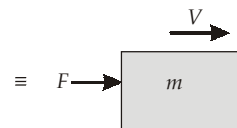


Fig. Equipment System

Here,

$$KE_{\text{equivalent}} = KE_{\text{actual}}$$

$$\frac{1}{2} m' V^2 = \frac{1}{2} m V^2 + 2 \left[ \frac{1}{2} I_w \omega_1^2 \right] + \frac{1}{2} I_e \omega_2^2$$

Where,

$\omega$  = Angular of wheels speed and  $\omega_2 = G\omega_1$  = Angular of engine speed

and

$$\omega_1 = \frac{V}{r}$$

So,

$$\frac{1}{2} m' V^2 = \frac{1}{2} m V^2 + 2 \left[ \frac{1}{2} I_w \left( \frac{V}{r} \right)^2 \right] + \frac{1}{2} I_e (G\omega_1)^2$$

$$\frac{1}{2} m' V^2 = \left[ \frac{1}{2} m + \frac{I_w}{r^2} + \frac{1}{2} I_e \frac{G^2}{r^2} \right] V^2$$

So,

$$m' = m + \frac{2I_w}{r^2} + \frac{I_e}{r^2} G^2$$

16. (b)

As per given information,

$$\begin{aligned}
 m &= 30 \text{ kg}; & r &= 0.2 \text{ m} \\
 \omega &= 20 \text{ rad/s}; & T &= 5 \text{ Nm} \\
 F &= 10 \text{ N}
 \end{aligned}$$

$$I = \frac{1}{2}mr^2 = \frac{1}{2} \times 30 \times 0.2^2 = 0.6 \text{ kg.m}^2$$

Let the disk rotate an angle of  $\theta$  rad.

From work energy principle

$$T \cdot \theta + F \times r \cdot \theta = \frac{1}{2} \times I \times \omega^2 \quad [\because \text{Workdone} = \text{change in energy}]$$

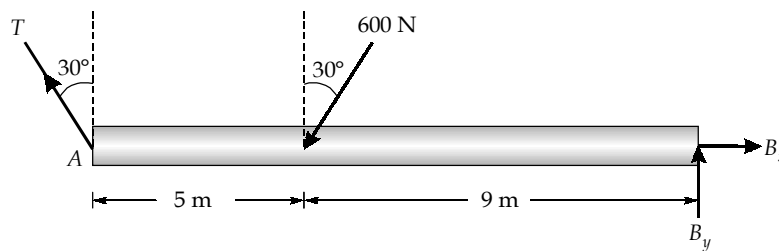
$$5 \cdot \theta + 10 \times 0.2 \times \theta = \frac{1}{2} \times 0.6 \times (20)^2$$

$$7 \cdot \theta = 120$$

$$\theta = 17.14 \text{ rad}$$

$$\text{Number of revolution} = \frac{\theta}{2\pi} = \frac{17.14}{2\pi} = 2.73 \text{ rev}$$

17. (c)

Let  $T$  be the tension in the rope,

The equilibrium equations are:

$$\begin{aligned}
 \Sigma F_x = 0; & & -T \sin 30^\circ - 600 \sin 30^\circ + B_x &= 0 \\
 \Sigma F_y = 0; & & T \cos 30^\circ - 600 \cos 30^\circ + B_y &= 0 \\
 \Sigma M_B = 0; & & (600 \cos 30^\circ)9 - (T \cos 30^\circ)14 &= 0
 \end{aligned}$$

By solving above three equation,

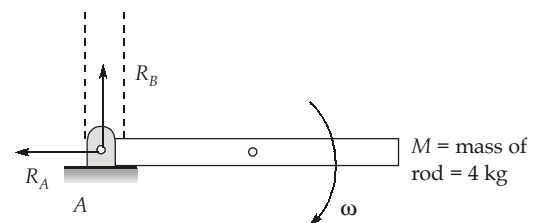
we get  $T = 386 \text{ N}$ ,  $B_x = 493 \text{ N}$ ,  $B_y = 186 \text{ N}$ 

Note : Calculation steps are left for students.

18. (c)

$$\frac{1}{2} \times \frac{ML^2}{3} \times \omega^2 = \frac{MgL}{2}$$

$$\Rightarrow \frac{L}{3} \times \omega^2 = g = \omega = \sqrt{\frac{3g}{L}}$$



$$\text{Horizontal force balance} \Rightarrow R_A = M\omega^2 \frac{L}{2}$$

$$\Rightarrow R_A = M \frac{3g}{L} \times \frac{L}{2} = \frac{3Mg}{2} = R_A = 58.86 \text{ N}$$

Vertical force balance

$$Mg - R_B = Ma$$

$$a = \frac{\alpha L}{2}$$

$$\Rightarrow \Sigma \tau_{\text{net}_A} = I \alpha$$

$$Mg \times \frac{L}{2} = \frac{ML^2}{3} \times \alpha$$

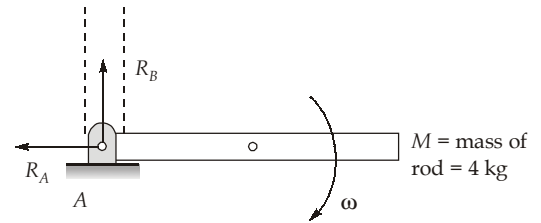
$$\alpha = \frac{3g}{2L}$$

So, 
$$a = \alpha \frac{L}{2} = \frac{3g}{4}$$

$$Mg - Ma = R_B$$

$$\Rightarrow R_B = \frac{Mg}{4} = 9.81 \text{ N}$$

$$\Rightarrow R_{\text{Net}} = \sqrt{R_A^2 + R_B^2} = 59.67 \text{ N}$$



19. (c)

Initial momentum of bullet and block = Final momentum of bullet and block

$$m_1 V_1 + m_2 \times 0 = (m_1 + m_2) \times V$$

$$V = \left( \frac{m_1}{m_1 + m_2} \right) V_1 = \left( \frac{25}{25 + 520} \right) \times 180 = 8.26 \text{ m/s}$$

By work energy principle:

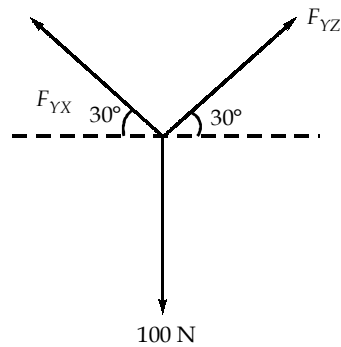
Final KE - Initial KE = Work done

$$\frac{1}{2} m V^2 - 0 = \mu \times Mgx$$

$$\mu = \frac{V^2}{2gx}$$

$$= \frac{(8.26)^2}{2 \times 9.8 \times 8.2} = 0.4245$$

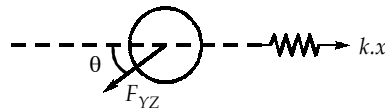
20. (b)  
From sine rule,



$$\frac{100}{\sin 120^\circ} = \frac{F_{YZ}}{\sin 120^\circ}$$

$$F_{YZ} = F_{YZ} = 100 \text{ N}$$

FBD



$$F_{YZ} \cos 30^\circ = k.x$$

$$100 \times \frac{\sqrt{3}}{2} = 10 \times 10^3 .x$$

$$x = \frac{100 \times \sqrt{3} \times 1000}{2 \times 10 \times 10^3} \text{ mm}$$

$$x = 5\sqrt{3} \text{ mm}$$

21. (c)

$$a = \frac{dv}{dt}$$

Let resisting force,

$$\Rightarrow F = Kv^2$$

Let  $m$  is mass of bullet

$$\therefore a = \frac{F}{m} = \frac{Kv^2}{m}$$

$$\frac{dv}{dt} = \frac{Kv^2}{m}$$

$$\frac{1}{v^{-2}} dv = \frac{K}{m} dt$$

$$\left[ \frac{v^{-1}}{-1} \right]_u^v = \frac{K}{m} \int_0^t dt$$

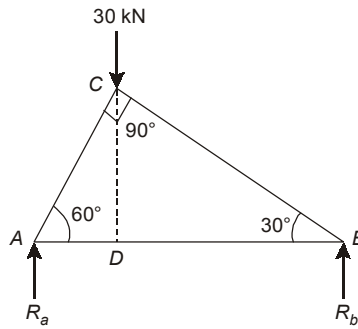
$$\Rightarrow \left[ \frac{v-u}{uv} \right] = \frac{K}{m} t$$

$$\Rightarrow t = \frac{(u-v)}{uv} \times \frac{-m}{K}$$

$$\therefore t \propto (u-v)(uv)^{-1}$$



22. (b)



$$AC = AB \cos 60^\circ = 2.5 \text{ m}$$

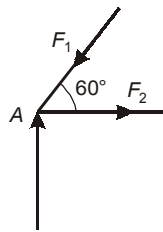
$$AD = AC \cos 60^\circ = 2.5 \times 0.5 = 1.25$$

∴ Taking moments about A,

$$R_b \times 5 = 30 \times 1.25$$

$$R_b = 7.5 \text{ kN}, \quad R_a = 30 - 7.5 = 22.5 \text{ kN}$$

Considering joint A,



$$\sum F_x = 0, \quad F_2 - F_1 \cos 60^\circ = 0$$

$$F_1 \sin 60^\circ - R_a = 0$$

$$F_1 = \frac{R_a}{\sin 60^\circ} = \frac{22.5}{\sin 60^\circ} = 25.97 \text{ kN} \quad (\text{compressive})$$

$$F_2 = F_1 \cos 60^\circ = 12.99 \text{ kN} \quad (\text{tensile})$$

∴ AB is in tension.

23. (d)

For no tipping or prevent overturning

$$Ph < \frac{Wb}{2}$$

where

$W \rightarrow$  weight of block

and

$b \rightarrow$  width of block

$$h < \frac{Wb}{2P} \quad \dots(1)$$

and for slipping without tipping

$$P > f(\text{force of friction})$$

$$P > \mu W \quad \dots(2)$$

From (1) and (2)

$$h < \frac{b}{2\mu}$$

$$\therefore h < \frac{60}{0.6}$$

$$\therefore h < 100 \text{ mm}$$

Option (d) is correct.

24. (c)

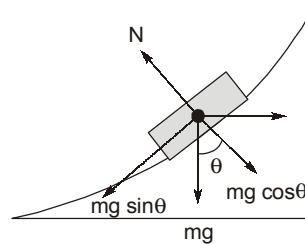
$$\begin{aligned} \text{Resistance} &= mg + W = 200 \times 9.81 + 100 \\ &= 2062 \text{ N} \end{aligned}$$

$$\therefore a = \frac{2062}{200}$$

$$a = 10.31 \text{ m/s}^2$$

$$\frac{V^2}{2a} = S = \frac{4^2}{2 \times 10.31} = 0.776 \text{ m}$$

25. (b)



$$\tan \theta = \frac{dy}{dx} = \frac{x^2}{2}$$

$$\text{Now, } mg \sin \theta = \mu mg \cos \theta$$

$$\Rightarrow \tan \theta = \mu$$

$$\Rightarrow \frac{x^2}{2} = 0.5$$

$$\Rightarrow x = 1$$

$$y = \frac{1}{6} \text{ m}$$

26. (c)

$$\Sigma F_x = 0$$

$$T_1 \cos 45^\circ + 100 \cos 30^\circ = T_2 \cos 60^\circ + 100$$

$$\Sigma F_y = 0$$

$$\therefore T_1 \sin 45^\circ + T_2 \sin 60^\circ = 100 \sin 30^\circ$$

$$\Rightarrow 0.707 T_1 + 86.602 = 0.5 T_2 + 100$$

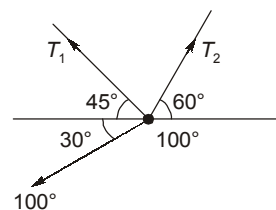
$$\Rightarrow 0.707 T_1 - 0.5 T_2 = 13.398$$

$$0.707 T_1 + 0.866 T_2 = 50$$

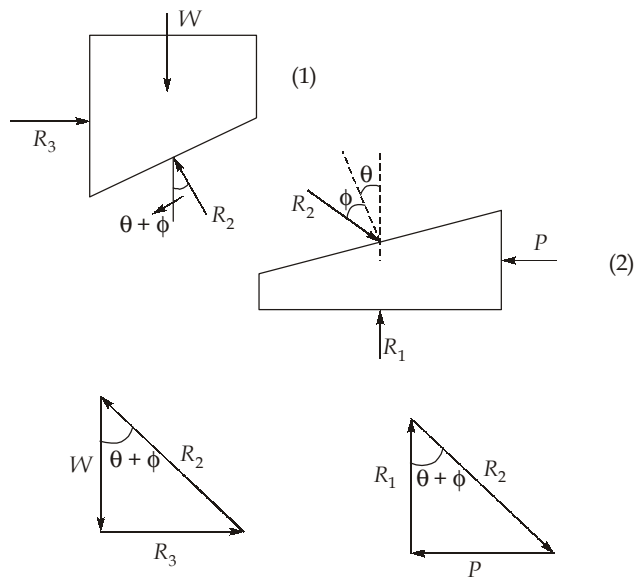
$$T_1 = 37.9 \text{ N}$$

$$T_2 = 26.795$$

$$\therefore T_1/T_2 = 1.414$$



27. (c)



$$\cos(\theta + \phi) = \frac{W}{R_2}, \quad \sin(\theta + \phi) = \frac{P}{R_2}$$

$$\frac{P}{W} = \tan(\theta + \phi)$$

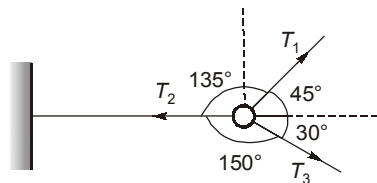
$$P = W \tan(\theta + \phi)$$

$$= 500 \tan(\theta + \phi)$$

$$\phi = \tan^{-1} 0.20 = 11.309$$

$$P = 500 \tan(15 + 11.309) = 247.21 \text{ N}$$

28. (b)



∴ Applying Lami's theorem as the disc is in equilibrium,

$$\frac{T_1}{\sin 150^\circ} = \frac{T_2}{\sin 75^\circ} = \frac{T_3}{\sin 135^\circ}$$

$$\therefore \frac{T_1}{T_2} = \frac{\sin 150^\circ}{\sin 75^\circ} = 0.517$$

29. (a)

Reaction at A is  $R_A$

Taking moments from point E,

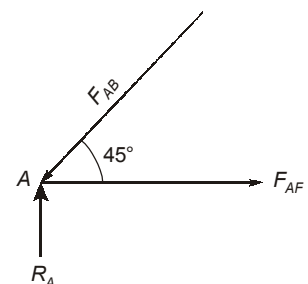
$$W \times \frac{a}{2} + Wa = 2a \cdot R_A$$

$$\therefore R_A = 0.75 W$$

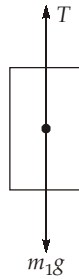
Joint A

$$F_{AB} \sin 45^\circ = R_A$$

$$F_{AB} = 1.06 W \text{ (compressive)}$$



30. (b)  
Cylinder

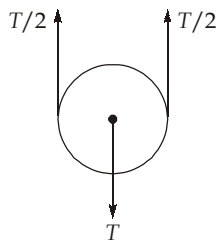


From Newton's first law,

$$m_1g - T = 0$$

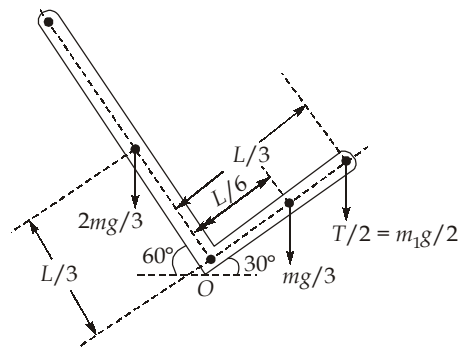
$$T = m_1g$$

Pulley



$$\frac{T}{2} = \frac{m_1g}{2}$$

To cause loss of contact at A, reaction at A will be zero.



$$\Sigma M_o = 0$$

$$\frac{2mg}{3} \times \frac{L}{3} \cos 60^\circ - \frac{mg}{3} \times \frac{L}{6} \cos 30^\circ - \frac{T}{2} \times \frac{L}{3} \cos 30^\circ = 0$$

$$\Rightarrow \frac{2mg}{9} gL \cos 60^\circ = \frac{m}{18} gL \cos 30^\circ + \frac{m_1g}{2} \times \frac{L}{3} \cos 30^\circ$$

$$\Rightarrow \frac{2m}{9} \cos 60^\circ = \frac{m}{18} \cos 30^\circ + \frac{m_1}{6} \cos 30^\circ$$

$$m_1 = 0.436 m$$

