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SIGNAL & SYSTEM

EC-EE

Date of Test: 15/07/2026

ANSWER KEY ➤

- | | | | | |
|--------|---------|---------|---------|---------|
| 1. (d) | 7. (d) | 13. (b) | 19. (b) | 25. (b) |
| 2. (b) | 8. (c) | 14. (a) | 20. (d) | 26. (d) |
| 3. (a) | 9. (d) | 15. (c) | 21. (a) | 27. (d) |
| 4. (c) | 10. (a) | 16. (d) | 22. (a) | 28. (b) |
| 5. (c) | 11. (b) | 17. (b) | 23. (d) | 29. (b) |
| 6. (d) | 12. (b) | 18. (a) | 24. (c) | 30. (c) |

DETAILED EXPLANATIONS

1. (d)

$$2^n u[n] \xleftrightarrow{z} \frac{1}{1 - 2z^{-1}}$$

$$\therefore \text{ROC} \Rightarrow |z| > 2$$

$$\text{and } (4)^n u[-n - 1] \xleftrightarrow{z} \frac{1}{1 - 4z^{-1}}$$

$$\therefore \text{ROC} \Rightarrow |z| < 4$$

$\therefore$ for the signal to converge

$$\text{ROC} \Rightarrow 2 < |z| < 4$$

2. (b)

$$y[n] = x[n] * \delta[n - 2] = x[n - 2]$$

$$\therefore y[2] = x[0] = 1$$

3. (a)

$$\text{Re} \{x(t)\} = \frac{x(t) + x^*(t)}{2}$$

$\therefore$ The Fourier coefficient of $x^*(t)$ are

$$b_K = \frac{1}{T} \int_T x^*(t) e^{-jK \frac{2\pi}{T} t} dt$$

Taking conjugate on both sides

$$b_K^* = \frac{1}{T} \int_T x(t) e^{-j(-K) \frac{2\pi}{T} t} dt$$

$$\therefore a_{-K} = b_K^*$$

$$\therefore \text{Fourier series Coefficient of } \text{Re} \{x(t)\} = \frac{a_K + a_{-K}^*}{2}$$

4. (c)

From the given figure of $x(t)$ and $y(t)$, we get conclude that,

$$x(0) = y(5)$$

$$\text{at } t = 5 \text{ sec, } y(5) = x(-5a + 20) = x(0)$$

$$\therefore -5a + 20 = 0$$

$$\therefore a = 4$$

5. (c)

We know that the Laplace transform of

$$\cos(at)u(t) = \frac{s}{s^2 + a^2}$$

$$\therefore \cos(\pi t)u(t) = \frac{s}{s^2 + \pi^2}$$

now, the given function $x(t)$ can be written as,

$$\begin{aligned} &= \cos \pi t [u(t) - u(t-1)] \\ &= \cos(\pi t)u(t) - \cos \pi t u(t-1) \\ &= \cos \pi t u(t) - \cos \pi(t-1+1)u(t-1) \\ &= \cos \pi t u(t) - \cos[\pi(t-1) + \pi]u(t-1) \\ x(t) &= \cos(\pi t)u(t) + \cos[\pi(t-1)]u(t-1) \end{aligned}$$

By taking Laplace transform,

$$X(s) = \frac{s}{s^2 + \pi^2} + \frac{s e^{-s}}{s^2 + \pi^2} \quad [\because x(t-t_0) = X(s) \cdot e^{-st_0}, \text{ by shifting property}]$$

$$X(s) = \frac{s[1 + e^{-s}]}{s^2 + \pi^2}$$

6. (d)

Let us consider two signals,

$$x_1(t) = 1, \quad \forall t$$

$$x_2(t) = -1, \quad \forall t$$

Clearly $x_1(t) \neq x_2(t)$ but $(x_1(t))^2 = (x_2(t))^2$

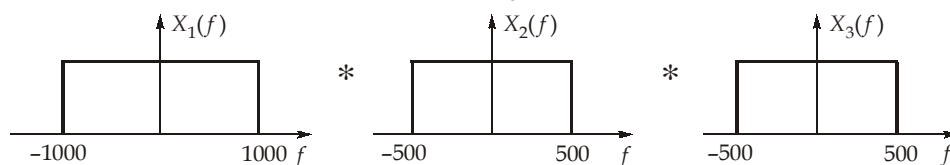
Therefore different inputs gives the same output hence the system is non invertible.

And also it is non linear system.

7. (d)

We know that,

$$\text{For } X(f) = X_1(f) * X_2(f) * X_3(f)$$



$$\begin{aligned} \text{Sampling frequency, } f_s &= 2(1000 + 500 + 500) \\ f_s &= 4000 \text{ samples/sec} \end{aligned}$$

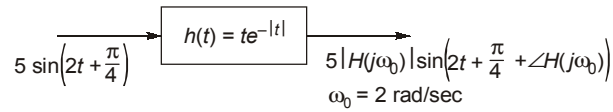
8. (c)

Conjugate anti-symmetric part of $x[n]$ is $\frac{x[n] - x^*[-n]}{2}$.

$$x^*[-n] = [2, 1 + j, -2 + j5]$$

$$\therefore \frac{x[n] - x^*[-n]}{2} = \frac{[-2 - j5, 1 - j, 2] - [2, (1 + j), -2 + j5]}{2} = [-2 - j2.5, -j, 2 - j2.5]$$

9. (d)



$$h(t) = te^{-|t|}$$

$$H(j\omega) = j \frac{d}{d\omega} \left(\frac{2}{1 + \omega^2} \right) = \frac{-4j\omega}{(1 + \omega^2)^2}$$

$$|H(j\omega_0)| = \left| \frac{-4j(2)}{(1 + 4)^2} \right| = \frac{8}{25} \quad (\omega_0 = 2 \text{ rad/sec})$$

$$\angle H(j\omega_0) = -90^\circ$$

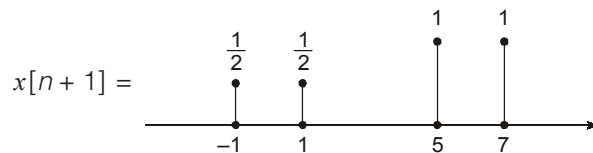
$$\text{output} = 5 \times \frac{8}{25} \sin\left(2t + \frac{\pi}{4} - \frac{\pi}{2}\right) = \frac{8}{5} \sin\left(2t - \frac{\pi}{4}\right)$$

$$= \frac{8}{5} \left(\frac{\sin 2t}{\sqrt{2}} - \frac{\cos 2t}{\sqrt{2}} \right)$$

$$= \frac{8}{5\sqrt{2}} (\sin 2t - \cos 2t)$$

$$= 1.13 (\sin 2t - \cos 2t)$$

10. (a)



$$\begin{aligned} \Rightarrow x[2n+1] &= 0 \\ \Rightarrow nx[2n+1] &= y[n] = 0 \\ \Rightarrow \sum_{n=-\infty}^{\infty} y[n] &= 0 \end{aligned}$$

11. (b)

$$Y(e^{j\omega}) = X(e^{j\omega}) * X(e^{j\omega - \pi/2})$$

$\therefore$ In time domain

$$Y(e^{j\omega}) = 2\pi x_1[n] \cdot x_2[n]$$

now, If $X(e^{j\omega}) \longleftrightarrow n \left(\frac{3}{4} \right)^{|n|}$

Then $X(e^{j\omega - \pi/2}) \longleftrightarrow n \cdot e^{j\pi/2} \left(\frac{3}{4} \right)^{|n|}$

$$\therefore y[n] \longleftrightarrow 2\pi n^2 e^{j\pi n/2} \left(\frac{3}{4}\right)^{2|n|}$$

12. (b)

$$X(z) = \frac{z}{z-1} \quad |z| > 1$$

$$Y(z) = \frac{2z}{z - \frac{1}{3}} \quad |z| > \frac{1}{3}$$

$$H(z) = \frac{2(z-1)}{z - \frac{1}{3}} \quad |z| > \frac{1}{3}$$

$$X'(z) = \frac{z}{z - \frac{1}{2}} \quad |z| > \frac{1}{2}$$

$$Y'(z) = H(z) \cdot X'(z)$$

$$= \frac{2z(z-1)}{\left(z - \frac{1}{2}\right)\left(z - \frac{1}{3}\right)} \quad |z| > \frac{1}{2}$$

Taking inverse z transform

$$y[n] = \left[-6\left(\frac{1}{2}\right)^n + 8\left(\frac{1}{3}\right)^n \right] u[n]$$

$$k_1 = -6, \quad k_2 = 8$$

$$\text{so,} \quad k_1 + k_2 = 2$$

13. (b)

If $x[n]$ is real

$$\text{odd}[x[n]] \xrightarrow{FT} j \text{Im}[X(e^{j\omega})]$$

$$\begin{aligned} \therefore \text{odd}[x[n]] &= F^{-1} \left[\frac{1}{2} (e^{j\omega} - e^{-j\omega} - e^{2j\omega} + e^{-2j\omega}) \right] \\ &= \frac{1}{2} [\delta[n+1] - \delta[n-1] - \delta[n+2] + \delta[n-2]] \end{aligned}$$

$$\therefore \text{odd}[x[n]] = \frac{x[n] - x[-n]}{2}$$

Since,

$$x[n] = 0 \text{ for } n > 0$$

$$x[n] = 2 \text{ odd}[x[n]]$$

$$= \delta[n+1] - \delta[n+2] \text{ for } n < 0$$

using parshel's theorem

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} |X(e^{j\omega})|^2 d\omega = \sum_{n=-\infty}^{\infty} |x[n]|^2$$

$$(x[0])^2 - 2 = 3$$

$$x[0] = \pm 1$$

$\therefore$

$$x[0] > 0$$

$\therefore$

$$x[n] = \delta[n] + \delta[n+1] - \delta[n+2]$$

14. (a)

$$x[n] = \delta[n]$$

$$X(e^{j\omega}) = 1$$

$$\frac{dX(e^{j\omega})}{d\omega} = 0$$

$\therefore$

$$Y(e^{j\omega}) = e^{-j\omega} X(e^{j\omega})$$

$$h[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{-j\omega} \cdot e^{j\omega n} d\omega = \frac{\sin \pi(n-1)}{\pi(n-1)}$$

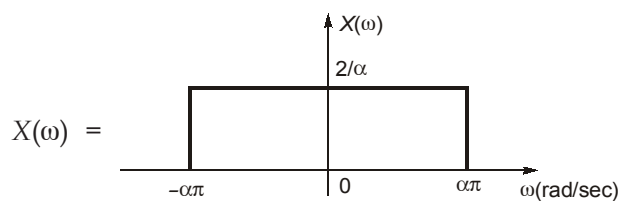
15. (c)

We know that,

Energy,

$$E = \int_{-\infty}^{\infty} x^2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega$$

Now,



$$E = \frac{1}{2\pi} \int_{-\alpha\pi}^{\alpha\pi} \left| \frac{2}{\alpha} \right|^2 d\omega$$

$$0.5 = \frac{1}{2\pi} \times \frac{4}{\alpha^2} [2\alpha\pi]$$

$$0.5 = \frac{4}{\alpha}$$

$\therefore$

$$\alpha = 8$$

16. (d)

Given,

$$x[n] = \cos \frac{\pi}{4} n + \sin \left(\frac{\pi}{3} n + \frac{1}{2} \right)$$

Let

$$x[n] = x_1[n] + x_2[n]$$

Let N_1 be the period of $x_1[n]$.

$$\frac{\pi/4}{2\pi} = \frac{m}{N_1}$$

$\Rightarrow$

$$N_1 = 8$$

Let N_2 be the period of $x_2[n]$.

$$\frac{\pi/3}{2\pi} = \frac{m}{N_2}$$

$\Rightarrow$

$$N_2 = 6$$

Overall time period, $N = \text{LCM}(N_1, N_2) = \text{LCM}(6, 8)$

$$\therefore N = 24$$

17. (b)

Given,
$$X(z) = \frac{1}{1 - 2.5z^{-1} + z^{-2}} = \frac{1}{(z^{-1} - 2)\left(z^{-1} - \frac{1}{2}\right)}$$

$$\frac{1}{(z^{-1} - 2)\left(z^{-1} - \frac{1}{2}\right)} = \frac{A}{z^{-1} - 2} + \frac{B}{z^{-1} - \frac{1}{2}}$$

$$\therefore A = \frac{1}{2 - \frac{1}{2}} = \frac{1}{3/2} = \frac{2}{3}$$

$$B = \frac{1}{\frac{1}{2} - 2} = -\frac{2}{3}$$

$$\begin{aligned} \therefore X(z) &= \frac{\frac{2}{3}}{z^{-1} - 2} + \frac{-\frac{2}{3}}{z^{-1} - \frac{1}{2}} \\ &= \frac{-\frac{1}{3}}{1 - \frac{1}{2}z^{-1}} + \frac{\frac{4}{3}}{1 - 2z^{-1}} \end{aligned}$$

Given $X(z)$ is a causal system, the ROC is right of the right most pole.

$$\therefore |z| > 2$$

hence,
$$x[n] = -\frac{1}{3}\left(\frac{1}{2}\right)^n u[n] + \frac{4}{3}(2)^n u[n]$$

$$\therefore x(0) = -\frac{1}{3} + \frac{4}{3} = \frac{3}{3} = 1$$

18. (a)

Given,
$$\begin{aligned} X(e^{j\omega}) &= \frac{\sin \frac{3\omega}{2}}{\sin \frac{\omega}{2}} = \frac{e^{j3\omega/2} - e^{-j3\omega/2}}{e^{j\omega/2} - e^{-j\omega/2}} = \frac{e^{j3\omega/2} [1 - e^{-j3\omega}]}{e^{j\omega/2} [1 - e^{-j\omega}]} \\ &= e^{j\omega} \left[\frac{1 - e^{-j3\omega}}{1 - e^{-j\omega}} \right] \end{aligned}$$

$$X(e^{j\omega}) = \frac{e^{j\omega}}{1 - e^{-j\omega}} - \frac{e^{-j2\omega}}{1 - e^{-j\omega}}$$

by taking inverse DTFT,

$$\begin{aligned} x[n] &= u[n+1] - u[n-2] \\ &= \begin{cases} 1; & -1 \leq n < 2 \\ 0; & \text{otherwise} \end{cases} \end{aligned}$$

From parseval's theorem,

$$\sum_{n=-\infty}^{\infty} |nx[n]|^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} \left| \frac{d}{d\omega} X(e^{j\omega}) \right|^2 d\omega$$

$$\begin{aligned} \therefore \frac{1}{\pi} \int_{-\pi}^{\pi} \left| \frac{d}{d\omega} X(e^{j\omega}) \right|^2 d\omega &= 2 \sum_{n=-\infty}^{\infty} |nx[n]|^2 d\omega \\ &= 2 \sum_{n=-1}^1 |n|^2 = 2[1+0+1] = 4 \end{aligned}$$

$$\frac{1}{\pi} \int_{-\pi}^{\pi} \left| \frac{d}{d\omega} X(e^{j\omega}) \right|^2 d\omega = 4$$

19. (b)

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N} nK}$$

$$g[n] = x[n-2]_{\text{mod } N}$$

$$G[k] = e^{-j\frac{2\pi}{N}(2)k} X[k]$$

$$G[1] = e^{-j\frac{2\pi}{4}(2)1} X[1] = e^{-j\pi} X[1]$$

$$G[1] = -X[1] = -7$$

20. (d)

Given pole-zero plot can be written as,

$$X(z) = \frac{(z-1)(z+1)}{z^2} = \frac{z^2-1}{z^2} = 1 - z^{-2}$$

put $z = e^{j\omega}$,

$$|X(e^{j\omega})| = |1 - \cos 2\omega + j \sin 2\omega|$$

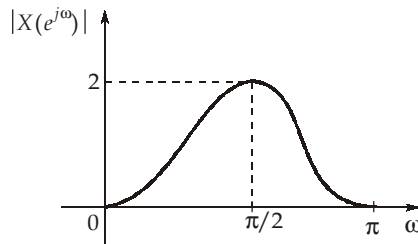
$$|X(e^{j\omega})| = |\sqrt{2-2\cos 2\omega}|$$

$$\text{put, } \omega = 0 \Rightarrow |X(e^{j\omega})| = 0$$

$$\omega = \pi/2 \Rightarrow |X(e^{j\pi/2})| = 2$$

$$\omega = \pi \Rightarrow |X(e^{j\pi})| = 0$$

It is a bandpass filter response,



If poles are moved towards $\pm \frac{\pi}{2}$

Suppose we take poles are at $z = \pm j0.5$

$$X(z) = \frac{(z+1)(z-1)}{(z+j0.5)(z-j0.5)}$$

still response will remain same as BPF.

Because of zeros at the same position.

21. (a)

By the definition of Fourier series,

We can write $C_{N_0/2}$ for N_0 is even,

$$\begin{aligned} C_{N_0/2} &= \frac{1}{N_0} \sum_{n=0}^{N-1} x[n] e^{-j\left(\frac{N_0}{2}\right)\left(\frac{2\pi}{N_0}\right)n} \\ &= \frac{1}{N_0} \sum_{n=0}^{N-1} x[n] e^{-j\pi n} = \frac{1}{N_0} \sum_{n=0}^{N-1} (-1)^n x[n] = \text{real} \end{aligned}$$

22. (a)

The difference equation is,

$$y[n] + 0.5 y[n-1] = x[n]$$

Characteristic equation,

$$\lambda + 0.5 = 0, \quad \text{root, } \lambda = -0.5$$

$$y_H[n] = C_1(-0.5)^n$$

$$y_p[n] = K$$

$$K + 0.5 K = 1$$

$$\Rightarrow K = \frac{2}{3}$$

$$\text{So, } y_p[n] = \frac{2}{3} u[n]$$

Complete response,

$$\begin{aligned} y[n] &= y_h[n] + y_p[n] \\ &= C_1(-0.5)^n + \frac{2}{3} \end{aligned}$$

Using given initial conditions,

$$y[-1] = C_1(-0.5)^{-1} + \frac{2}{3} = 0$$

$$\Rightarrow C_1 = \frac{1}{3}$$

$$\text{and, } y[n] = \left[\frac{1}{3} \left(\frac{-1}{2} \right)^n + \frac{2}{3} \right] u[n]$$

Alternative Solution:

$$x[n] = 0.5y[n-1] + y[n]$$

Taking z-transform,

$$X(z) = Y(z) + 0.5[z^{-1}Y(z) + 0]$$

$$\Rightarrow \text{Put, } X(z) = \frac{z}{z-1} \quad [\because x[n] = u(n)]$$

$$Y(z) = \frac{z}{(z-1)(z+0.5)}$$

by partial fraction method,

$$\frac{A}{(z+0.5)} + \frac{B}{(z-1)} = \frac{z}{(z-1)(z+0.5)}$$

$$\text{Solving, } A = \frac{1}{3},$$

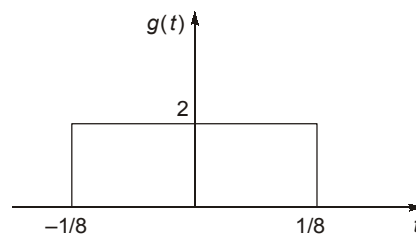
$$B = \frac{2}{3}$$

$$\text{Hence, } y[n] = \left[\frac{1}{3}[-0.5]^n + \frac{2}{3} \right] u[n]$$

23. (d)

$$\begin{aligned} g(t) &= \text{rect}(4t) * 4\delta(-2t) \\ &= 4 \text{rect}(4t) * \delta(-2t) \quad (\because \delta(-t) = \delta(t)) \\ &= 2 \text{rect}(4t) \quad \left(\because \delta(at) = \frac{1}{|a|} \delta(t) \right) \end{aligned}$$

thus $g(t)$ is given as



now,

$$\text{rect}(t) \xrightarrow{F.T} \text{sinc}(f)$$

$$2\text{rect}(t) \xrightarrow{F.T} 2\text{sinc}(f)$$

$$2\text{rect}(4t) \xrightarrow{F.T} 2 \cdot \frac{1}{4} \text{sinc}\left(\frac{f}{4}\right) \quad (\text{scaling property})$$

$$\therefore 2\text{rect}(4t) \xrightarrow{F.T} \frac{1}{2} \text{sinc}\left(\frac{f}{4}\right)$$

24. (c)

Given that,

Let, $y_1(t) = 2\pi X(-\omega)|_{\omega=t}$

We have, $y_1(t) = 2\pi \int_{u=-\infty}^{\infty} x(u)e^{jut} du$

Similarly, let $y_2(t)$ be the output due to passing $x(t)$ through 'F' twice.

$$y_2(t) = 2\pi \int_{v=-\infty}^{\infty} 2\pi \int_{u=-\infty}^{\infty} x(u)e^{juv} du e^{jt v} dv$$

$$= (2\pi)^2 \int_{u=-\infty}^{\infty} x(u) \int_{v=-\infty}^{\infty} e^{j(t+u)v} dv du$$

$$= (2\pi)^2 \int_{u=-\infty}^{\infty} x(u)(2\pi)\delta(t+u) du$$

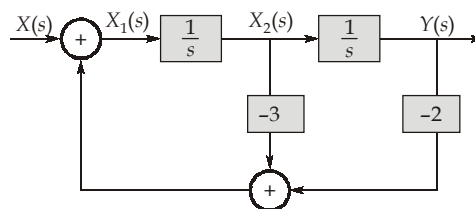
$$= (2\pi)^3 X(-t)$$

Finally, let $y_3(t)$ be the output due to passing $x(t)$ through F three times

$$y_3(t) = 2\pi \int_{u=-\infty}^{\infty} (2\pi)^3 x(-u)e^{jtu} du$$

$$= (2\pi)^4 \int_{-\infty}^{\infty} e^{-jtu} x(u) du = (2\pi)^4 X(t)$$

25. (b)



now, $Y(s) = \frac{X_2(s)}{s},$

$$X_2(s) = \frac{X_1(s)}{s}$$

now, $X_1(s) = X(s) - 2Y(s) - 3X_2(s)$

$$s^2 Y(s) = X(s) - 3sY(s) - 2Y(s)$$

$$(s^2 + 3s + 2)Y(s) = X(s)$$

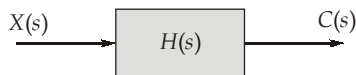
$$\frac{Y(s)}{X(s)} = \frac{1}{s^2 + 3s + 2} = \frac{1}{(s+1)(s+2)}$$

$$\frac{Y(s)}{X(s)} = \frac{1}{s+1} - \frac{1}{s+2}$$

26. (d)

Let, the given transfer function,

$$H(s) = \frac{b(s+a)}{(s+b)}$$



where, $X(s) = \frac{1}{s}$ ($\because$ unit step response)

$$C(s) = X(s)H(s) = \frac{b(s+a)}{s(s+b)}$$

Given, $c(0) = 2$

$$\Rightarrow \lim_{s \rightarrow \infty} s \cdot \frac{b(s+a)}{s(s+b)} = 2$$

$$b = 2$$

and $c(\infty) = 8$

$$\Rightarrow \lim_{s \rightarrow 0} s \cdot \frac{b(s+a)}{s(s+b)} = 8$$

$$a = 8$$

now, $\frac{a}{b} = \frac{8}{2} = 4$

27. (d)

We know that

$$FT[e^{-t}u(t)] = \frac{1}{1+j\omega}$$

Using duality property

$$x(t) \xleftrightarrow{FT} X(\omega)$$

$$X(t) \xleftrightarrow{FT} 2\pi x(-\omega)$$

we have

$$FT\left[\frac{1}{1+jt}\right] \xleftrightarrow{FT} 2\pi e^{-(\omega)} u(-\omega)$$

$$\xleftrightarrow{FT} 2\pi e^{\omega} u(-\omega)$$

Using the time reversal property,

i.e. $x(-t) = X(-\omega)$, we have

$$FT\left[\frac{1}{1-jt}\right] \xleftrightarrow{FT} 2\pi e^{-\omega} u(\omega)$$

$$\therefore e^{-\omega} u(\omega) \xleftrightarrow{IFT} \frac{1}{2\pi} FT \left[\frac{1}{1-jt} \right]$$

$$\therefore FT^{-1} [e^{-\omega} u(\omega)] = \frac{1}{2\pi(1-jt)}$$

28. (b)

Given, $X(s) = \ln \left[1 + \frac{\omega^2}{s^2} \right]$

Let $x(t) = L^{-1} [X(s)] = L^{-1} \left[\ln \left(1 + \frac{\omega^2}{s^2} \right) \right]$

$$\begin{aligned} \therefore L[x(t)] &= \ln \left[1 + \frac{\omega^2}{s^2} \right] = \ln \left[\frac{s^2 + \omega^2}{s^2} \right] \\ &= \ln[s^2 + \omega^2] - \ln s^2 \end{aligned}$$

$$\begin{aligned} L[tx(t)] &= \frac{-d}{ds} [\ln(s^2 + \omega^2) - \ln s^2] \\ &= \frac{-1}{s^2 + \omega^2} \cdot 2s + \frac{1}{s^2} 2s = \frac{2}{s} - \frac{2s}{s^2 + \omega^2} \end{aligned}$$

$$\begin{aligned} \therefore tx(t) &= L^{-1} \left[\frac{2}{s} - \frac{2s}{s^2 + \omega^2} \right] \\ &= (2 - 2\cos\omega t)u(t) = 2(1 - \cos\omega t)u(t) \end{aligned}$$

$$\therefore x(t) = \frac{2(1 - \cos\omega t)}{t} u(t)$$

29. (b)

$$Y(z) = X(z) \cdot H(z)$$

for unit step input, $X(z) = \frac{1}{1-z^{-1}}$ ($\because x[n] = \text{unit step}$)

$$\therefore Y(z) = \frac{z^3}{(z-1)\left(z-\frac{1}{2}\right)\left(z-\frac{1}{4}\right)}$$

$$\frac{Y(z)}{z} = \frac{C_1}{z-1} + \frac{C_2}{z-\frac{1}{2}} + \frac{C_3}{z-\frac{1}{4}}$$

$$C_1 = \left. \frac{z^2}{\left(z-\frac{1}{4}\right)\left(z-\frac{1}{2}\right)} \right|_{z=1} = \frac{8}{3}$$

$$C_2 = \frac{z^2}{(z-1)\left(z-\frac{1}{4}\right)} \bigg|_{z=\frac{1}{2}} = -2$$

$$C_3 = \frac{z^2}{(z-1)\left(z-\frac{1}{2}\right)} \bigg|_{z=\frac{1}{4}} = \frac{1}{3}$$

$$\therefore Y(z) = \frac{8}{3} \frac{z}{z-1} - 2 \frac{z}{z-\frac{1}{2}} + \frac{1}{3} \frac{z}{z-\frac{1}{4}}$$

Taking inverse z-transform,

$$y[n] = \frac{1}{3} \left[8 - 6 \left(\frac{1}{2} \right)^n + \left(\frac{1}{4} \right)^n \right] u[n]$$

30. (c)

- Linear in $x[n]$
- Upper limit of summation operator is a function of $n \Rightarrow$ Time variant
- $n^2 > n \Rightarrow$ non causal
- When $x[n]$ is bounded, $y[n]$ is also bounded $\Rightarrow$ Stable

■■■■