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# MACHINE

## (TRANSFORMER + INDUCTION)

# ELECTRICAL ENGINEERING

**Date of Test : 17/07/2025****ANSWER KEY** ➤

|        |         |         |         |         |
|--------|---------|---------|---------|---------|
| 1. (c) | 7. (c)  | 13. (d) | 19. (a) | 25. (d) |
| 2. (b) | 8. (d)  | 14. (a) | 20. (d) | 26. (c) |
| 3. (b) | 9. (d)  | 15. (b) | 21. (d) | 27. (b) |
| 4. (c) | 10. (c) | 16. (c) | 22. (c) | 28. (d) |
| 5. (a) | 11. (c) | 17. (d) | 23. (d) | 29. (b) |
| 6. (b) | 12. (a) | 18. (b) | 24. (b) | 30. (c) |

## DETAILED EXPLANATIONS

1. (c)

For maximum torque ( $T_{\max}$ )

$$s_{\max, T} = \frac{R_2}{X_2}$$

$$s_{\max, T} = \frac{1}{4}$$

$$\text{Synchronous speed, } N_s = \frac{120 \times 50}{6} = 1000 \text{ rpm}$$

Now at  $T_{\max}$  speed of motor,

$$N_r = (1 - s) N_s = (1 - 0.25) \times 1000$$

$$N_r = 750 \text{ rpm}$$

2. (b)

Given,

$$V_1 = 1000 \text{ V,}$$

$$V_2 = 400 \text{ V}$$

No load current,  $I_{e1} = 3 \text{ A}$  at 0.75 lag p.f.

No load current on l.v. side;

$$I_{e2} = I_{e1} \times \frac{V_1}{V_2} = 3.0 \times \frac{1000}{400} = 7.5 \text{ A}$$

At no load, the p.f. remains same on both sides;

then power factor = 0.75 lag

3. (b)

As we can write:

$$\text{Voltage regulation; } V.R. = Z_{pu} \cdot \cos(\theta_{eq} - \phi)$$

For leading power factor angle =  $-30^\circ$

$$V.R. = 0.1 \cos(90^\circ + 30^\circ)$$

If resistance is negligible;

$$\text{then } \theta_{eq} = 90^\circ$$

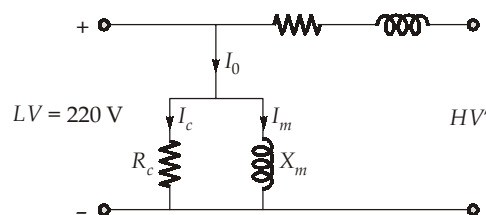
$$\text{therefore; } V.R. = 0.1 \{-\sin 30^\circ\}$$

$$= -0.1 \times 0.5 = -0.05$$

$$\% V.R. = -5\%$$

4. (c)

Lets take circuit referred to low voltage side,



$$\text{Watt meter reading} = VI \cos \phi$$

$$\cos \phi = \frac{100}{220 \times 2.5} = 0.1818$$

$$\sin \phi = \sin (\cos^{-1} (0.1818)) = 0.9833$$

$$I_c = I_0 \cos \phi = 2.5 \times 0.1818 = 0.4545 \text{ A}$$

$$I_m = I_0 \sin \phi = 2.5 \times 0.9833 = 2.46 \text{ A}$$

$$\therefore R_c = \frac{V}{I_c} = \frac{220}{0.4545} = 484 \Omega$$

$$X_m = \frac{V}{I_m} = \frac{220}{2.46} = 89.43 \Omega$$

$\therefore$  Option (c) is the only equivalent circuit matching.

5. (a)

Impedance under block rotor condition,

$$Z_b = \frac{V_b}{I_b} = \frac{82.5}{9.3} = 8.87 \Omega$$

Resistance under block rotor condition,

$$R_b = \frac{W_b}{I_b^2} = \frac{500}{(9.3)^2} = 5.78 \Omega$$

Rotor resistance referred to stator,

$$\begin{aligned} R'_2 &= R_b - R_1 \\ &= 5.78 - 2.5 = 3.28 \Omega \end{aligned}$$

6. (b)

Rotor input (or) air gap power

$$= 45 - 1.5 = 43.5 \text{ kW}$$

$$s = 0.04$$

Internal mechanical power developed is

$$= 43.5 (1 - 0.04) = 43.5 \times 0.96 = 41.76 \text{ kW}$$

7. (c)

$$T_{st} = 0.8 T_{\max}$$

$$0.8 = \frac{2s_{\max}}{s_{\min}^2 + 1}$$

$$s_{\max}^2 - \frac{2}{0.8}s_{\max} + 1 = 0$$

$$s_{\max}^2 - 2.5s_{\max} + 1 = 0$$

$$s_{\max} = 0.5$$

$$\therefore 0.5 = \frac{0.03 + R_{\text{ext}}}{0.18}$$

$$0.09 = 0.03 + R_{\text{ext}}$$

$$R_{\text{ext}} = 0.09 - 0.03 = 0.06 \Omega$$

8. (d)

We know, 
$$\frac{N_{\Delta(P)}}{N_{Y(P)}} = 5$$

Also, 
$$\frac{N_{\Delta(P)}}{N_{Y(P)}} = \frac{V_{\Delta(P)}}{V_{Y(P)}}$$

$$V_{Y(P)} = \frac{400}{\sqrt{3}} \text{ V}$$

$$V_{\Delta(P)} = \frac{N_{\Delta(P)}}{N_{Y(P)}} V_{Y(P)} = 5 \times \frac{400}{\sqrt{3}} = \frac{2000}{\sqrt{3}} \text{ V}$$

For delta side, 
$$V_{\Delta(L)} = V_{\Delta(P)} = \frac{2000}{\sqrt{3}} \text{ V}$$

9. (d)

For maximum efficiency at unity power factor using condition,

$$\text{kVA}_m = (\text{kVA})_{fl} \sqrt{\frac{P_i}{P_{cu}}} = 400 \sqrt{\frac{700}{2800}} = 400 \sqrt{\frac{1}{4}} = 200 \text{ kVA}$$

At maximum efficiency,

$$P_c = P_i$$

$$\% \eta_{\max} = \frac{200}{200 + \frac{700}{1000} + \frac{700}{1000}} = 99.30\%$$

10. (c)

For a 3-phase induction motor, spatial displacement,

$$\delta = 90^\circ + \phi_2$$

where ' $\phi_2$ ' is power factor angle,

$$\cos \phi_2 = 0.707$$

$$\phi_2 = 45^\circ$$

$$\delta = 90^\circ + 45^\circ = 135^\circ$$

11. (c)

For  $f_2 = 15 \text{ Hz}$ , the slip is

$$s = \pm \frac{f_2}{f_1} = \pm \frac{15}{60} = \pm \frac{1}{4}$$

The synchronous speed,  $N_s = \frac{120 \times f}{P} = \frac{120 \times 60}{6} = 1200 \text{ rpm}$

The speed of the system for  $f_2 = 15 \text{ Hz}$

$$N_r = (1 \pm s)N_s = (1 \pm 0.25)1200 = 900 \text{ and } 1500 \text{ rpm}$$

∴ hence option (c) is correct.

We can check for  $f_2 = 120 \text{ Hz}$

$$s = \pm \frac{120}{60} = \pm 2$$

$$N_r = (1 \pm 2) 1200 = -1200 \text{ and } 3600 \text{ rpm}$$

12. (a)

At no load;

$$\begin{aligned}\text{Back emf, } E_{b0} &= V_t - I_{a0} (R_a) \\ E_{b0} &= 220 - 3(0.5) \\ E_{b0} &= 218.5 \text{ V}\end{aligned}$$

At full load;

$$\begin{aligned}\text{Back emf, } E_{bfl} &= V_t - I_{afl} (R_a) \\ &= 220 - 45(0.5) \\ E_{bfl} &= 197.5 \text{ V}\end{aligned}$$

As flux is given constant;

then, we can write;  $E_b \propto N$ 

$$\text{or, } \frac{E_{bfl}}{E_{b0}} = \frac{N_{fl}}{N_0}$$

$$\begin{aligned}N_{fl} &= \left( \frac{197.5}{218.5} \right) \times 1500 \\ &= 1355.83 \approx 1356 \text{ rpm}\end{aligned}$$

13. (d)

Given:

S.C. Test (H.V): 57.5 V, 8.34 A, 284 W

$$Z_{eq} = \frac{57.5}{8.34} = 6.894 \Omega$$

$$R_{eq} = \frac{284}{(8.34)^2} = 4.083 \Omega$$

$$X_{eq} = \sqrt{Z_{eq}^2 - R_{eq}^2} = 5.555 \Omega$$

For voltage regulation to be zero;

$$\text{Power factor; } \cos \phi = \cos \tan^{-1} \left( \frac{R_{eq}}{X_{eq}} \right) = \cos (36.32^\circ)$$

$$\cos \phi = 0.805 \text{ leading}$$

14. (a)

Primary is star connected and secondary is delta connected.

$$(V_L)_{\text{primary}} = 11000 \text{ V}$$

$$(V_{ph})_{\text{primary}} = \frac{11000}{\sqrt{3}} \text{ V}$$

$$\frac{(V_{ph})_{\text{sec}}}{(V_{ph})_{\text{prim}}} = \frac{1}{5}$$

$$\therefore \text{ Turns ratio} = \left( \frac{\text{High voltage}}{\text{Low voltage}} \right)_{\text{phase}}$$

$$\therefore (V_{ph})_{\text{sec}} = \frac{11000}{5\sqrt{3}} \text{ V}$$

$$\begin{aligned}(V_{ph})_{\Delta} &= (V_L)_{\Delta} \\ \text{Output kVA} &= \sqrt{3} V_L I_L \\ &= \sqrt{3} \times \frac{11000}{5\sqrt{3}} \times 423 = 930.6 \text{ kVA}\end{aligned}$$

15. (b)

Given that,

$$\begin{aligned}V_{OC} &= 230 \text{ V}, \\ I_{OC} &= 1.3 \text{ A}, \\ P_{OC} &= 100 \text{ W} \\ R_C &= \frac{V_{OC}^2}{P_{OC}} = \frac{230^2}{100} = 529 \Omega\end{aligned}$$

Power factor angle,

$$\begin{aligned}\phi_{OC} &= \cos^{-1}\left(\frac{P_{OC}}{V_{OC} I_{OC}}\right) = \cos^{-1}\left(\frac{100}{230 \times 1.3}\right) = 70.46^\circ \\ X_\phi &= \frac{R_C}{\tan \phi_{OC}} = \frac{529}{\tan 70.46^\circ} = 187.73 \Omega\end{aligned}$$

Referred to high voltage side,

$$\begin{aligned}R_C &= 529 \times \left(\frac{400}{230}\right)^2 = 1600 \Omega \\ X_\phi &= 187.73 \times \left(\frac{400}{230}\right)^2 = 567.8 \Omega\end{aligned}$$

16. (c)

From the given diagram,

$$\begin{aligned}N_1 : N_2 : N_3 &= 9 : 3 : 1 \\ \text{Induced emf} &= 400 \angle 0^\circ \text{ V}\end{aligned}$$

As we know that;  $\frac{E_1}{E_2} = \frac{N_1}{N_2}$

$$\Rightarrow E_2 = \frac{N_2}{N_1} E_1 = \left(\frac{3}{9}\right) \times 400 \angle 0^\circ = \frac{400}{3} \angle 0^\circ \text{ V}$$

and  $\frac{E_1}{E_3} = \frac{N_1}{N_3}$

$$\Rightarrow E_3 = \left(\frac{1}{9}\right) 400 \angle 0^\circ = \frac{400}{9} \angle 0^\circ \text{ V}$$

Current in secondary winding;

$$\Rightarrow I_2 = \frac{E_2}{R} = \frac{400/3}{20} = \frac{20}{3} \text{ A}$$

Current in tertiary winding;

$$\Rightarrow I_3 = \frac{E_3}{-jX_c} = \frac{400/9}{-j5} = \frac{80}{9} \angle 90^\circ \text{ A}$$

$I_2$  referred to primary side,

$$I_2' = \left( \frac{N_2}{N_1} \right) I_2 = \left( \frac{3}{9} \right) \times \frac{20}{3} = \frac{20}{9} \angle 0^\circ \text{ A}$$

$I_3$  referred to primary side,

$$I_3' = \left( \frac{N_3}{N_1} \right) I_3 = \frac{1}{9} \times \frac{80}{9} \angle 90^\circ \text{ A} = \frac{80}{81} \angle 90^\circ \text{ A}$$

Then supply current, 
$$I_1 = \frac{20}{9} \angle 0^\circ + \frac{80}{81} \angle 90^\circ$$

$$= \frac{20}{81} (9 + j4) \text{ A}$$

17. (d)

Given, 
$$N_s = \frac{120 \times f}{P} = \frac{120 \times 50}{4} = 1500 \text{ rpm}$$

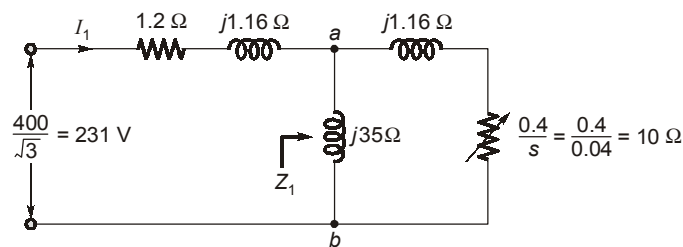
$$N_r = 1440 \text{ rpm}$$

$$\text{Slip, } s = \frac{1500 - 1440}{1500} = 0.04$$

Rotor resistance at  $s = 0.04$ ,

$$r_2' = \frac{0.4}{0.04} = 10 \Omega$$

Consider the circuit diagram shown below,



$$Z_1 = \frac{j35(10 + j1.16)}{10 + j(35 + 1.16)}$$

$$= \frac{352.45 \angle 96.6^\circ}{37.51 \angle 74.5^\circ} = 9.4 \angle 22.1^\circ \Omega = (8.703 + j 3.53) \Omega$$

Total impedance of circuit,

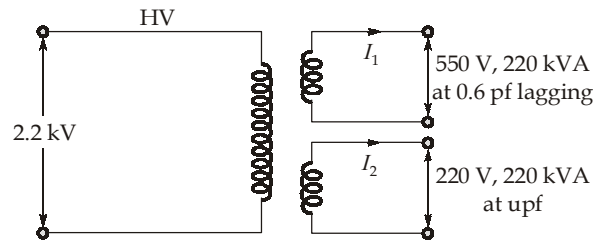
$$\vec{Z}_i = (8.703 + j 3.53) + (1.2 + j 1.16)$$

$$= 9.90 + j 4.69 = 10.955 \angle 25.35^\circ \Omega$$

Stator current, 
$$I_1 = \frac{231}{10.955} = 21.09 \text{ A}$$

18. (b)

Consider the below circuit:



Rated current in winding - 1

$$I_1 = \frac{220 \times 1000}{550} = 400 \angle -53.13^\circ \text{ A}$$

Rated current in winding - 2

$$I_2 = \frac{220 \times 1000}{220} = 1000 \angle 0^\circ \text{ A}$$

Current in HV side due to rated current in winding - 1

$$I_1' = \frac{(400 \angle -53.13) \times 0.55}{2.2} = 100 \angle -53.13^\circ \text{ A}$$

Current in HV side due to rated current in winding - 2

$$I_2' = \frac{(1000 \angle 0^\circ) \times 0.22}{2.2} = 100 \angle 0^\circ \text{ A}$$

$$\text{HV side current} = 100 \angle -53.13^\circ + 100 \angle 0^\circ$$

$$I = 178.885 \angle -26.565^\circ \text{ A}$$

$$|I| = 178.885 \text{ A}$$

19. (a)

We know that,

$$\text{Torque, } T = \frac{3}{\omega_{sm}} \times \frac{V^2}{R_2'} s \text{ (for low slip)}$$

$$\text{Now, } T = \text{constant} \quad T \propto V^2 s$$

$$(\text{or}) \quad V_2^2 s_2 = V_1^2 s_1$$

$$(\text{or}) \quad s_2 = \left( \frac{V_1}{V_2} \right)^2 s_1$$

$$(\text{or}) \quad s_2 = 4s_1,$$

hence slip increases 4 times,

$$\text{Also, } T = \frac{3I_2'^2}{\omega_{sm}} \times \frac{R_2'}{s} = \text{const.}$$

$$(\text{or}) \quad I_2'^2 \propto s$$

$$\frac{I_2'}{I_1'} = \sqrt{\frac{s_2}{s_1}} = \sqrt{\frac{4}{1}} = 2$$

Hence, current increases by 2 times.

20. (d)

Power factor of the load;

$$\text{p.f.} = \frac{P}{VI} = \frac{5 \times 10^3}{400 \times 16}$$

$$\text{p.f.} = 0.781 \text{ lagging}$$

$$\text{or p.f. angle } \phi = \cos^{-1} 0.781 = 38.62^\circ$$

The equivalent circuit of the transformer referred to H.V. side can be shown as below;

From circuit;

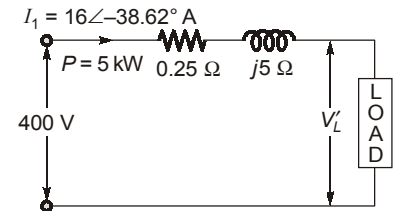
$$V_L' = 400 \angle 0^\circ - (0.25 + j5) \times 16 \angle -38.62^\circ$$

$$V_L' = 352.094 \angle -9.81^\circ \text{ V}$$

The voltage on load side or L.V. side

$$V_L = \frac{352.094}{5} \angle -9.81^\circ$$

$$V_L = 70.42 \angle -9.81^\circ \text{ V}$$



21. (d)

$$V_{sc} = 120 \text{ V}, I_{sc} = 9.6 \text{ A}, P_{sc} = 460 \text{ W}$$

$$Z_e = \frac{V_{sc}}{I_{sc}} = \frac{120}{9.6} = 12.5 \Omega$$

$$R_e = \frac{P_{sc}}{I_{sc}^2} = \frac{460}{(9.6)^2} = 4.99 \Omega$$

$$R_{lm} = 1.5 \Omega$$

$$R_2' = R_e - R_{lm} = 4.99 - 1.5 = 3.49 \Omega$$

$$\text{Given, } V_0 = 220 \text{ V}, I_0 = 4.6 \text{ A}, P_0 = 125 \text{ W}$$

Core, friction and windage losses

$$= 125 - (4.6)^2 \left( 1.5 + \frac{3.49}{4} \right) = 74.8 \text{ W}$$

22. (c)

$$\text{Synchronous speed, } N_s = \frac{120f}{P} = \frac{120 \times 50}{4} = 1500 \text{ rpm}$$

$$\text{Forward slip, } s_f = \frac{N_s - N_r}{N_s} = \frac{1500 - 1420}{1500} = 0.053$$

$$\text{Backward slip, } s_b = (2 - s) = (2 - 0.053) = 1.947$$

The effective rotor resistance in backward branch

$$= \frac{R_2}{2(2 - s)} = \frac{7.5}{2(2 - 0.053)} = 1.926 \Omega \approx 1.93 \Omega$$

23. (d)

Given transformer rating 50 kVA, 22 kV/220 V percent resistance = 1% percent reactance = 8%.

Taking hv side voltage as base voltage is 22 kV.

$$\text{Base apparent power, } S_B = 50 \text{ kVA}$$

As primary is  $\Delta$  connected.

Phase voltage,  $V_p = \text{line voltage, } V_L$

$$\therefore \text{Base impedance, } Z_{\text{base}} = \frac{3(V_{\phi, \text{base}})^2}{S_{\text{base}}} = \frac{3 \times (22000)^2}{50 \times 10^3} = 29040 \Omega$$

The per unit impedance of transformer,

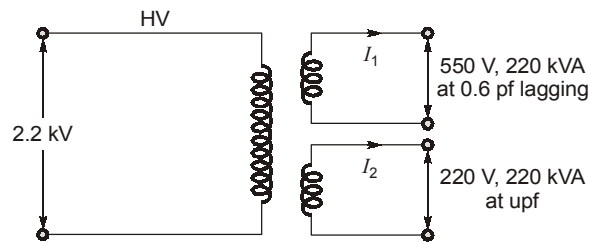
$$Z_{\text{eq pu}} = 0.01 + j0.08 \text{ pu}$$

$\therefore$  High voltage side impedance,

$$Z_{\text{ph hv}} = Z_{\text{eq pu}} \times Z_{\text{base}} = (0.01j + j0.08) \times 29040 = 290.40 + j2323.2 \Omega$$

**24. (b)**

Consider the below circuit:



Rated current in winding - 1

$$I_1 = \frac{220 \times 1000}{550} = 400 \angle -53.13^\circ \text{ A}$$

Rated current in winding - 2

$$I_2 = \frac{220 \times 1000}{220} = 1000 \angle 0^\circ \text{ A}$$

Current in HV side due to rated current in winding - 1

$$I_1' = \frac{(400 \angle -53.13) \times 0.55}{2.2} = 100 \angle -53.13^\circ \text{ A}$$

Current in HV side due to rated current in winding - 2

$$I_2' = \frac{(1000 \angle 0^\circ) \times 0.22}{2.2} = 100 \angle 0^\circ \text{ A}$$

$$\text{HV side current} = 100 \angle -53.13^\circ + 100 \angle 0^\circ$$

$$I = 178.885 \angle -26.565^\circ \text{ A}$$

$$|I| = 178.885 \text{ A}$$

**25. (d)**

Given, Starting torque,  $T_{\text{st}} = 0.65 T_{\text{fl}}$

Short circuit current,  $I_{\text{sc}} = 5 I_{\text{fl}}$

Full load slip,  $s_{\text{fl}} = 0.04$

As we know; for auto-transformer starting

$$\frac{T_{\text{st}}}{T_{\text{fl}}} = x^2 \left( \frac{I_{\text{sc}}}{I_{\text{fl}}} \right)^2 s_{\text{fl}}$$

$$\frac{0.65}{1} = x^2 \left( \frac{5}{1} \right)^2 \times 0.04$$

$$x^2 = \frac{0.65}{25 \times 0.04}$$

$$\text{Transformation ratio, } x = 0.806 \approx 0.81$$

26. (c)

For transformer,

$$\frac{E_2}{E_1} = \frac{N_2}{N_1} = K \text{ (transformation ratio)}$$

the transformation ratio does not depend on frequency

Hence; 
$$\frac{E'_2}{E_2} = \frac{E'_1}{E_1} = K$$

Here, 
$$K = \frac{440}{110} = 4$$

therefore, on l.v. side voltage  $E'_2$ , when h.v. side voltage  $E'_1 = 300$  V is,

$$E'_2 = \frac{300}{440} \times 110 = 75 \text{ V}$$

The frequency does not change on l.v. side as transformer is a constant frequency machine.

27. (b)

The mmf distribution contains a fundamental and a family of space harmonics of order  $h = 6m \pm 1$ , where  $m$  is positive number.

In a three phase machine, when sinusoidally varying currents flow through the winding, the space harmonic wave rotate at  $(1/h)$  times the speed of the fundamental wave. The space harmonic waves rotate in the same direction as the fundamental wave if  $h = 6m + 1$  and in the opposite direction if  $h = 6m - 1$ .

28. (d)

By referring the transformer impedance to LV side,

$$R_{LV} = 0.05 + \frac{3}{(10)^2} = 0.08 \Omega$$

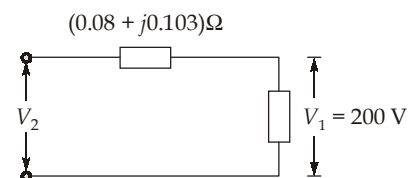
$$X_{LV} = 0.05 + \frac{5.3}{(10)^2} = 0.103 \Omega$$

Drawing circuit representation,

$$\text{Current, } I_2 = \frac{20 \times 1000}{200} = 100 \text{ A}$$

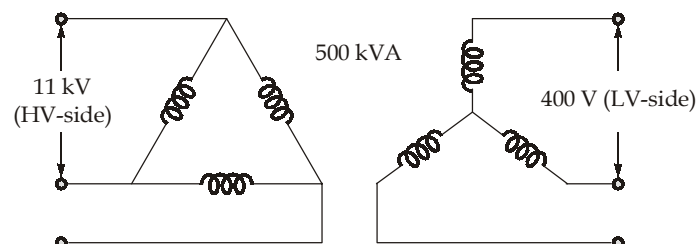
$$\text{Voltage drop} = 100(0.08 \times 0.8 + 0.103 \times 0.6) = 12.58 \text{ V}$$

$$\text{Voltage regulation} = \frac{12.58}{200} \times 100 = 6.29\%$$



29. (b)

For given transformer configuration,



Phase current at star side,

$$I_{PY \text{ (rated)}} = \frac{500}{\sqrt{3} \times 0.40} = 721.687 \text{ A}$$

Phase current at delta side,

$$I_{P\Delta \text{ (rated)}} = \frac{500}{3 \times 11} = 15.151 \text{ A}$$

$$\text{At lv side, resistance } R_{LV} = \frac{2000}{3 \times (721.687)^2} = 1.28 \times 10^{-3} \Omega$$

$$\text{At hv side, resistance } R_{HV} = \frac{2500}{3 \times (15.15)^2} = 3.63 \Omega$$

Turn ratio,

$$\frac{\text{Phase voltage (hv side)}}{\text{Phase voltage (lv side)}} = \frac{11}{0.40 / \sqrt{3}} = 47.63$$

Referred values on delta side ( $\Delta$  side)

$$R_{eq} \text{ (HV)} = 3.63 + 1.28 \times 10^{-3} (47.63)^2 = 6.53 \Omega \text{ (per phase)}$$

$$X \text{ (p.u.)} = 0.05$$

$$Z_{base \text{ (HV)}} = \frac{11000}{15.15} = 726.024 \Omega$$

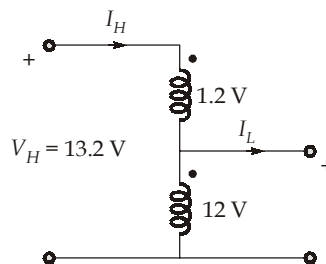
$$X_{eq \text{ HV}} = 0.05 \times 726.024 = 36.30 \Omega \text{ (per phase)}$$

30. (c)

The apparent power rating will be

$$S_{auto} = \frac{N_{series} + N_{common}}{N_{series}} S_{TW}$$

$$= \frac{1.2 + 12}{1.2} \times 1000 = 11000 \text{ KVA}$$



The transformer impedance in p.u. system when connected in two winding manner is,

$$Z_{eq} = (0.01 + j0.08) \text{ p.u.}$$

The apparent power advantage of this auto transformer is 11, so the per unit impedance of the auto transformer is,

$$Z_{eq} = \frac{0.01 + j0.08}{11} = (0.00091 + j0.00727) \text{ p.u.}$$

