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STRUCTURE ANALYSIS

CIVIL ENGINEERING

Date of Test : 16/09/2025

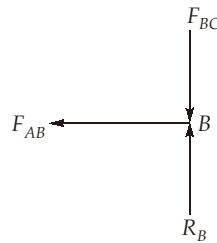
ANSWER KEY >

1. (c)	7. (a)	13. (a)	19. (b)	25. (0)
2. (a)	8. (d)	14. (a)	20. (b)	26. (b)
3. (d)	9. (d)	15. (b)	21. (c)	27. (b)
4. (c)	10. (a)	16. (d)	22. (a)	28. (b)
5. (a)	11. (a)	17. (a)	23. (b)	29. (d)
6. (a)	12. (b)	18. (d)	24. (c)	30. (c)

DETAILED EXPLANATIONS

1. (c)

For joint B,



Now, $\Sigma F_y = 0 \Rightarrow F_{AB} = 0$

2. (a)

$$D_k = 3j - r_e - m$$

Given that members are not inextensible i.e. members are extensible,

$$\Rightarrow m = 0$$

$$\therefore D_k = 3 \times 4 - (3 + 2) = 12 - 5 = 7$$

3. (d)

Moment induced at A \geq Half of moment applied at B = $\frac{60}{2} = 30 \text{ kNm}$

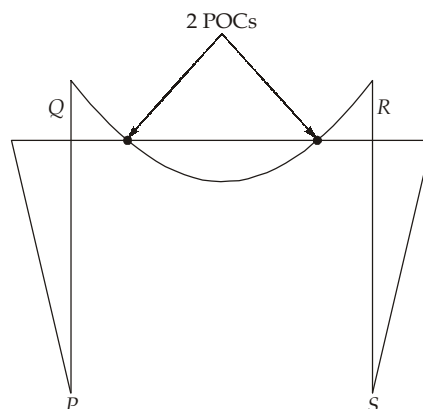
4. (c)

Slope deflection equations can be written for

$$M_{AB}, M_{BA}, M_{BC}, M_{CB}, M_{CD}, M_{DC}, M_{CE} \text{ and } M_{EC}$$

5. (a)

BMD



6. (a)

7. (a)

When there is a rise in temperature, the length of the cable increases and dip increases. The relation between change in length of cable and the dip is

$$\Delta y_c = \frac{3}{16} \frac{l}{y_c} \Delta L$$

Increase in temperature leads to increase in length of cable and hence dip.

8. (d)

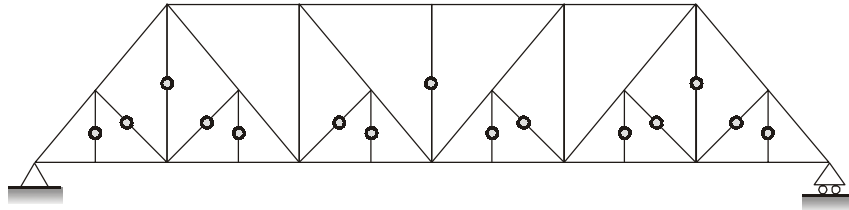
Castingliano's first theorem,

$$\frac{\partial U}{\partial \Delta_j} = P_j$$

Castingliano's second theorem,

$$\frac{\partial U}{\partial P_j} = \Delta_j$$

9. (d)



10. (a)

B

 $B \sin$

B

C C

 $C \cos$

As length of member will not change because members are inextensible,

$$\Delta_B \sin \theta = \Delta_C \cos \theta$$

$$\Rightarrow \Delta_C = \Delta_B \tan \theta$$

$$\Rightarrow \Delta_C = \frac{4\Delta_B}{3} = \frac{4}{3} \Delta$$

11. (a)

Applying, Work done by load = Strain energy stored in beam

Strain energy stored in beam = $U_{RQ} + U_{QP}$

$$= \int_0^2 \frac{(3x)^2 dx}{2EI} + \int_0^4 \frac{(6)^2 dx}{2EI} = \frac{9}{2EI} \left[\frac{x^3}{3} \right]_0^2 + \frac{36}{2EI} \left[x \right]_0^4 = \frac{9}{2} \times \frac{8}{3EI} + \frac{36}{2EI} \times 4 = \frac{84}{EI}$$

$$\Rightarrow \frac{1}{2} \times P \times \Delta = \frac{84}{EI}$$

$$\Rightarrow \frac{1}{2} \times 3 \times \Delta = \frac{84}{EI}$$

$$\Rightarrow \Delta = \frac{56}{10^4} \times 10^3 = 5.6 \text{ mm}$$

12. (b)

$$M_x = \frac{wR^2}{2} (\sin\theta - \sin^2\theta)$$

For maximum bending moment,

$$\frac{dM_x}{d\alpha} = 0$$

$$\frac{wR^2}{2} (\cos\theta - 2\sin\theta\cos\theta) = 0$$

$$\Rightarrow \cos\theta(1 - 2\sin\theta) = 0$$

$$\Rightarrow \cos\theta = 0 \Rightarrow \theta = 90^\circ \text{ and } \sin\theta = \frac{1}{2} \Rightarrow \theta = 30^\circ$$

$$\theta = 90^\circ \text{ (Rejected as BM = 0)}$$

$$\therefore \theta = 30^\circ$$

$$\therefore M_x = \frac{-wR^2}{2} (\sin 30^\circ - \sin^2 30^\circ) = \frac{-wR^2}{8} \quad \text{or } \frac{wR^2}{8} \text{ (Hogging)}$$

13. (a)

Let the applied moment M be clockwise in direction.

$$M_{FAB} = -\frac{12 \times 5^2}{12} = -25 \text{ kNm}$$

$$M_{FBA} = 25 \text{ kNm}$$

$$M_{FBC} = -\frac{10 \times 4}{8} = -5 \text{ kNm}$$

$$M_{FCB} = 5 \text{ kNm}$$

Using slope deflection method,

We know that, $M_{BA} + M_{BC} = M$

$$\begin{aligned} M_{BA} &= +25 + \frac{2E(2I)}{5} \left[2\theta_B^0 + \theta_A \right] \\ &= +25 \end{aligned} \quad \dots \text{ (i)}$$

where $\theta_A = 0$ (End A is fixed)

$$\begin{aligned} M_{BC} &= -5 + \frac{2EI}{4} \left[2\theta_B^0 + \theta_C \right] \\ &= -5 + 0.5EI [\theta_C] \end{aligned} \quad \dots \text{ (ii)}$$

$$M_{CB} = 0 = 5 + \frac{2EI}{4} \left[2\theta_C + \theta_B^0 \right]$$

$$\Rightarrow -5 = \frac{2EI}{4} \times 2\theta_C$$

$$\Rightarrow \theta_C = -\frac{5}{EI} \quad \dots \text{ (iii)}$$

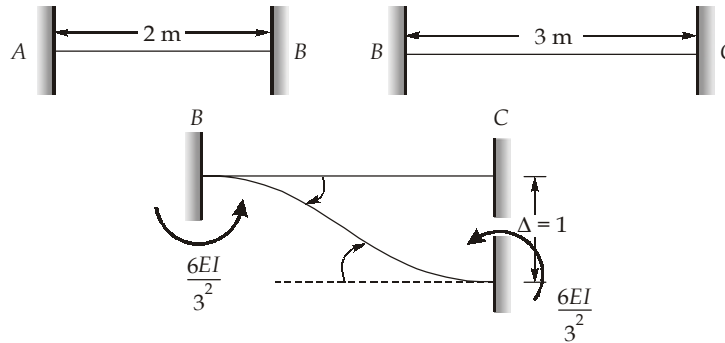
Substituting (iii) in (ii),

$$M_{BA} = 25 \text{ kNm}$$

$$M_{BC} = -5 + 0.5EI \times \left(-\frac{5}{EI} \right) = -5 - 2.5 = -7.5 \text{ kNm}$$

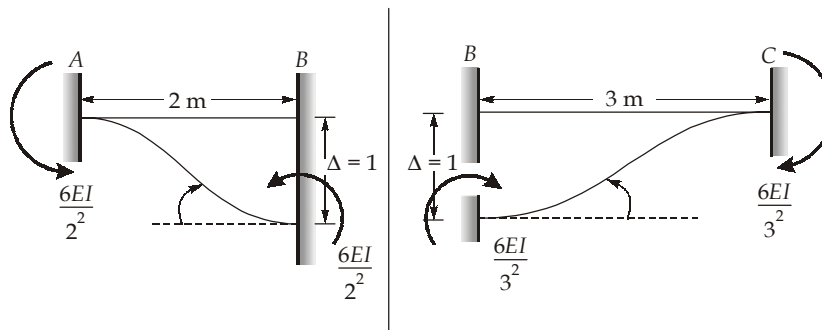
$$\begin{aligned} \therefore M_{BA} + M_{BC} &= M \\ \Rightarrow 25 + (-7.5) &= M \\ \Rightarrow M &= 17.5 \text{ kNm} \end{aligned}$$

14. (a)
 k_{41} :



$$k_{41} = -\frac{6EI}{3^2} = -\frac{6EI}{9}$$

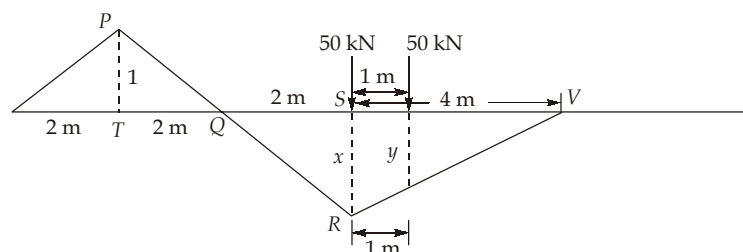
k_{43} :



$$k_{43} = \frac{6EI}{9} - \frac{6EI}{4} = \frac{2}{3}EI - \frac{3}{2}EI = -\frac{5EI}{6}$$

$$\text{Ratio} = \frac{k_{41}}{k_{43}} = \frac{-6EI/9}{-5EI/6} = \frac{4}{5} = 0.8$$

15. (b)
 As per Muller Breslau principle,



$$BM_{\max} = 50 \times x + 50 \times y$$

From Δs PTQ and QSR

$$\frac{x}{2} = \frac{1}{2} \Rightarrow x = 1$$

Using ΔSVR
$$\frac{x}{4} = \frac{y}{4-1} \Rightarrow \frac{1}{4} = \frac{y}{3} \Rightarrow y = \frac{3}{4}$$

$$BM_{max} = 50 \times 1 + 50 \times \frac{3}{4} = 87.5 \text{ kNm}$$

16. (d)

Let l_1 and l_2 be the distances of point C from A and B respectively.

$$\therefore \frac{l_1}{l_2} = \sqrt{\frac{4}{9}} \text{ [Property of parabola]}$$

$$\Rightarrow 3l_1 = 2l_2$$

$$\Rightarrow l_2 = 1.5l_1$$

Also, $l_1 + l_2 = 30 \text{ m}$

$$\Rightarrow l_1 + 1.5l_1 = 30$$

$$\Rightarrow l_1 = 12 \text{ m}$$

So, $l_2 = 18 \text{ m}$

Now, $V_A + V_B = 50 \text{ kN}$

$$\Sigma M_B = 0$$

$$\Rightarrow V_A \times 30 + H_A \times 5 = 50 \times DB$$

$$DB = BC + CD = 18 + 5 = 23 \text{ m}$$

$$\therefore 6V_A + H_A = 230 \text{ kN} \quad \dots(i)$$

$$\Sigma M_C = 0 \text{ (from left)}$$

$$\Rightarrow V_A \times 12 - H_A \times 4 - 50 \times 5 = 0$$

$$\Rightarrow 3V_A - H_A = 62.5 \text{ kN}$$

$$V_A = \frac{62.5 + H_A}{3} \quad \dots(ii)$$

From eq. (i) and (ii),

$$\Rightarrow 6 \times \frac{62.5 + H_A}{3} + H_A = 230$$

$$\therefore H_A = 35 \text{ kN}$$

17. (a)

P-System of forces

Consider joint C,

$$\Sigma F_y = 0$$

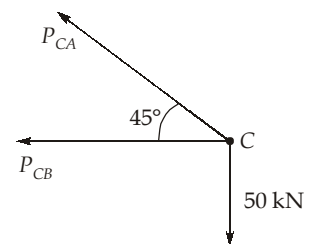
$$\Rightarrow P_{CA} \sin 45^\circ = 50$$

$$\Rightarrow P_{CA} = \frac{50}{(1/\sqrt{2})} = 70.71 \text{ kN}$$

$$\Sigma F_x = 0$$

$$\Rightarrow P_{CA} \cos 45^\circ + P_{CB} = 0$$

$$\Rightarrow P_{CB} = -P_{CA} \cos 45^\circ$$



$$= -70.71 \times \frac{1}{\sqrt{2}} = -50 \text{ kN}$$

As unit load to be applied will be in the same direction of 50 kN.

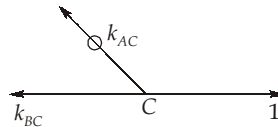
So, $k_{CA} = \sqrt{2}$

$$k_{CB} = 1$$

Members	P	k	L	PKL
AC	70.71	$\sqrt{2}$	$4\sqrt{2}$	565.68
BC	-50	-1	4	200
				$\Sigma PKL = 765.68$

Hence, $\Delta_{VC} = \frac{765.68}{AE}$

To find horizontal deflection, apply unit load at C in the horizontal direction.



$$k_{AC} = 0$$

$$k_{BC} = 1$$

So,
$$\Delta_{HC} = \frac{\Sigma PKL}{AE} = (P_{AC} k_{AC} L_{AC}) + (P_{BC} k_{BC} L_{BC})$$

$$= 0 + \frac{(-50) \times (1) \times 4}{AE} = -\frac{200}{AE}$$

So, Required ratio = $\frac{\Delta_{VC}}{\Delta_{HC}} = \frac{765.68}{200} = 3.83$

18. (d)

$$M_{FAB} = -\frac{wL^2}{12} = -\frac{16 \times 4^2}{12} = -21.33 \text{ kNm}$$

$$M_{FBA} = \frac{wL^2}{12} = \frac{16 \times 4^2}{12} = 21.33 \text{ kNm}$$

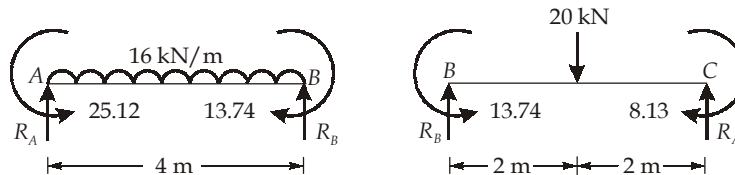
$$M_{FBC} = -\frac{wL}{8} = -\frac{20 \times 4}{8} = -10 \text{ kNm}$$

$$M_{FCB} = \frac{wL}{8} = \frac{20 \times 4}{8} = 10 \text{ kNm}$$

Consider B as rigid joint.

Joint	Members	Stiffness	Total stiffness	DF
B	BA	$\frac{8EI}{4}$	$3EI$	0.67
	BC	$\frac{4EI}{4}$		0.33

Joint	A	B		C
DF	—	0.67	0.33	—
Fixed end moment	-21.33	21.33	-10	10
Balancing moment	—	-7.59	-3.74	—
Carry over moment	-3.79	—	—	-1.87
Final Moment (kNm)	-25.12	13.74	-13.74	8.13



Considering AB : $\Sigma M_B = 0$

$$\Rightarrow R_A \times 4 - 25.12 + 13.74 - 16 \times 4 \times 2 = 0$$

$$\Rightarrow R_A = 34.845 \text{ kN}$$

Considering BC : $\Sigma M_B = 0$

$$-R_C \times 4 + 20 \times 2 + 8.13 - 13.74 = 0$$

$$\Rightarrow R_C = 8.5975 \text{ kN}$$

$$\begin{aligned} \text{So, } \Sigma \text{Vertical forces} &= 34.845 (\uparrow) + 8.5975 (\uparrow) - 16 \times 4 (\downarrow) - 20 (\downarrow) \\ &= -40.56 \text{ kN} \end{aligned}$$

So, an upward force of 40.56 kN (\uparrow) is required at B to prevent deflection of B .

19. (b)

$$\text{Stiffness of beam} = \frac{3EI}{L^3} = \frac{3 \times 2.5 \times 10^3}{5^3} = 60 \text{ kN/m}$$

As spring and beam are in parallel,

$$\therefore k_{eq} = k + k + \frac{3EI}{L^3} = 40 + 40 + 60 = 140 \text{ kN/m}$$

$$\text{Mass, } m = 10 \text{ kN} = \frac{10000}{9.081} = 1019.37 \text{ kg}$$

$$\text{Therefore, angular frequency, } \omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{140 \times 10^3}{1019.37}} = 11.72 \text{ rad/s}$$

$$\text{Now, } V = A\omega \cos(\omega t + \theta)$$

Here,

$$A = \sqrt{y_0^2 + \left(\frac{V_0}{\omega}\right)^2} = \sqrt{5^2 + \left(\frac{135}{11.72}\right)^2} = 12.56 \text{ mm}$$

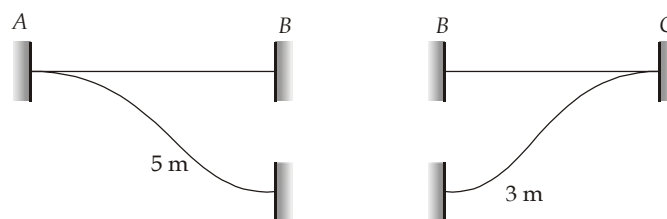
$$\tan \theta = \frac{\frac{y_0}{V_0}}{\frac{1}{\omega}} = \frac{5 \times 11.72}{135}$$

$$\Rightarrow \theta = 0.409 \text{ rad}$$

Hence, velocity,

$$V = A\omega \cos(\omega t + \theta) = 12.56 \times 11.72 \times \cos(11.72 \times 2 + 0.409) = 41.68 \text{ mm/s}$$

20. (b)



$$k = \frac{12EI}{(5)^3} + \frac{12EI}{(3)^3} = \frac{12 \times 3240}{125} + \frac{12 \times 3240}{27}$$

$$= 311.04 + 1440 = 1751.04 \text{ kN/m}$$

$$T = 2\pi \sqrt{\frac{m}{K}}$$

$$= 2\pi \sqrt{\frac{20}{1751.04 \times 10^3}}$$

$$= 0.0212 \text{ sec} \approx 0.02 \text{ sec}$$

21. (c)

Applying Betti's theorem to system (I) and (III)

$$20(0.001) + 10(0.008) = 10\Delta_A + 20(0.003)$$

$$\Rightarrow \Delta_A = 0.004 \text{ rad}$$

Applying Betti's theorem to system (II) and (III)

$$5(0.004) + 20(0.008) = 10(0.0015) + 20\Delta_B$$

$$\Rightarrow \Delta_B = 0.00825 \text{ rad}$$

$$\therefore \Delta_A + \Delta_B = 0.01225 \text{ rad}$$

22. (a)

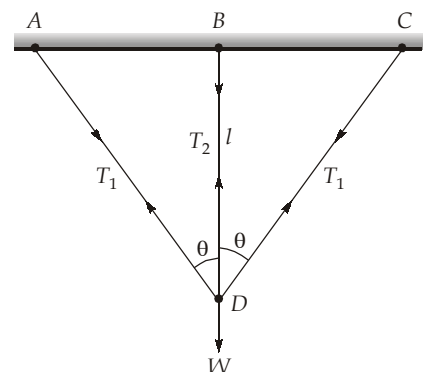
$$2T_1 \cos \theta + T_2 = W$$

$$\Rightarrow T_1 = \frac{W - T_2}{2 \cos \theta}$$

Strain energy stored in the wires,

$$U_1 = \sum \frac{P^2 L}{2AE} = \frac{T_2^2 l}{2AE} + 2T_1^2 \frac{l}{\cos^2 \theta} \frac{1}{2AE}$$

$$= \frac{T_2^2 l}{2AE} + \left(\frac{W - T_2}{2 \cos \theta}\right)^2 \frac{l}{AE \cos \theta}$$



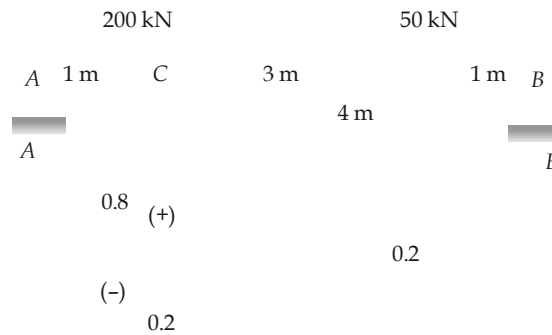
$$= \frac{T_2^2 l}{2AE} + \frac{(W - T_2)^2 l}{4AE \cos^3 \theta}$$

$$\frac{\partial U_i}{\partial T_2} = 0, \quad 0 = \frac{T_2 l}{AE} - \frac{2(W - T_2)l}{AE \cos^3 \theta}$$

$$T_2 = \frac{W}{1 + 2 \cos^3 \theta}$$

23. (b)

The ILD for shear force (S_c)



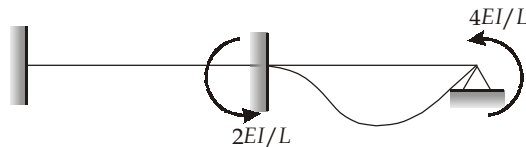
$$\frac{0.8}{4} = \frac{x}{1} \Rightarrow x = 0.2$$

Maximum shear force at C,

$$= 200(0.8) + 50(0.2) = 170 \text{ kN}$$

24. (c)

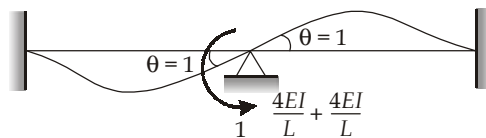
Give unit displacement in the direction (1)



$$k_{11} = \frac{4EI}{L}$$

$$k_{21} = \frac{2EI}{L}$$

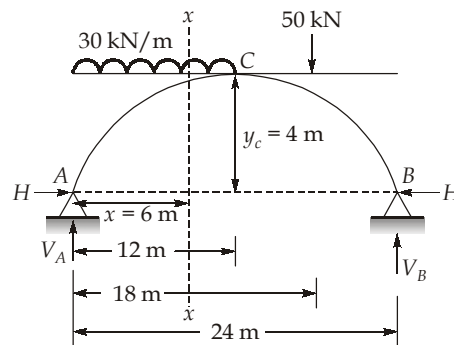
Give unit displacement in the direction (2)



$$k_{12} = \frac{2EI}{L}; \quad k_{22} = \frac{8EI}{L}$$

$$\therefore \text{The stiffness matrix } [k] = \begin{bmatrix} \frac{4EI}{L} & \frac{2EI}{L} \\ \frac{2EI}{L} & \frac{8EI}{L} \end{bmatrix}$$

25. (0)



The arch is shown in figure above,

Taking moments about B,

$$\Sigma M_B = 0$$

$$V_A \times 24 - 30 \times 12 \times 18 - 50 \times 6 = 0$$

$$\Rightarrow V_A = 282.5 \text{ kN}$$

$$\therefore V_B = 30 \times 12 + 50 - 282.5 = 127.5 \text{ kN}$$

$$\Sigma M_C = 0 \text{ (From right)}$$

$$V_B \times 12 - H \times 4 - 50 \times 6 = 0$$

$$\Rightarrow H = \frac{127.5 \times 12 - 50 \times 6}{4} = 307.5 \text{ kN}$$

Now, at 6 m from left support, $y = \frac{4y_c}{L^2} x(L-x) = \frac{4 \times 4}{24^2} \times 6(24-6) = 3 \text{ m}$

Also, $\frac{dy}{dx} = \frac{4y_c}{L^2} (L-2x)$

At $x = 6 \text{ m}$, $\frac{dy}{dx} = \tan \theta = \frac{4 \times 4}{24^2} (24 - 2 \times 6) = \frac{1}{3}$

$$\therefore \cos \theta = \frac{3}{\sqrt{10}}; \quad \sin \theta = \frac{1}{\sqrt{10}}$$

Radial shear at a section 6 m from left support,

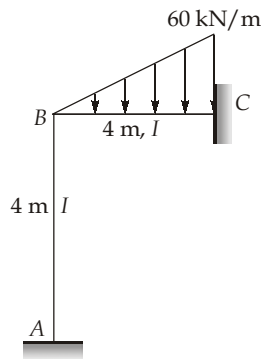
$$Q = V \cos \theta - H \sin \theta$$

$$V = \text{Vertical shear at } x-x = V_A - wx = 282.5 - 30 \times 6 = 102.5 \text{ kN}$$

$$\therefore Q = 102.5 \times \frac{3}{\sqrt{10}} - 307.5 \times \frac{1}{\sqrt{10}} = 0$$

26. (b)

Here degree of freedom is 3 i.e. the rotations θ_B , θ_C and θ_D . But due to symmetry, we have $\theta_B = -\theta_D$ and $\theta_C = 0$. For analysis of the frame as shown in figure above, only half as of the given structure is considered and $\theta_C = 0$, therefore only θ_B is the only unknown.



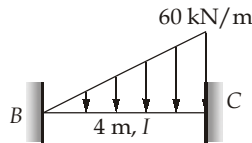
Joint equilibrium equation,

$$M_{BA} + M_{BC} = 0$$

Fixed end moment: Span AB

$$M_{FAB} = M_{FBA} = 0$$

Span BC:



$$M_{FBC} = -\frac{wL^2}{30} = \frac{60 \times 4^2}{30} = 32 \text{ kNm} \quad (\theta_A = 0, \Delta = 0)$$

$$\begin{aligned} \therefore M_{BC} &= M_{FBC} + \frac{2EI}{4} \left(2\theta_A + \theta_B - \frac{3\Delta}{4} \right) \\ &= 32 + \frac{EI\theta_B}{2} \quad \dots (\alpha) \end{aligned}$$

$$\begin{aligned} M_{BA} &= M_{FBA} + \frac{2EI}{4} \left(2\theta_B + \theta_A - \frac{3\Delta}{4} \right) \\ \Rightarrow M_{BA} &= EI\theta_B \quad \dots (\beta) \end{aligned}$$

$$\begin{aligned} M_{BC} &= M_{FBC} + \frac{2EI}{4} \left(2\theta_B + \theta_C - \frac{3\Delta}{4} \right) \\ &= -32 + EI\theta_B \quad \dots (\gamma) \end{aligned} \quad (\theta_C = 0, \Delta = 0)$$

$$\begin{aligned} M_{CB} &= M_{FCB} + \frac{2EI}{4} \left(2\theta_C + \theta_B - \frac{3\Delta}{4} \right) \\ &= 48 + \frac{EI\theta_B}{2} \quad \dots (\delta) \end{aligned}$$

Now, from equation (i), $M_{BA} + M_{BC} = 0$

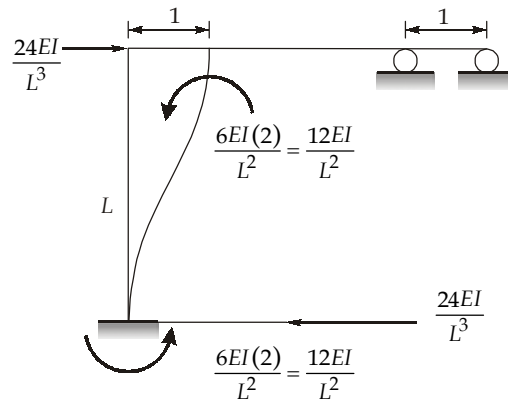
$$\Rightarrow EI\theta_B - 32 + EI\theta_B = 0$$

$$\Rightarrow EI\theta_B = 16$$

Now, from equation (δ)

$$M_{CB} = 48 + \frac{16}{2} = 56 \text{ kNm}$$

27. (b)



$$\therefore k_{11} = \frac{24EI}{L^3}$$

$$\therefore \alpha = 24$$

28. (b)

Using slope deflection method

Equilibrium equation at joint B is:

$$M_{BA} + M_{BC} + 10 \times 3 + 12 \times 3 \times 1.5 = 0$$

$$\Rightarrow \frac{2EI}{4}(2\theta_B) + \frac{2EI}{4}(2\theta_B) + 84 = 0$$

$$\Rightarrow \theta_B = \frac{-42}{EI}$$

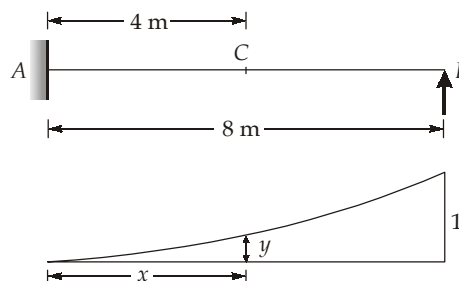
29. (d)

Area under free moment diagram = Area under fixing moment

$$\Rightarrow \frac{1}{2} \times 2 \times 370.02 + \frac{1}{2} \times 2 \times (370.02 + 332.18) + \frac{1}{2} \times 2 \times 332.18 = \frac{1}{2} \times 6 \times (M_A + 228.29)$$

$$\Rightarrow M_A = 239.843 \text{ kNm} \simeq 239.84 \text{ kNm}$$

30. (c)



$$\Delta_B = 0$$

$$\Rightarrow \frac{x^3}{3EI} + \frac{x^2}{2EI}(L-x) = \frac{R_B L^3}{3EI} \quad (x = 4 \text{ m}, L = 8 \text{ m})$$

$$\Rightarrow \frac{4^3}{3} + \frac{4^2}{2}(8-4) = \frac{R_B \times 8^3}{3}$$

$$\Rightarrow R_B = 0.3125 = \text{Ordinate of ILD for } R_B \text{ at } C.$$

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