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# ENGINEERING MECHANICS

## CIVIL ENGINEERING

Date of Test : 03/03/2024

### ANSWER KEY >

- |        |         |         |         |         |
|--------|---------|---------|---------|---------|
| 1. (b) | 6. (a)  | 11. (c) | 16. (d) | 21. (c) |
| 2. (c) | 7. (d)  | 12. (d) | 17. (d) | 22. (d) |
| 3. (c) | 8. (b)  | 13. (d) | 18. (c) | 23. (b) |
| 4. (a) | 9. (d)  | 14. (c) | 19. (a) | 24. (b) |
| 5. (d) | 10. (a) | 15. (d) | 20. (b) | 25. (d) |

**DETAILED EXPLANATIONS**

1. (b)

Given data: Constant angular acceleration,  $\alpha = 2.5 \text{ rad/s}^2$

Initial velocity,  $w_0 = 1 \text{ rad/sec}$   
 $t = 6 \text{ secs}$

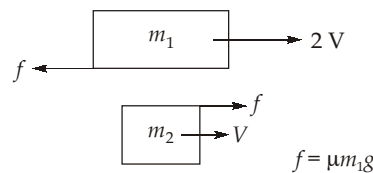
Now, 
$$\theta = w_0 t + \frac{1}{2} \alpha t^2$$

$\Rightarrow \theta = 1 \times 6 + \frac{1}{2} \times 2.5 \times 6^2$

$\Rightarrow \theta = 6 + 45 = 51 \text{ radians}$

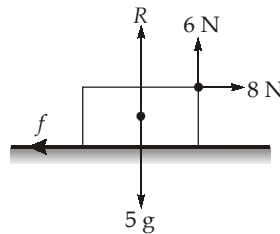
Number of revolutions =  $\frac{\theta}{2\pi} = \frac{51}{2\pi} = 8.12$

2. (c)



3. (c)

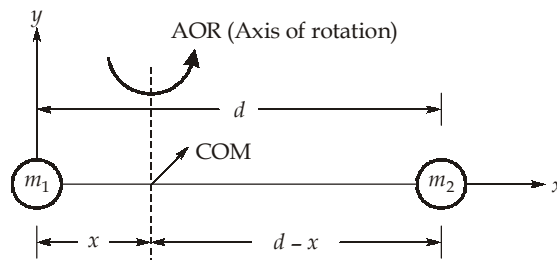
Consider the free body system as shown.



Since the system is at rest,

$\Rightarrow \Sigma F_v = 0$   
 $\Rightarrow R + 6 = 50 \quad [ \because g = 10 \text{ ms}^{-2} ]$   
 $\Rightarrow R = 44 \text{ N}$

4. (a)



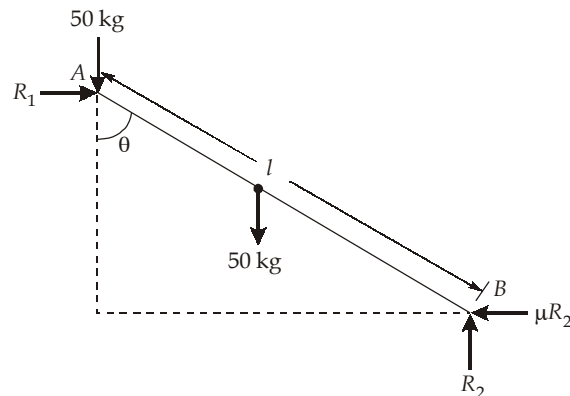
Centre of mass calculation:

$(m_1 + m_2)x = m_1 \times 0 + m_2 \times d$

$$\begin{aligned} \Rightarrow x &= \frac{m_2 d}{m_1 + m_2} \\ \therefore d - x &= \frac{m_1 d}{m_1 + m_2} \\ \therefore I &= m_1 x^2 + m_2 (d - x)^2 \\ &= \frac{m_1 \times (m_2 d)^2}{(m_1 + m_2)^2} + m_2 \times \left( \frac{m_1 d}{m_1 + m_2} \right)^2 \\ &= \frac{m_1 m_2^2 d^2 + m_2 m_1^2 d^2}{(m_1 + m_2)^2} = \frac{m_1 m_2 d^2 [m_2 + m_1]}{(m_1 + m_2)^2} \\ &= \frac{m_1 m_2}{m_1 + m_2} \times d^2 \end{aligned}$$

5. (d)

FBD when man is on the top of the ladder,



$$\begin{aligned} \Rightarrow \sum F_x = 0 &\Rightarrow R_1 = \mu R_2 \\ \Rightarrow \sum F_y = 0 &\Rightarrow 50 + 50 = R_2 \\ \Rightarrow R_2 &= 100 \text{ kg} \\ \Rightarrow R_1 &= \mu R_2 = 0.25 \times 100 = 25 \text{ kg} \\ \Rightarrow \sum M_B = 0 \\ \Rightarrow R_1 l \cos \theta &= 50 \times l \sin \theta + 50 \times 0.5 \times l \times \sin \theta \\ \Rightarrow 25 \cos \theta &= 75 \sin \theta \\ \Rightarrow \tan \theta &= \frac{1}{3} \quad \Rightarrow \theta = \tan^{-1} \left( \frac{1}{3} \right) \\ \therefore x &= \frac{1}{3} \end{aligned}$$

6. (a)

Centroid,

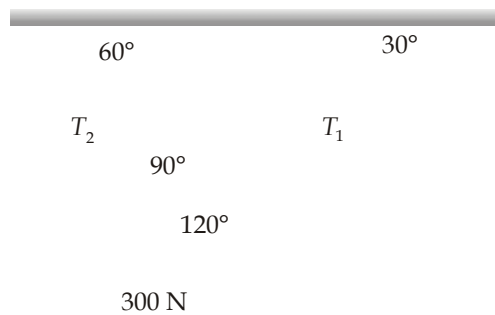
$$\begin{aligned} \bar{x} &= \frac{\int x dA}{A} \\ A &= \int_0^1 (1 - x^2) dx = \left[ x - \frac{x^3}{3} \right]_0^1 = \left( 1 - \frac{1}{3} \right) - (0 - 0) = \frac{2}{3} \text{ unit} \end{aligned}$$

$$\bar{x} = \int_0^1 \frac{x(1-x^2)dx}{2/3} \quad [dA = ydx = (1-x^2)dx]$$

$$\Rightarrow \bar{x} = \frac{3}{2} \int_0^1 (x-x^3)dx = \frac{3}{2} \left[ \frac{x^2}{2} - \frac{x^4}{4} \right]_0^1 = \frac{3}{2} \left[ \frac{1}{2} - \frac{1}{4} \right]$$

$$\Rightarrow \bar{x} = \frac{3}{2} \times \frac{1}{4} = \frac{3}{8} \text{ unit}$$

7. (d)

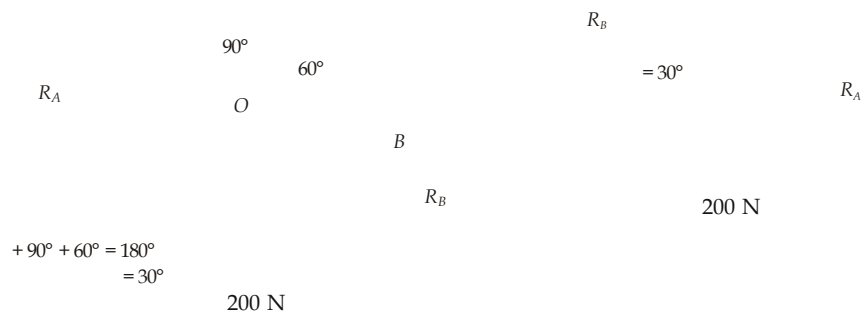


Using Lami's Theorem

$$\frac{T_2}{\sin 120^\circ} = \frac{T_1}{\sin \{360^\circ - (90^\circ + 120^\circ)\}}$$

$$\Rightarrow \frac{T_1}{T_2} = \frac{\sin 150^\circ}{\sin 120^\circ} = 0.577$$

8. (b)



Using Lami's theorem

$$\frac{R_A}{\sin 120^\circ} = \frac{200}{\sin 150^\circ} = \frac{R_B}{\sin 90^\circ}$$

$$\therefore R_A = 200 \times \frac{\sin 120^\circ}{\sin 150^\circ} = 346.4 \text{ N}$$

$$R_B = \frac{200 \times \sin 90^\circ}{\sin 150^\circ} = 400 \text{ N}$$

$$\begin{aligned} \therefore R_A + R_B &= 400 + 346.4 \\ &= 746.41 \text{ N} \simeq 746.4 \text{ N} \end{aligned}$$

9. (d)

$$\begin{aligned} I_p &= I_x + I_y = \frac{bd^3}{12} + \frac{db^3}{12} \\ &= \frac{bd}{12} (b^2 + d^2) \\ &= \frac{2 \times 5}{12} (2^2 + 5^2) = 24.167 \text{ cm}^4 \end{aligned}$$

10. (a)

$$\text{Radial acceleration, } a_r = \frac{V^2}{R} = \frac{(40)^2}{1000} = 1.6 \text{ m/s}^2$$

$$\text{Total acceleration, } a = 2 \text{ m/s}^2$$

$\therefore$  Maximum deceleration with speed can be decreased is

$$\begin{aligned} \text{Tangential acceleration, } a_t &= \sqrt{a^2 - a_r^2} = \sqrt{(2)^2 - (1.6)^2} \\ &= \sqrt{4 - 2.56} = \sqrt{1.44} = 1.2 \text{ m/s}^2 \end{aligned}$$

11. (c)

For perfectly elastic collision  $e = 1.0$

12. (d)

Using energy principle,

$$\text{Initial energy} = \text{Final energy} + \text{Work done by air resistance}$$

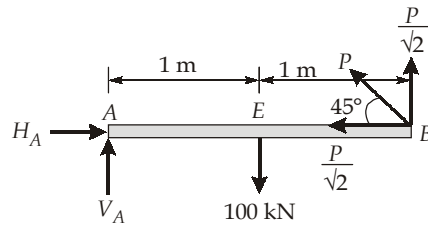
$$\Rightarrow mgh_1 = mgh_2 + \frac{1}{2}mv^2 + W_{air}$$

$$\therefore W_{air} = 5 \times 10 \times 20 - \frac{1}{2} \times 5 \times 10^2 = 750 \text{ J} \quad [ \because h_2 = 0 ]$$

13. (d)

14. (c)

FBD of beam AB,



$$\Sigma M_A = 0$$

$$\Rightarrow -\frac{P}{\sqrt{2}} \times 2 + 100 \times 1 = 0$$

$$\Rightarrow P = 70.71 \text{ kN}$$

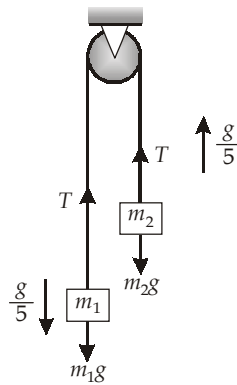
15. (d)

$$\text{Time } (t) = \frac{L}{v} = \frac{12}{5} = 2.4 \text{ sec}$$

$$\text{Height } (h) = \frac{1}{2} g t^2 \quad [\because u = 0]$$

$$= \frac{1}{2} \times 9.81 \times 2.4^2 = 28.25 \text{ m}$$

16. (d)



$$m_1 g - T = m_1 a = \frac{m_1 g}{5} \quad \dots(i)$$

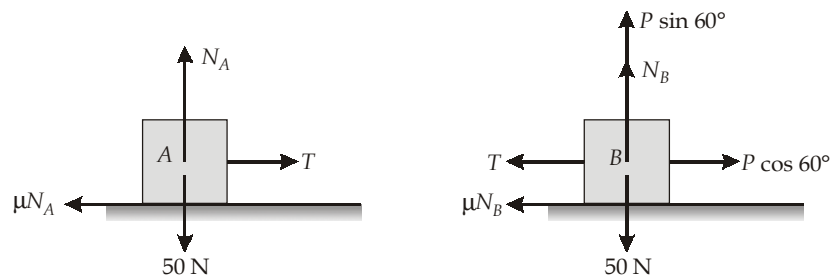
$$T - m_2 g = m_2 a = m_2 \frac{g}{5} \quad \dots(ii)$$

From (i) and (ii), we get

$$\frac{m_1}{m_2} = \frac{6}{4} = 1.5$$

17. (d)

FBD of block A and B :



Normal reaction at A,  $N_A = 50 \text{ N}$

Normal reaction at B,  $N_B = 50 - P \sin 60^\circ$

$$T = \mu N_A \quad \dots(i)$$

$$T + \mu N_B = P \cos 60^\circ \quad \dots(ii)$$

From (i)

$$T = 0.3 \times 50 = 15 \text{ N}$$

... (iii)

Substituting (iii) in (ii),

$$T + (0.3) \times [50 - P \sin 60^\circ] = P \cos 60^\circ$$

$$\Rightarrow 15 + 0.3 \times 50 = P \times 0.3 \sin 60^\circ + P \cos 60^\circ$$

$$\Rightarrow 30 = P [\cos 60^\circ + 0.3 \sin 60^\circ]$$

$$\Rightarrow P = \frac{30}{0.5 + 0.2598}$$

$$\Rightarrow P = 39.48 \text{ N}$$

18. (c)

Centroid from base,

$$\begin{aligned} \bar{y} &= \frac{A_1 y_1 - A_2 y_2}{A_1 - A_2} \\ &= \frac{d^2 \times \frac{d}{2} - \frac{\pi}{8} d^2 \times \frac{2d}{3\pi}}{d^2 - \frac{\pi d^2}{8}} \\ &= \frac{5 \times 8d}{12(8 - \pi)} = \frac{10d}{3(8 - \pi)} \end{aligned}$$

19. (a)

Applying conservation of angular momentum,

$$I\omega = I'\omega'$$

$$\Rightarrow MR^2 \times \omega = (MR^2 + 2mR^2)\omega'$$

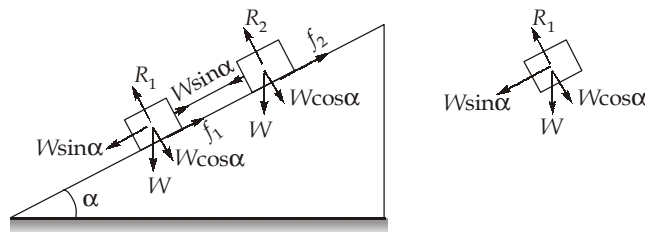
$$\Rightarrow 5 \times (0.3)^2 \times 15 = (5 \times 0.3^2 + 2 \times 0.1 \times 0.3^2) \times \omega'$$

$$\Rightarrow \omega' = 14.42 \text{ rad/s}$$

20. (b)

Given,

$$W_1 = W_2 = W(\text{say})$$



$$R_1 = R_2 = W \cos \alpha$$

Along the plane,  $0.2R_1 + 0.3R_2 = 2W \sin \alpha$

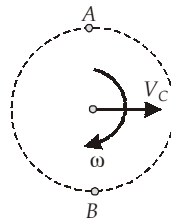
$$\tan \alpha = \frac{0.2 + 0.3}{2} = 0.25$$

$$\alpha = \tan^{-1}(0.25) = 14^\circ.04^\circ$$

21. (c)

∴ Velocities are in opposite directions,

∴ I will lie between A and B,



$$\therefore V_A = V_C + R\omega$$

$$V_B = R\omega - V_C$$

$$\therefore V_C + R\omega = 5$$

and  $R\omega - V_C = 3$

$$\therefore V_C + 0.25 \omega = 5 \quad \dots(a)$$

$$0.25 \omega - V_C = 3 \quad \dots(b)$$

On solving (a) and (b),

$$\omega = 16 \text{ rad/s}$$

22. (d)

Let the two forces are  $P$  kN and  $Q$  kN and angle between  $P$  and  $Q$  be ' $\theta$ '

$$\therefore \text{Resultant force, } R = \sqrt{P^2 + Q^2 + 2PQ \cos \theta}$$

For maximum resultant force,  $\cos \theta$  must be equal to 1.

$$\therefore R_{\max} = \sqrt{(P+Q)^2} = P+Q$$

$$\Rightarrow P+Q = 40 \quad \dots(i)$$

For minimum resultant force,  $\cos \theta$  must be equal to (-1)

$$\therefore R_{\min} = \sqrt{(P-Q)^2} = P-Q$$

$$\Rightarrow P-Q = 10 \quad \dots(ii)$$

Solving (i) and (ii), we get  $P = 25$  kN,  $Q = 15$  kN.

23. (b)



Mass of the block is  $m$ , therefore, stretch in the spring ( $x$ ) is given by,

$$mg = kx$$

$$\Rightarrow x = \frac{mg}{k}$$

Total mechanical energy of the system just after the blow is,

$$T_i = \frac{1}{2}mv^2 + \frac{1}{2}kx^2$$

$$\Rightarrow T_i = \frac{1}{2}mv^2 + \frac{1}{2}k\left(\frac{mg}{k}\right)^2$$

$$\Rightarrow T_i = \frac{1}{2}mv^2 + \frac{m^2g^2}{2k}$$

If the block descends through a height ' $h$ ' before coming to an instantaneous rest then the elastic potential energy becomes  $\frac{1}{2}k\left(\frac{mg}{k} + h\right)^2$  and the gravitational potential energy will be  $-mgh$ .

$$\therefore T_f = \frac{1}{2}k\left(\frac{mg}{k} + h\right)^2 - mgh$$

On applying conservation of energy, we get

$$T_i = T_f$$

$$\Rightarrow \frac{1}{2}mv^2 + \frac{m^2g^2}{2k} = \frac{1}{2}k\left(\frac{mg}{k} + h\right)^2 - mgh$$

$$\Rightarrow \frac{1}{2}mv^2 = \frac{1}{2}kh^2$$

$$\Rightarrow h = v\sqrt{\frac{m}{k}}$$

24. (b)

The free body diagrams of the two blocks are as shown:



From the consideration of equilibrium of block 1 and block 2.

For block 1:

$$W_1 \cos \alpha - N_1 = 0$$

$$\Rightarrow N_1 = W_1 \cos \alpha$$

$$\text{Also, } W_1 \sin \alpha = T + F_1 = T + \mu \cdot N_1$$

$$= T + \mu \cdot W_1 \cos \alpha \quad \dots(i)$$

For block 2:

$$\begin{aligned} W_2 &= N_2 \\ T_1 &= \mu \cdot N_2 = \mu \cdot W_2 \end{aligned} \quad \dots(ii)$$

Put the value of  $T$  in eq. (i)

$$\begin{aligned} W_1 \sin \alpha &= \mu W_2 + \mu W_1 \cos \alpha \\ \Rightarrow W_1 \sin \alpha - \mu W_1 \cos \alpha &= \mu W_2 \\ \text{Since, } W_1 &= W_2 \\ \therefore \sin \alpha - \mu \cdot \cos \alpha &= \mu \\ \Rightarrow \sin \alpha &= \mu(1 + \cos \alpha) \\ \Rightarrow 2 \sin \frac{\alpha}{2} \cos \frac{\alpha}{2} &= \mu \cdot 2 \cdot \cos^2 \frac{\alpha}{2} \\ \Rightarrow \tan \frac{\alpha}{2} &= \mu \\ \Rightarrow \frac{\alpha}{2} &= \tan^{-1}(\mu) \\ \Rightarrow \alpha &= 2 \times \tan^{-1}(0.3) = (16.7^\circ) \times 2 = 33.4^\circ \end{aligned}$$

25. (d)

For no tipping or prevent overturning

$$Ph < \frac{Wb}{2}$$

where  
and

$W$  is weight of block  
 $b$  is width of block

$$h < \frac{Wb}{2P} \quad \dots(1)$$

and for slipping without tipping

$$\begin{aligned} P &> f(\text{force of friction}) \\ P &> \mu W \end{aligned} \quad \dots(2)$$

From (1) and (2)

$$\begin{aligned} h &< \frac{b}{2\mu} \\ \therefore h &< \frac{60}{0.6} \\ \therefore h &< 100 \text{ mm} \end{aligned}$$

Option (d) is correct.

